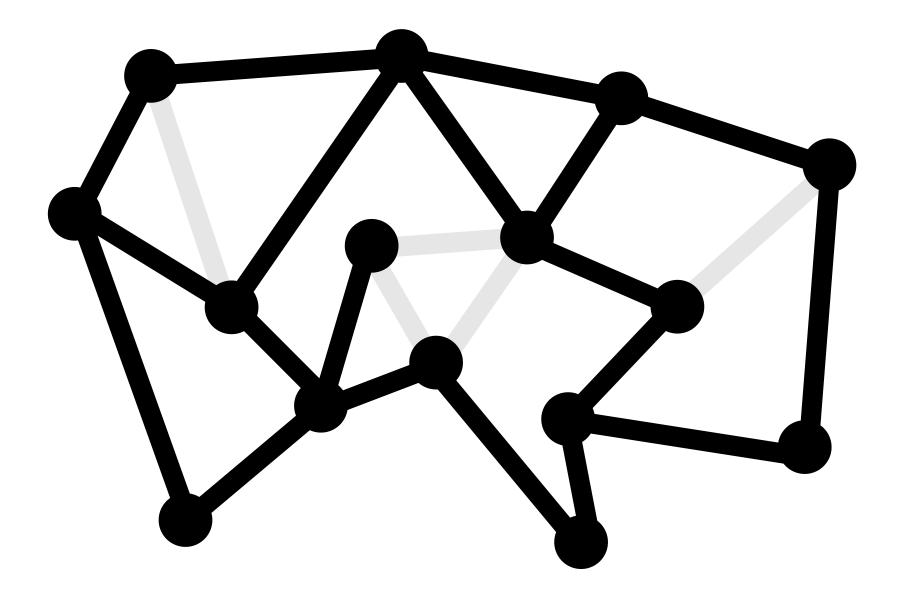
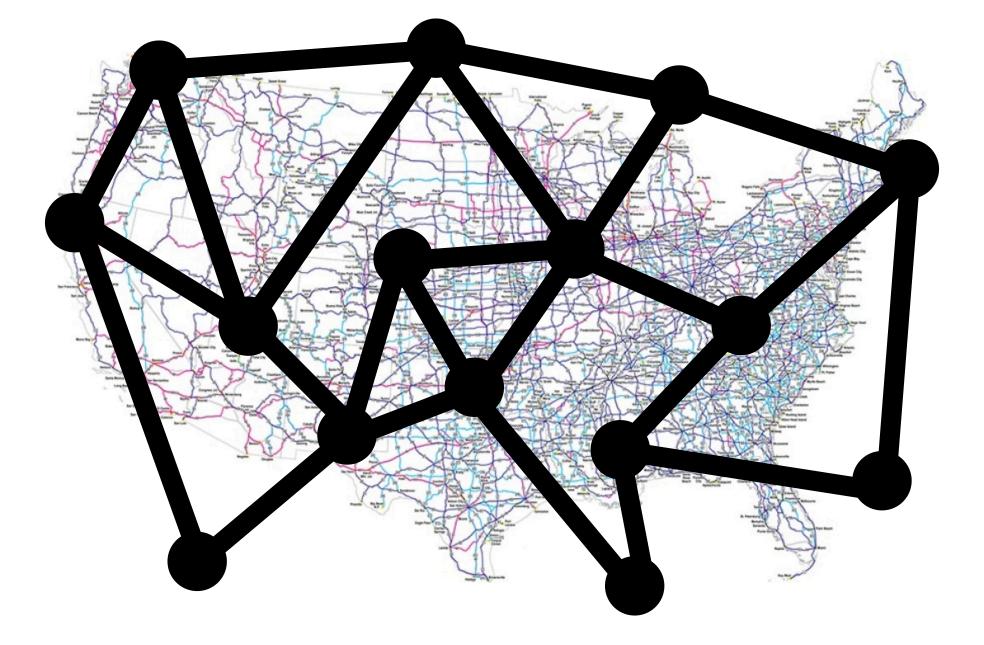
Spanners Mini-Talk Fall 2023 Brown University

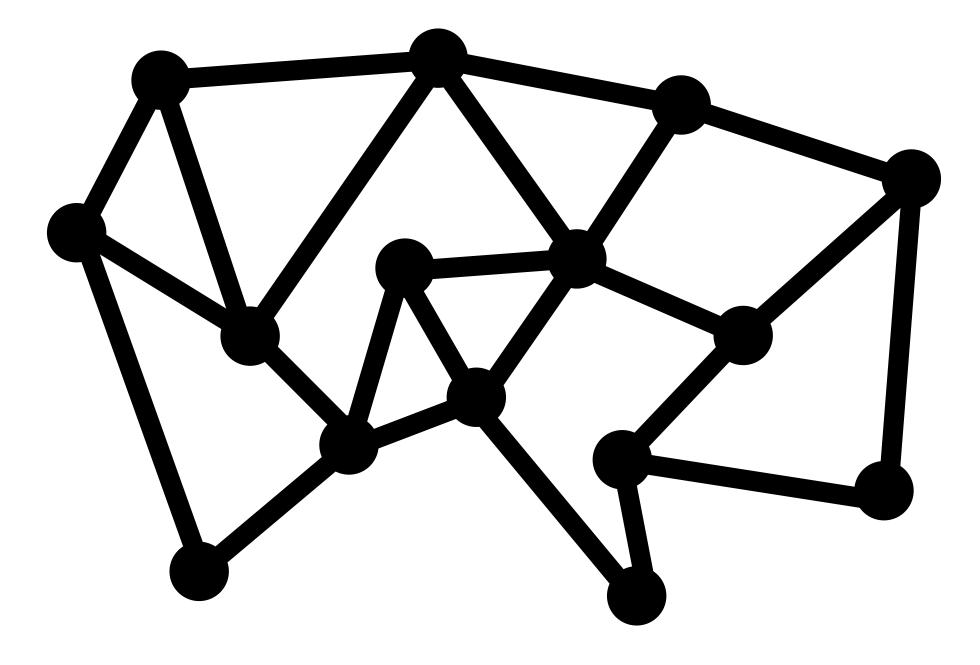
D Ellis Hershkowitz (Ellis)





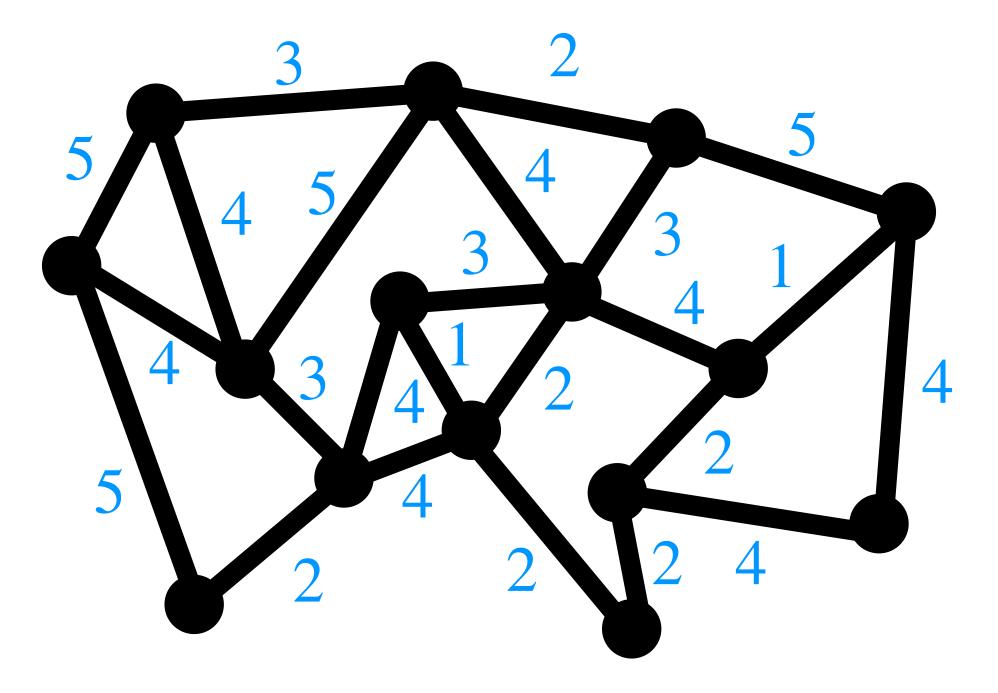
(Transportation) Network

Some notion of distance



Graph G = (V, E)

 $d_G(u, v) := \min\{|P| : \text{path } P \text{ from } u \text{ to } v\}$

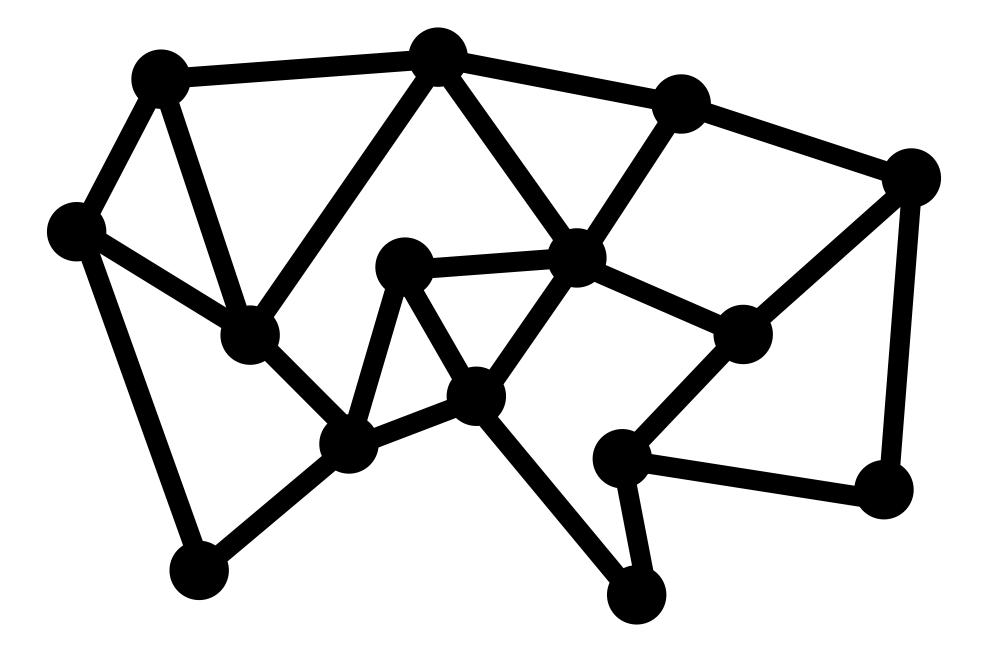


Graph G = (V, E, w)

 $d_G(u, v) := \min\{w(P): \text{ path } P \text{ from } u \text{ to } v\}$



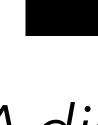
 $e \in P$



Graph G = (V, E)

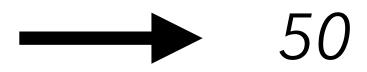
 $d_G(u, v) := \min\{|P| : \text{path } P \text{ from } u \text{ to } v\}$

How far from u to v?

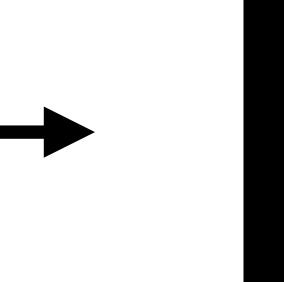


A distance "API"

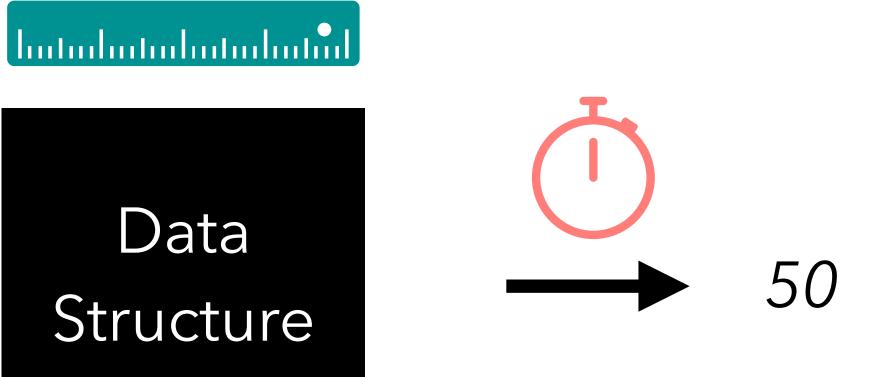




How far from u to v?



A distance "API"

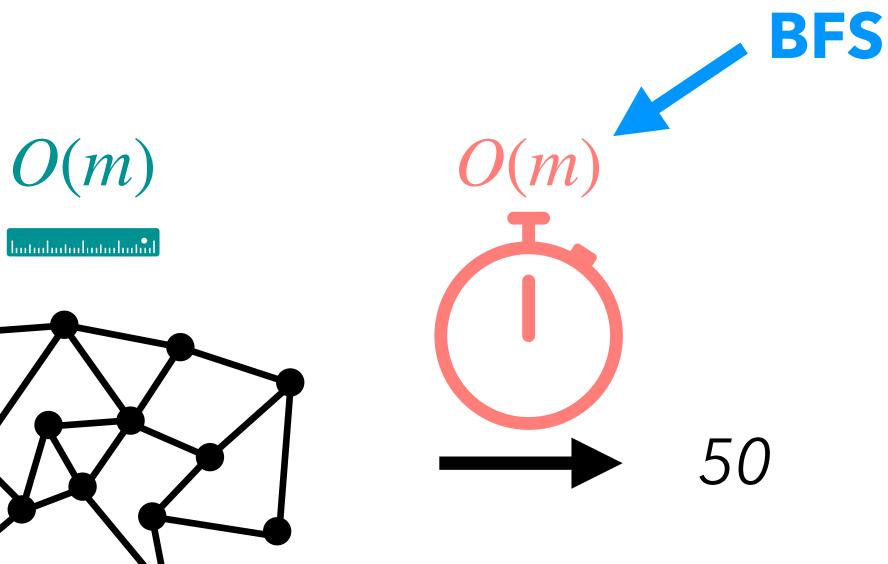


Tradeoff: space (of data structure) vs (response) **time**

Motivation: Distance Oracles Small but Slow

How far from u to v?Input Graph

n := |V| and m := |E|

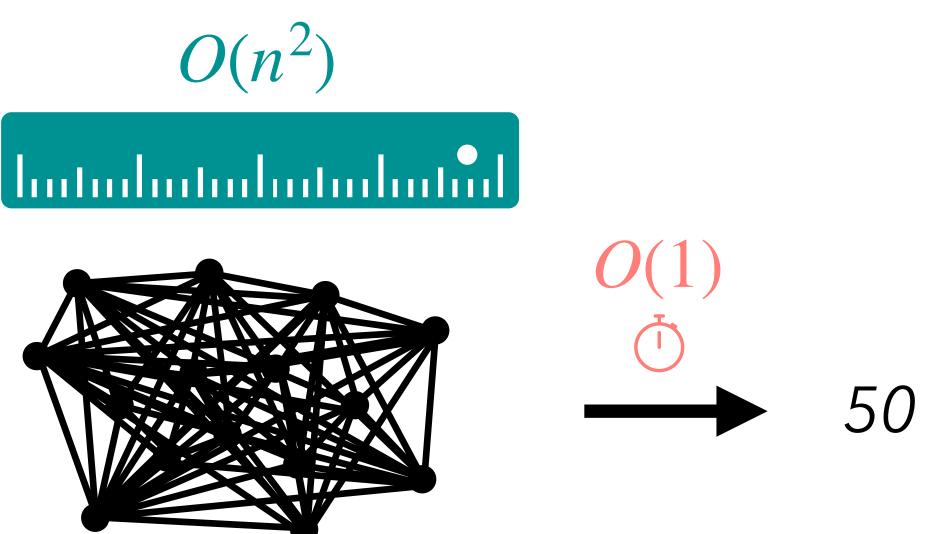


Tradeoff: space (of data structure) vs (response) **time**

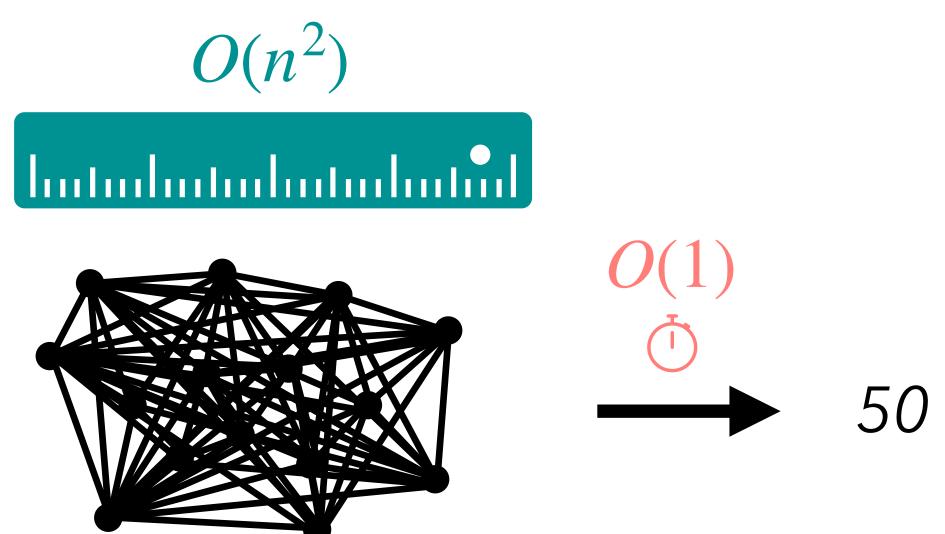


Motivation: Distance Oracles Fast but Large

How far from u to v?





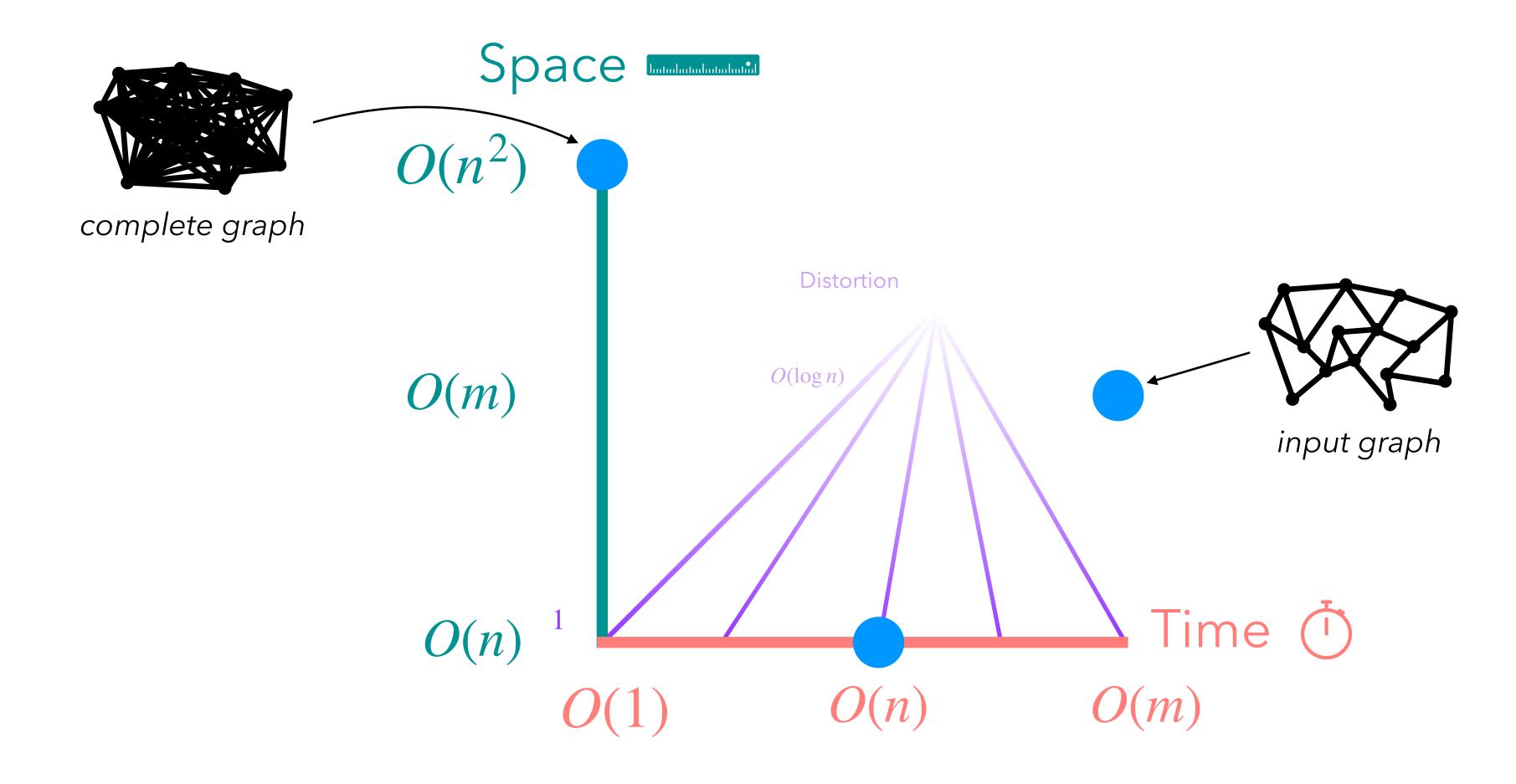


Tradeoff: space (of data structure) vs (response) time

Complete Graph with $w = d_G$

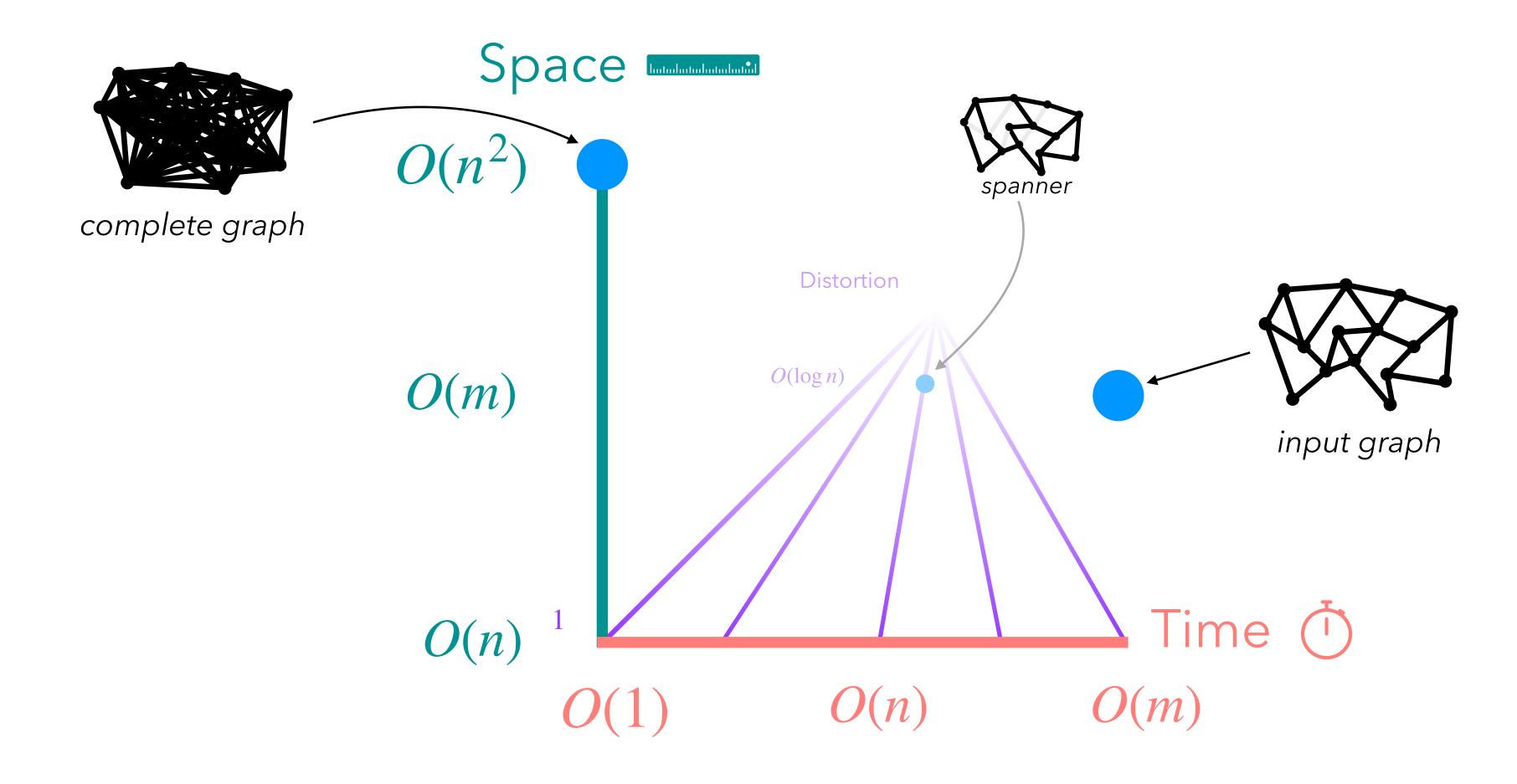


Motivation: Distance Oracles Plotting Tradeoffs

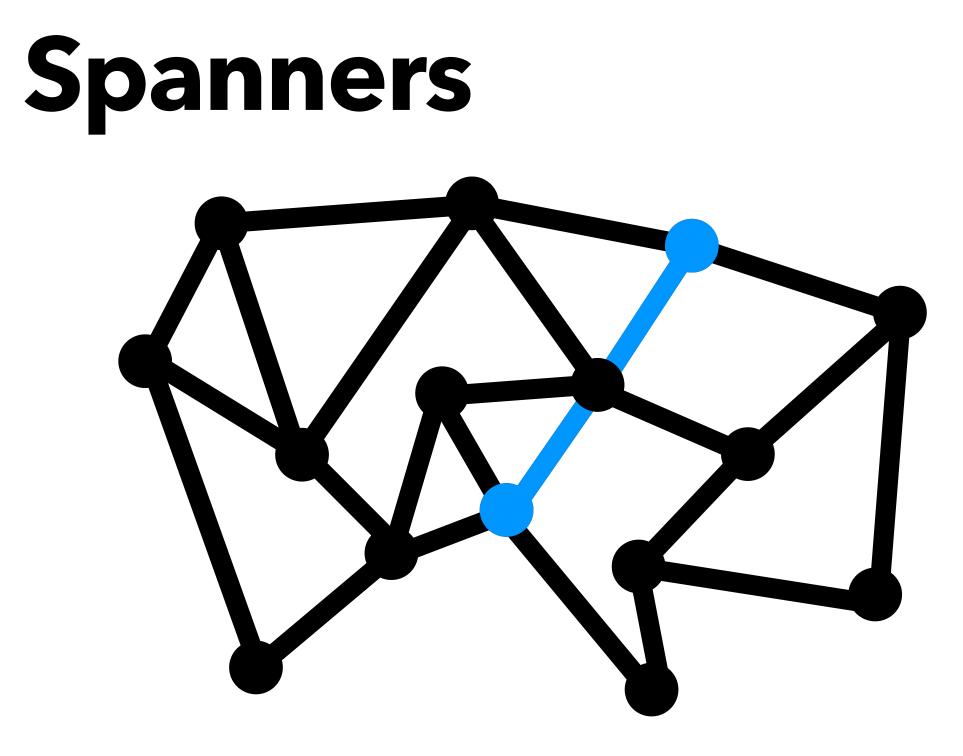




Motivation: Distance Oracles Plotting Tradeoffs

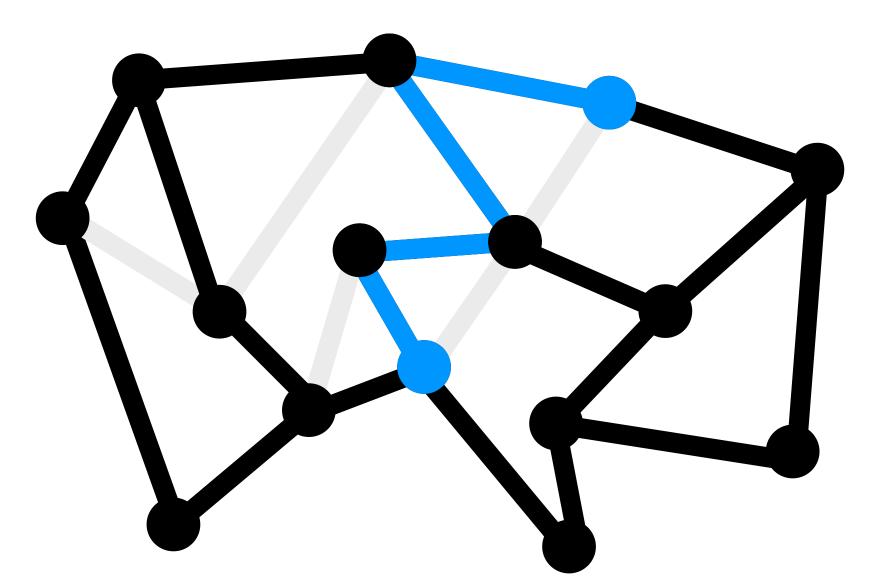






graph G

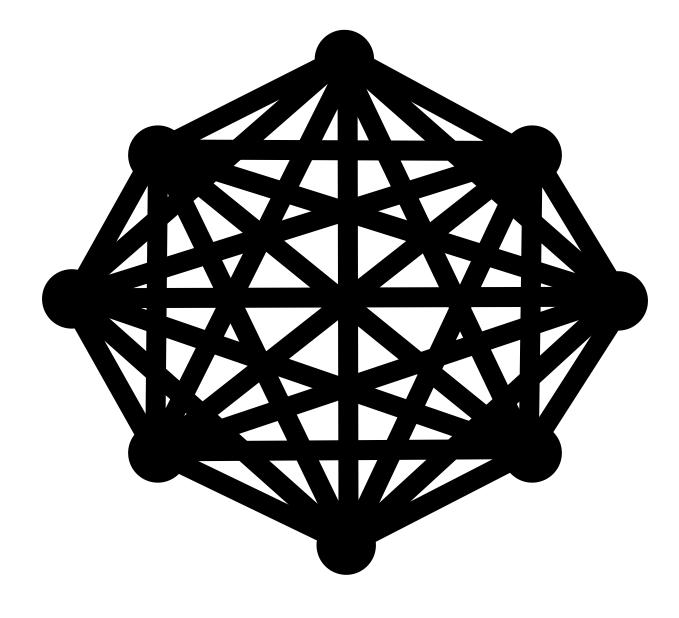
Observe: $d_G(u, v) \le d_H(u, v) \ \forall u, v \in V$



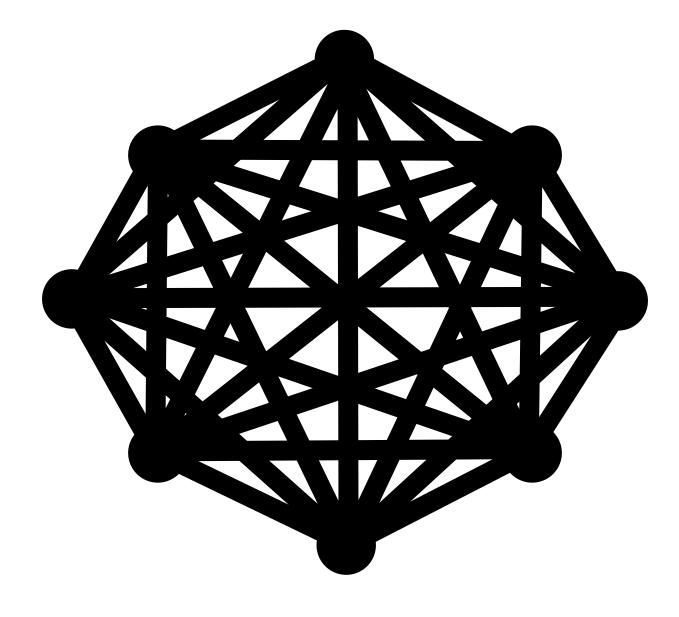
2-spanner H of G

Definition (spanner): given graph G = (V, E) and $t \ge 1$, a *t*-spanner H is a subgraph of G satisfying $d_H(u,v) \leq t \cdot d_G(u,v)$ $\forall u, v \in V$

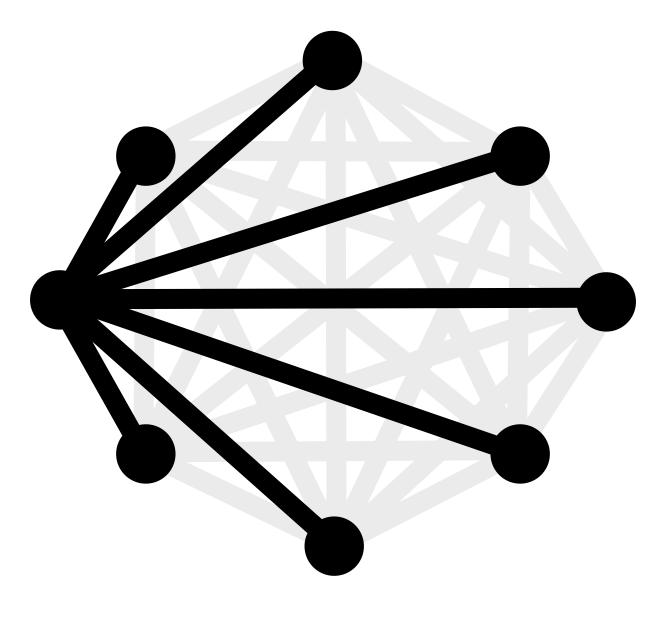




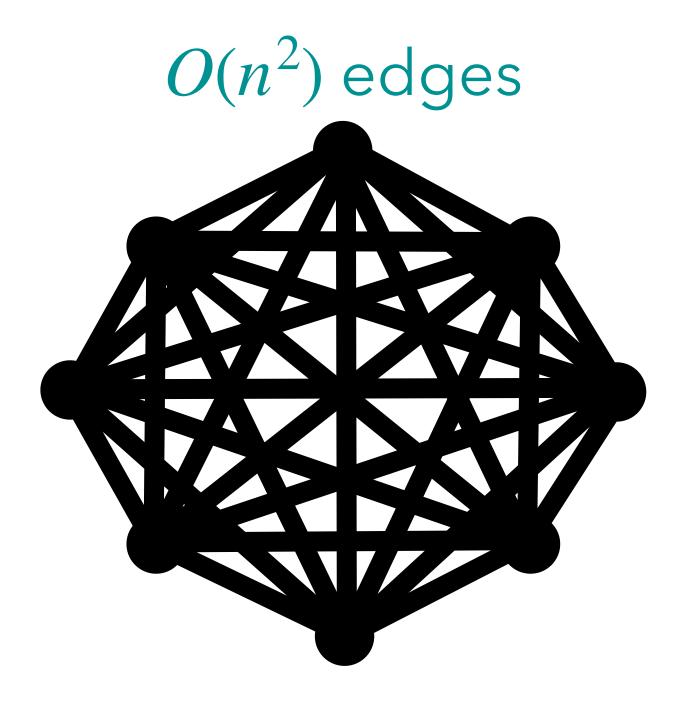
Question: smallest 1-spanner of complete graph?



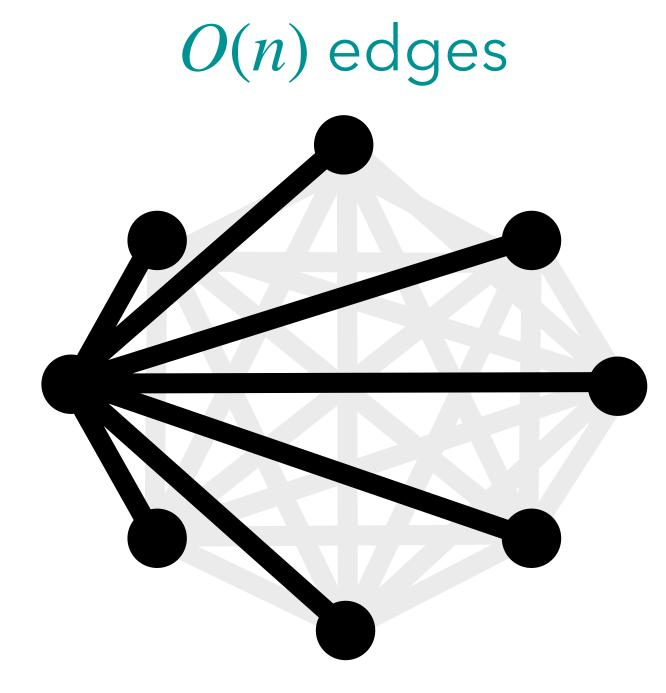
Question: smallest 2-spanner of complete graph?



Question: smallest 2-spanner of complete graph?

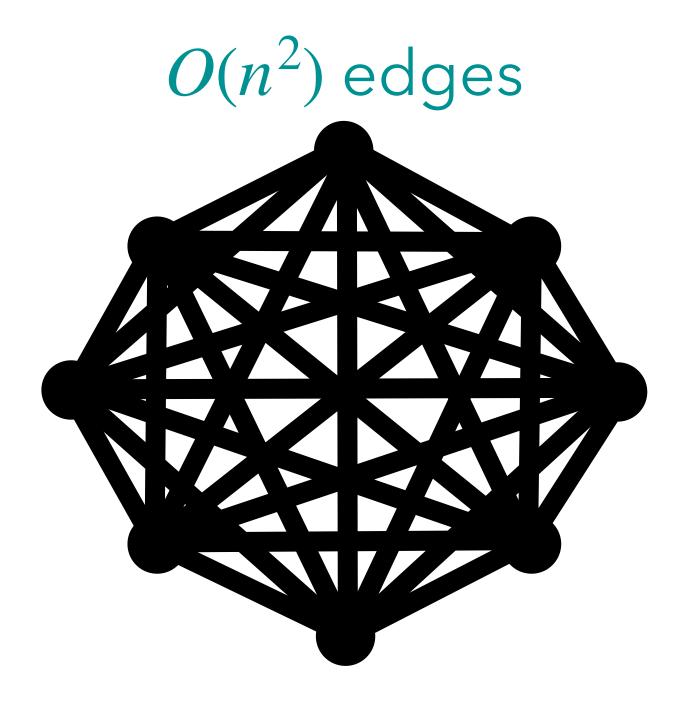


smallest 1-spanner (of complete graph)

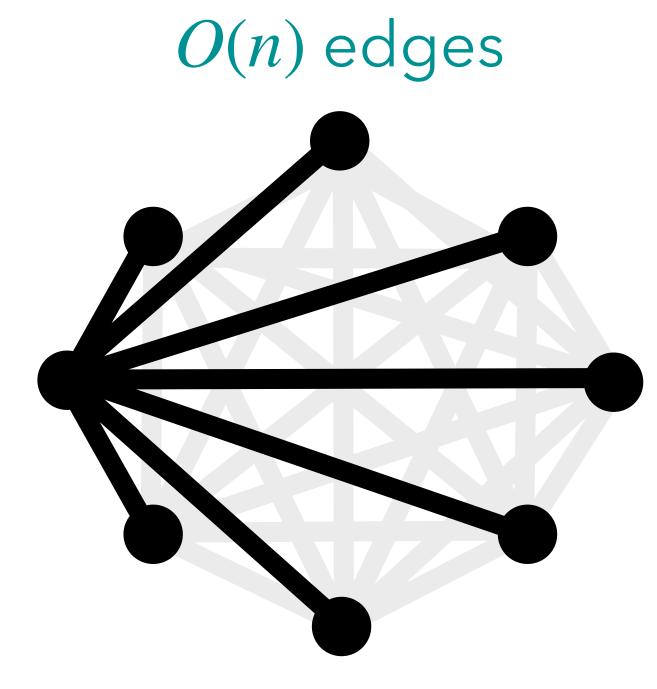


smallest 2-spanner (of complete graph)

Moral: larger distortion allows smaller size (of spanner)



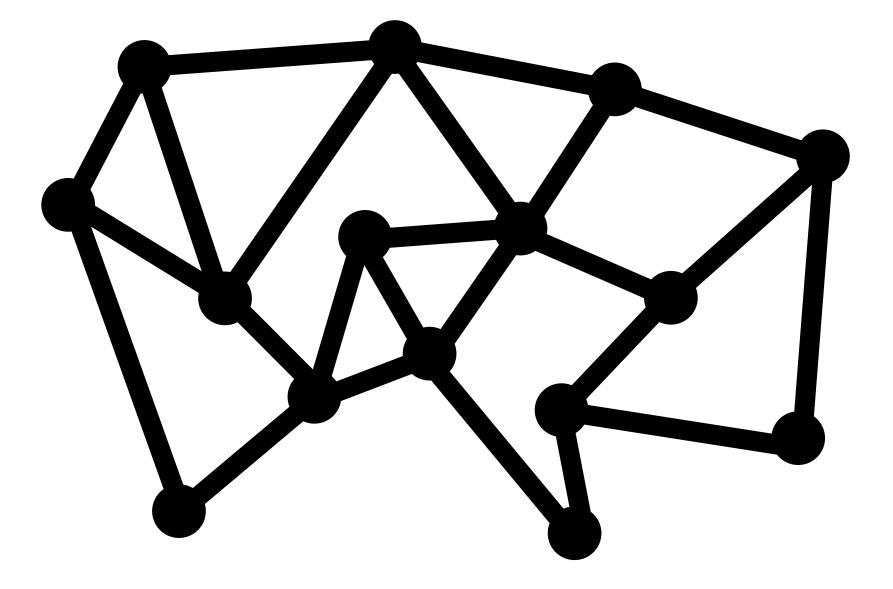
smallest 1-spanner (of complete graph)



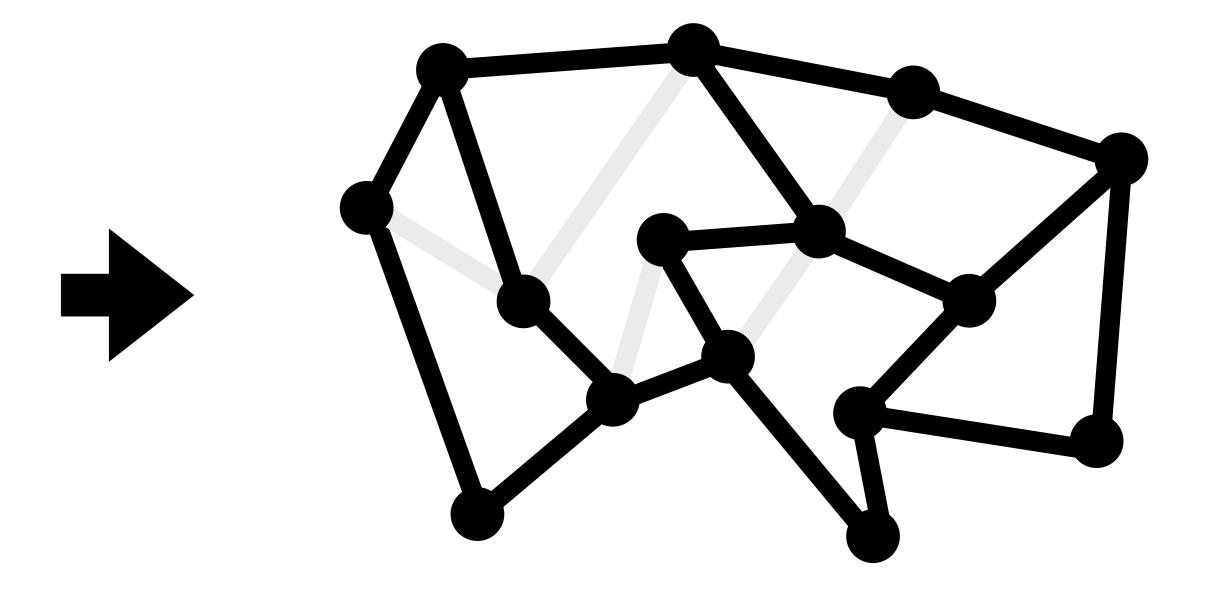
smallest 2-spanner (of complete graph)

Main Question: how large of distortion for O(n) edges in general?

Main Result Today



Theorem: every graph *G* has a *t*-spanner *H* w/ • **Distortion:** $t = O(\log n)$ • **Size:** |H| = O(n)

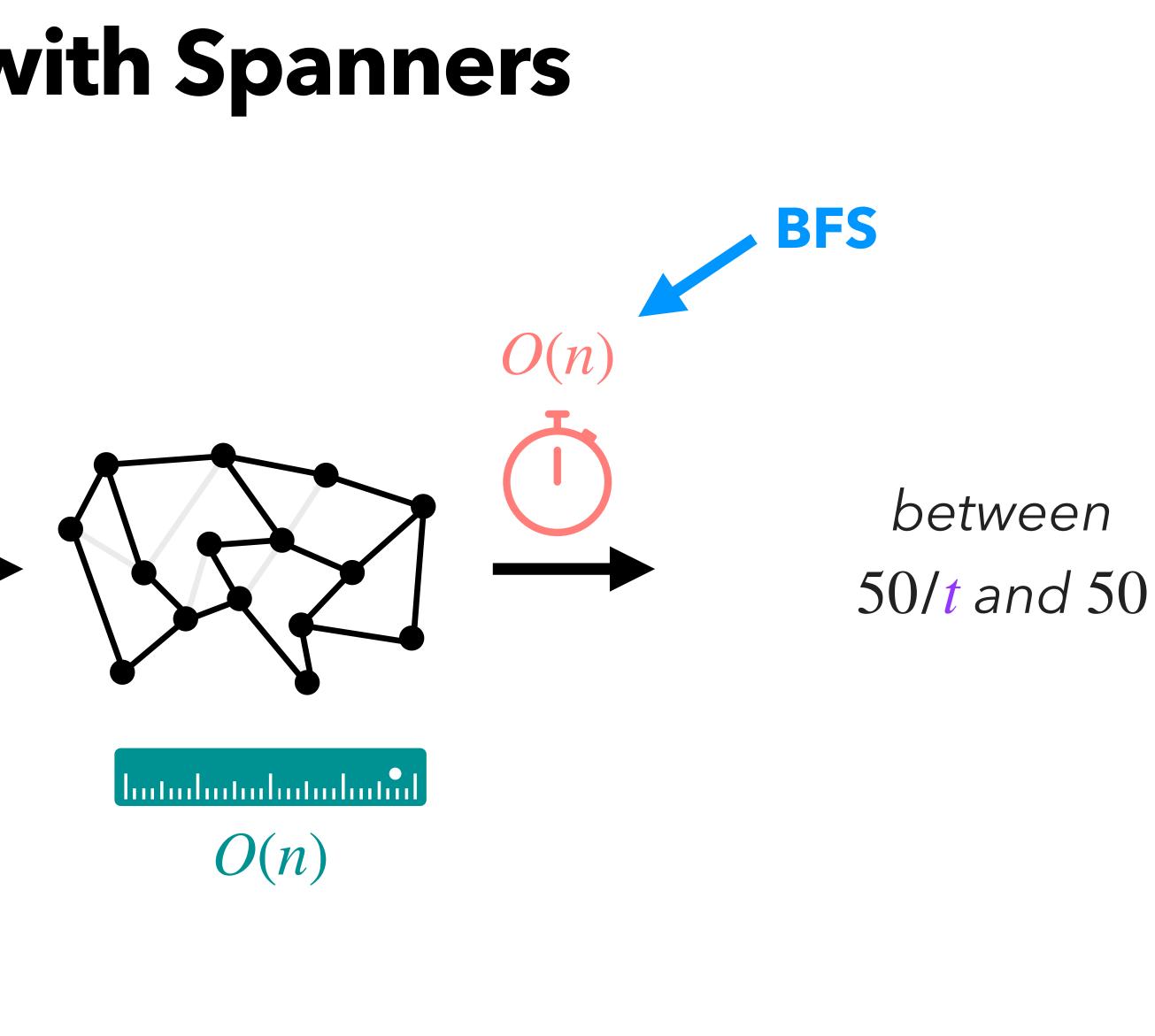


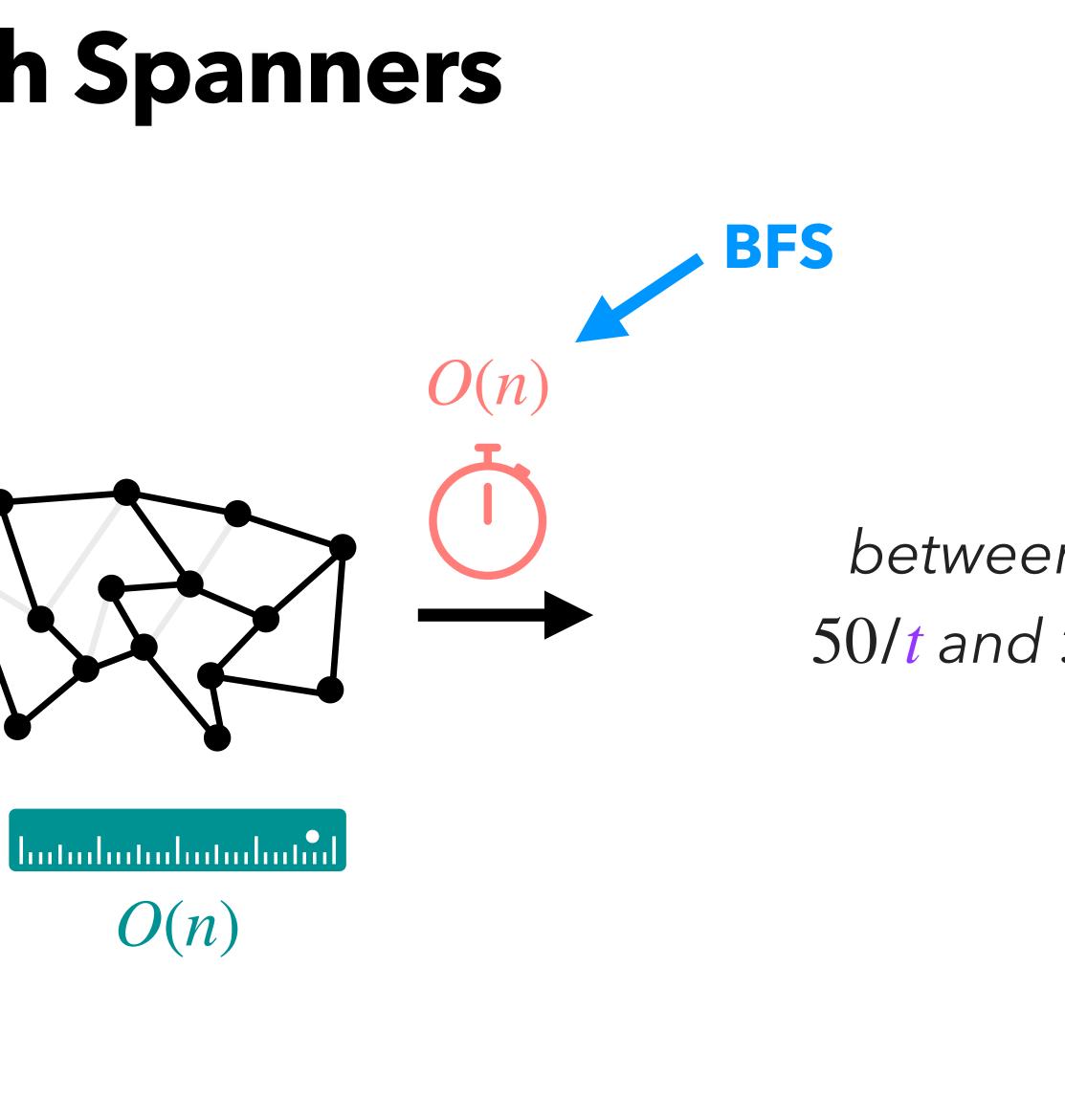


Distance Oracles with Spanners

How far from u to v?







Roadmap of Proof

1. Simple Observation

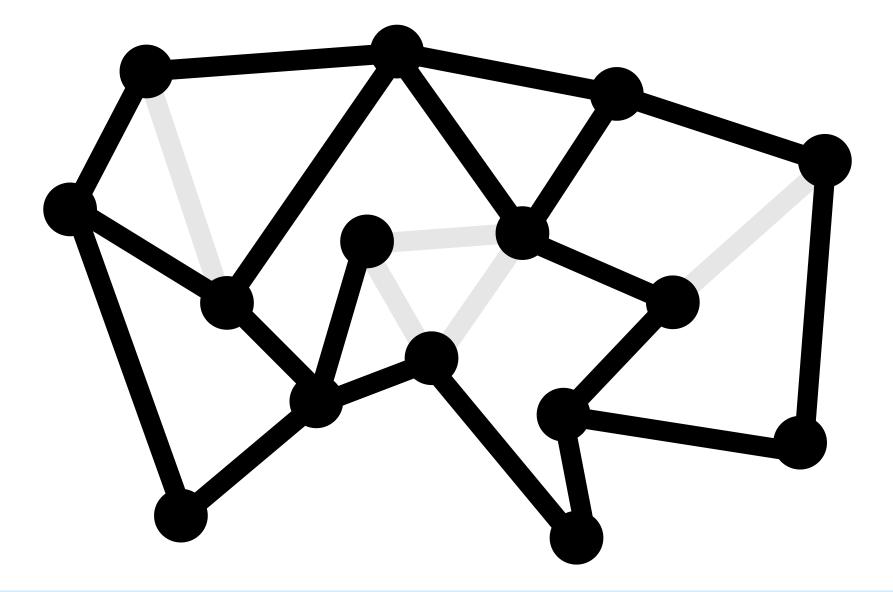
edge spanners suffice

2. Greedy Algorithm

suggested by observation

- 3. Distortion Analysis
- 4. Size Analysis

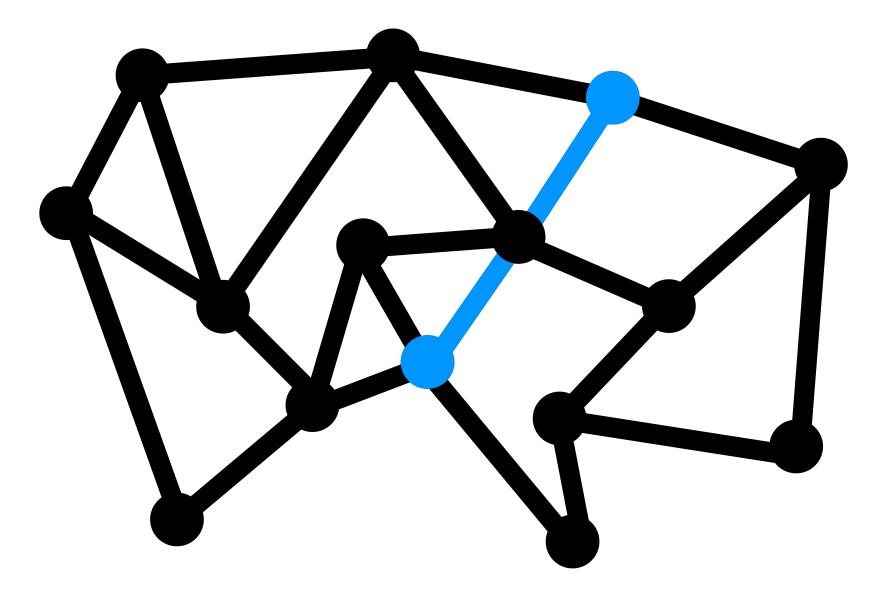
by "Moore Bounds"

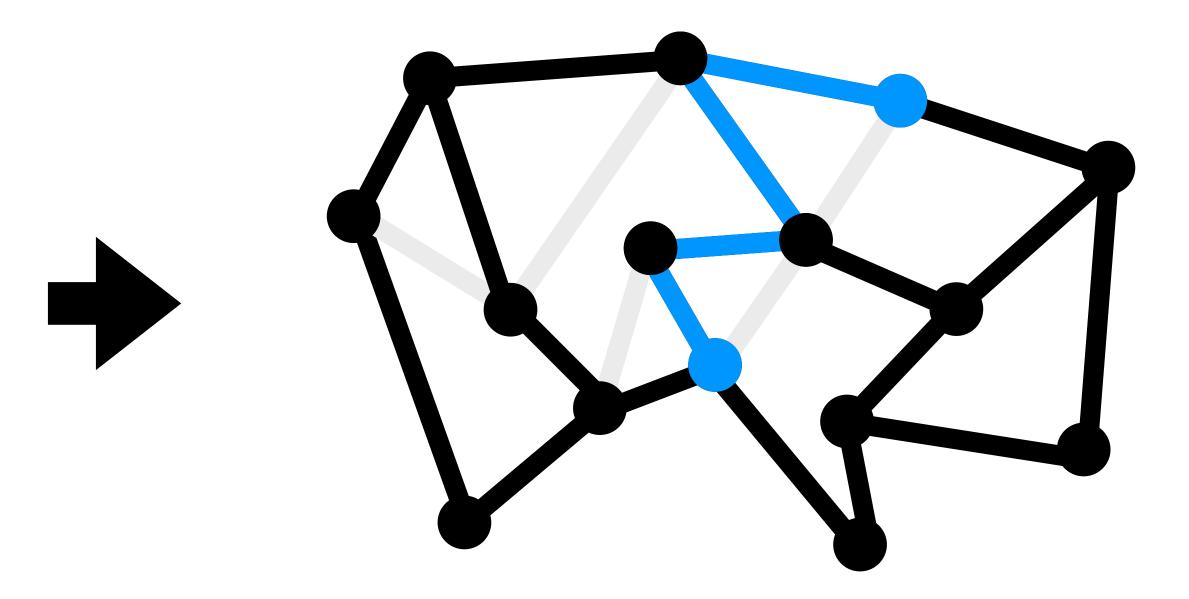


Theorem: every graph G has a t-spanner H w/
Distortion: t = O(log n)

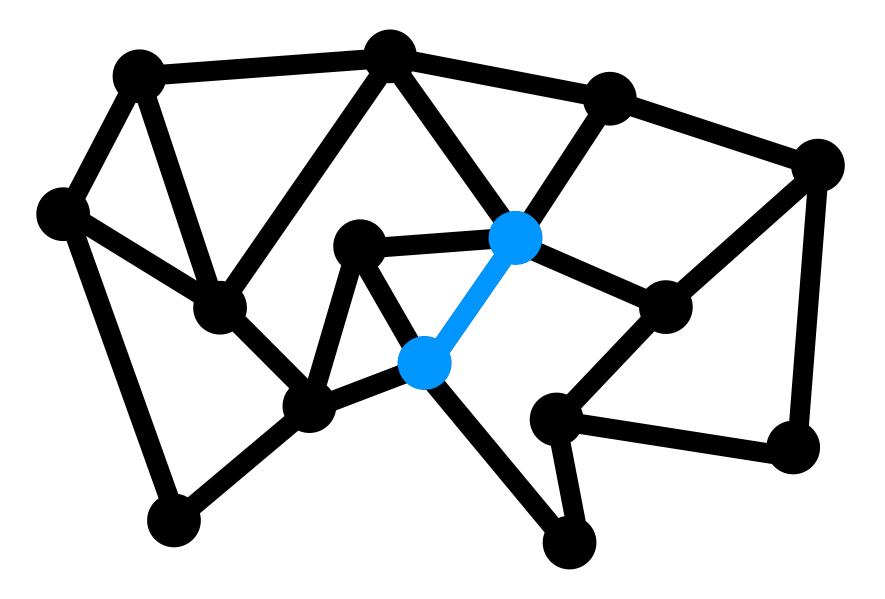
• **Size:** |H| = O(n)

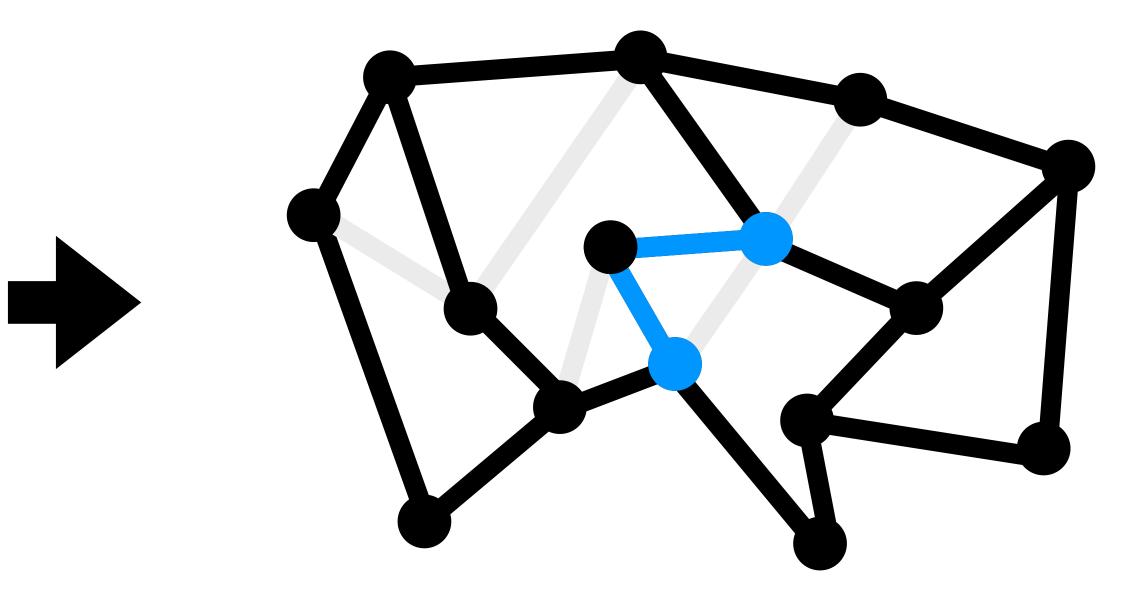






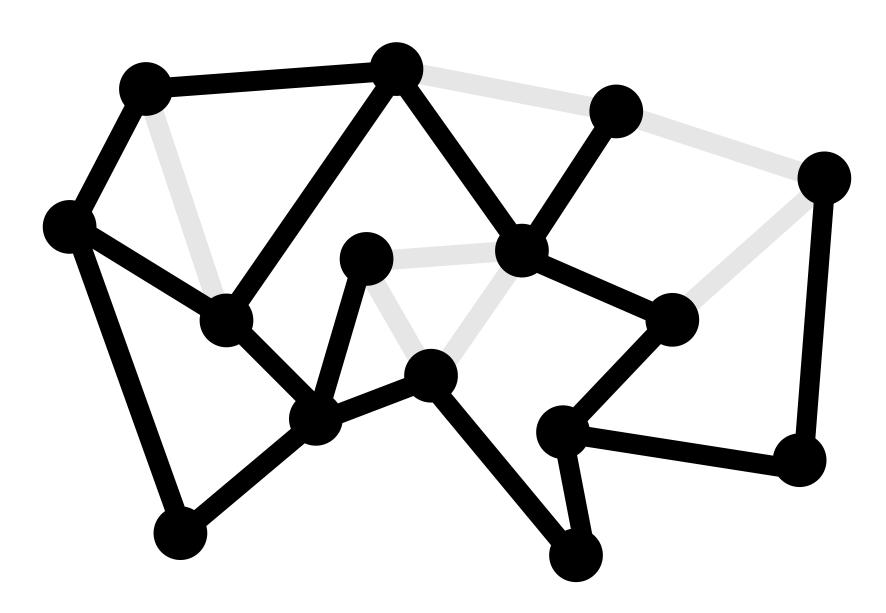
Definition (spanner): given graph G = (V, E) and $t \ge 1$, a t-spanner H is a subgraph of G satisfying $d_H(u,v) \le t \cdot d_G(u,v)$ $\forall u, v \in V$





Definition (edge spanner): given graph G = (V, E) and $t \ge 1$, a *t*-edge-spanner H is a subgraph of G satisfying $\forall \{u, v\} \in E$ $d_H(u,v) \leq t$

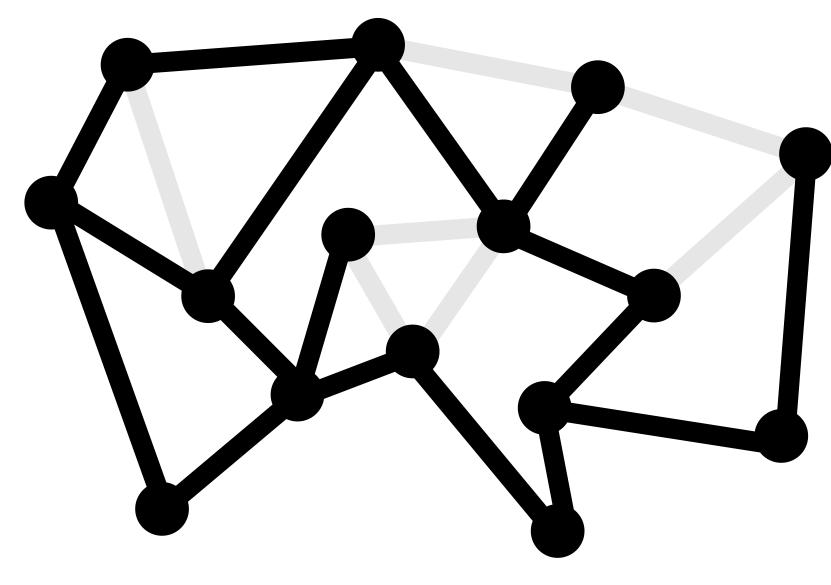
all pairs distorted $\leq t$ all edges distorted $\leq t$ **Claim**: *H* is a *t*-spanner iff it is a *t*-edge-spanner



t-spanner (trivially a t-edge-spanner)



all pairs distorted $\leq t$ all edges distorted $\leq t$ **Claim**: *H* is a *t*-spanner iff it is a *t*-edge-spanner



t-edge-spanner *H*

 $\in H$ $d_G(u,v)$

So $d_H(u, v) \le t \cdot d_G(u, v)$

Roadmap of Proof

1. Simple Observation

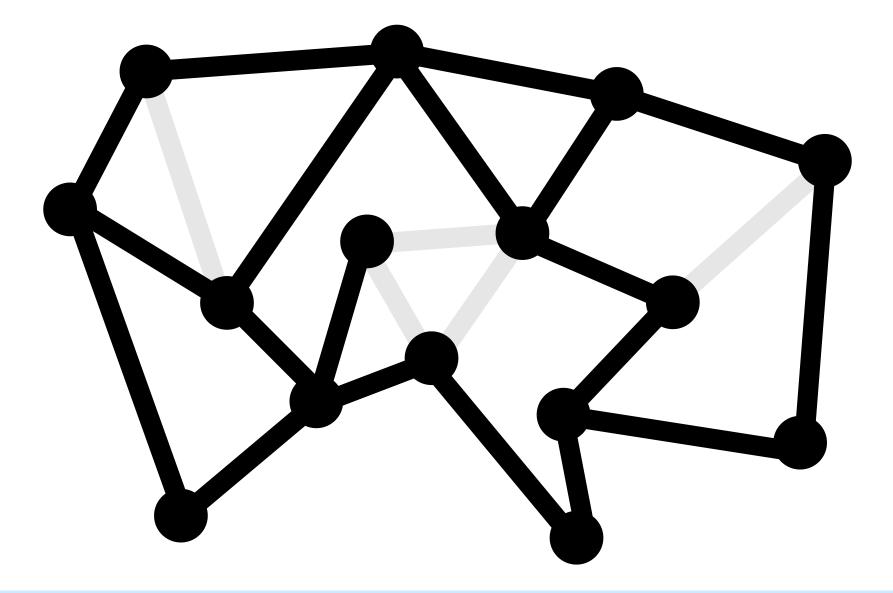
edge spanners suffice

2. Greedy Algorithm

suggested by observation

- 3. Distortion Analysis
- 4. Size Analysis

by "Moore Bounds"



Theorem: every graph G has a t-spanner $H \le t - O(\log n)$

- **Distortion:** $t = O(\log n)$
- **Size:** |H| = O(n)



Roadmap of Proof



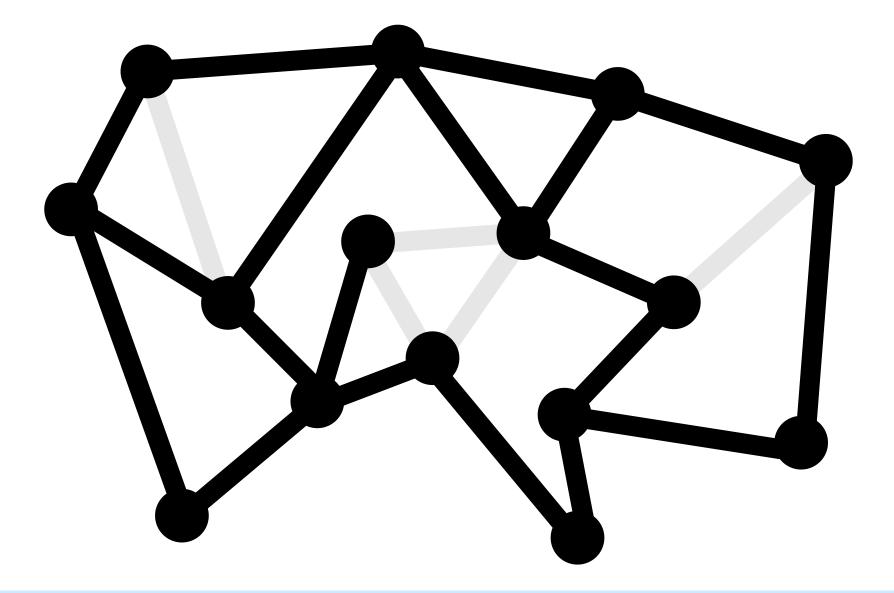
edge spanners suffice

2. Greedy Algorithm

suggested by observation

- 3. Distortion Analysis
- 4. Size Analysis

by "Moore Bounds"



Theorem: every graph G has a t-spanner H w/
Distortion: t = O(log n)

• **Size:** |H| = O(n)



Claim: *H* is a *t*-spanner iff it is a *t*-edge-spanner



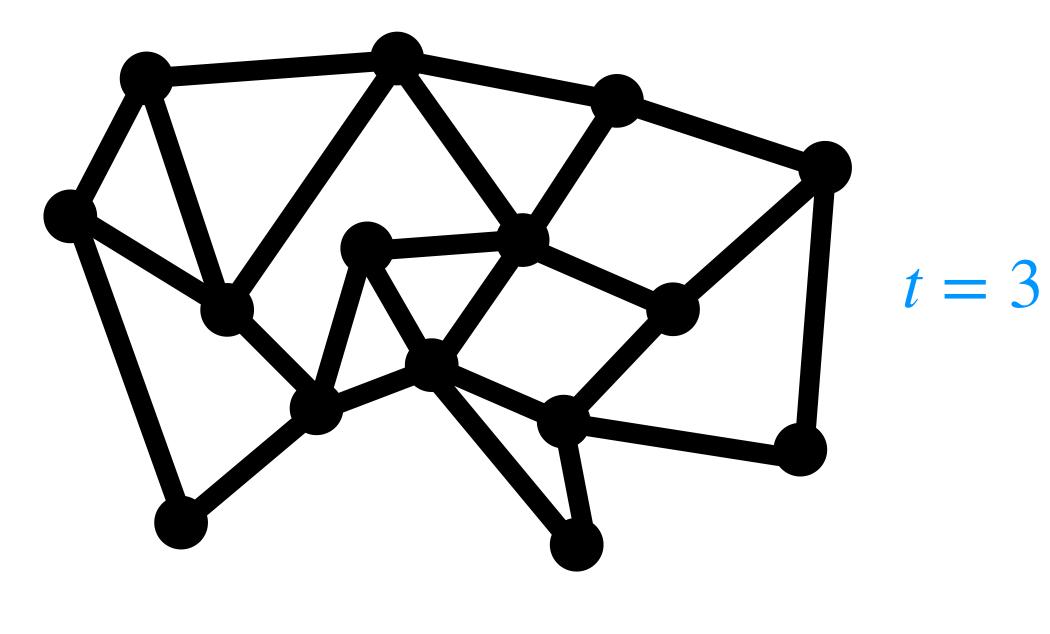
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



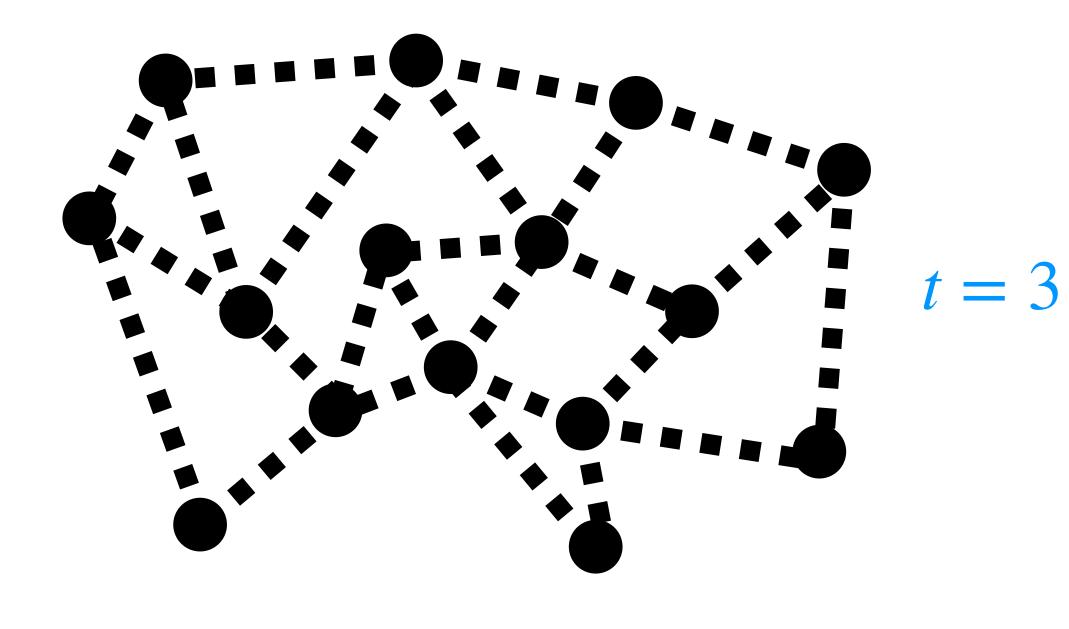
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



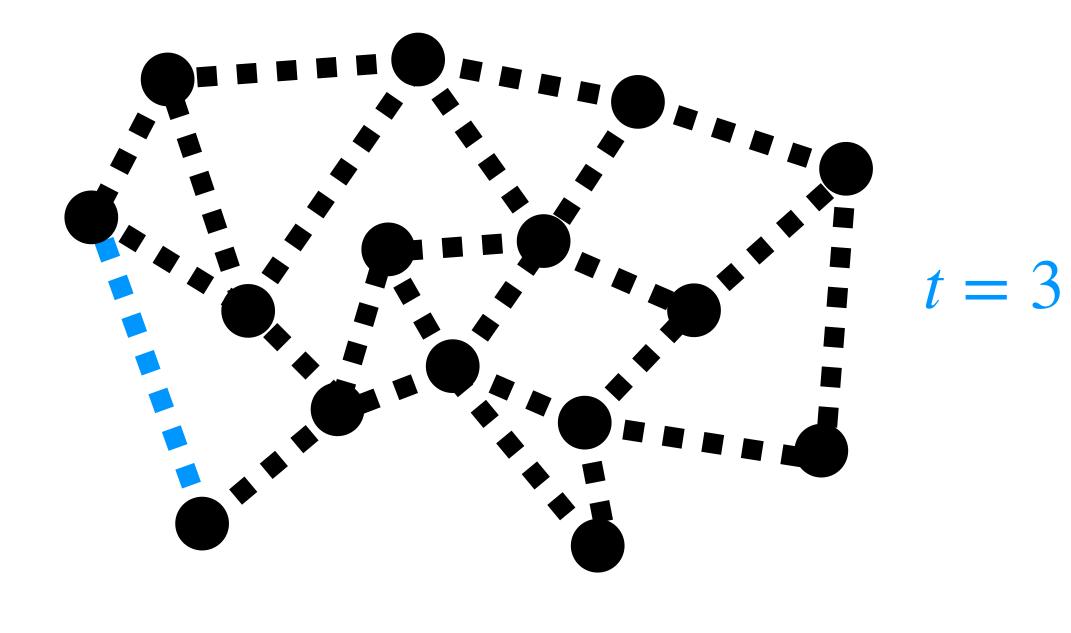
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



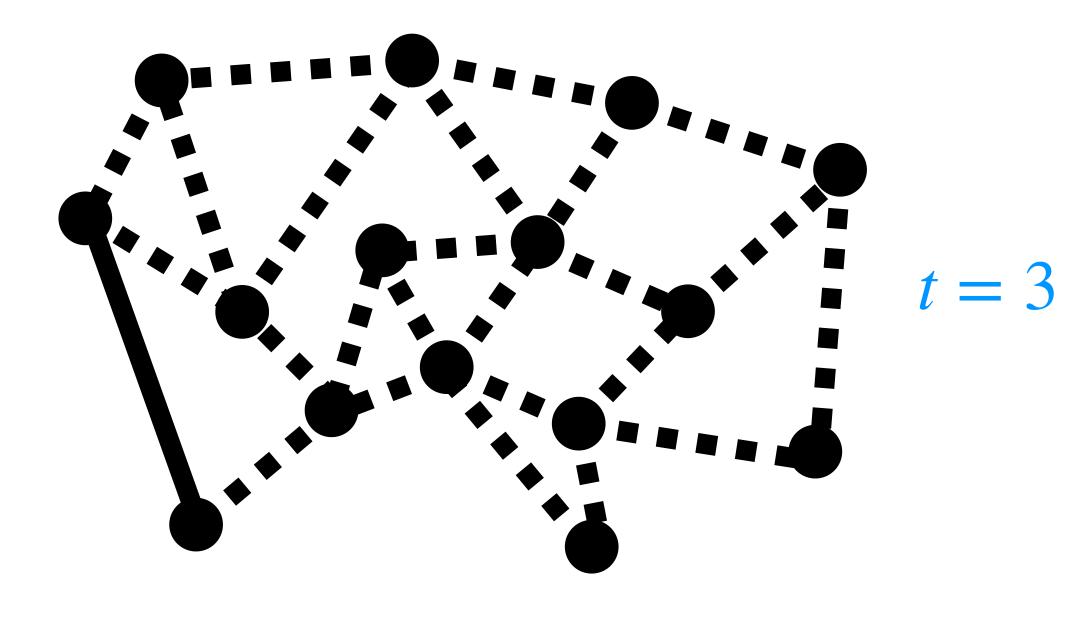
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



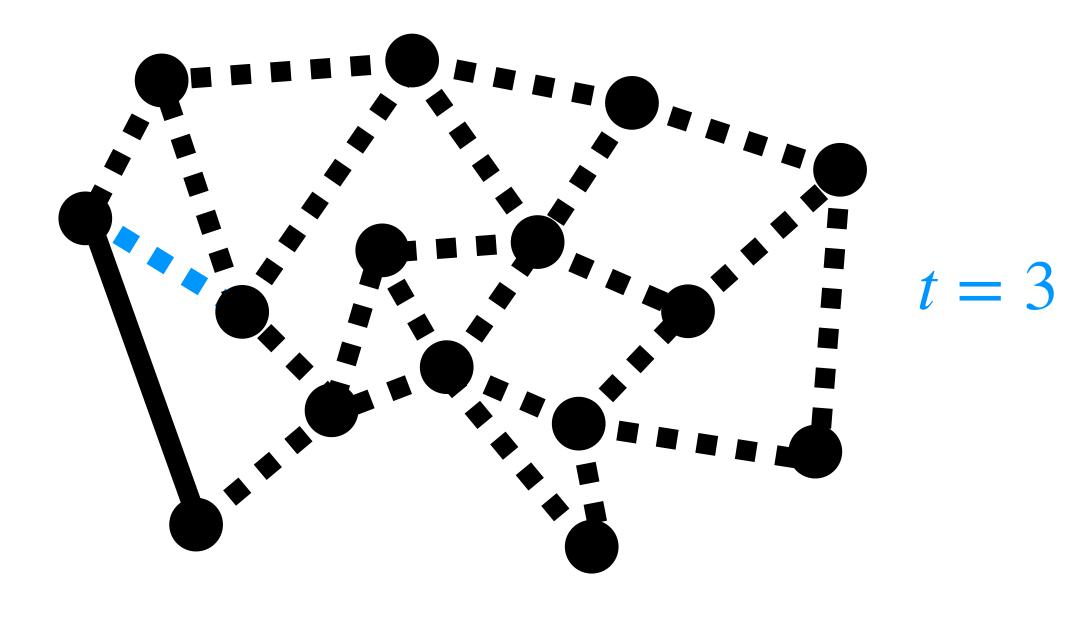
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



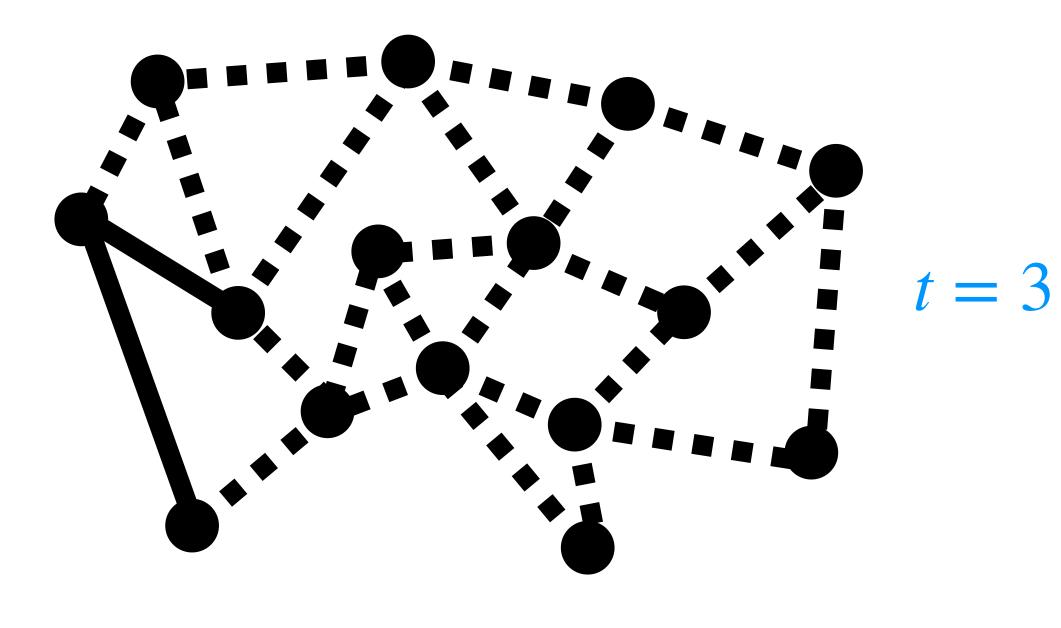
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



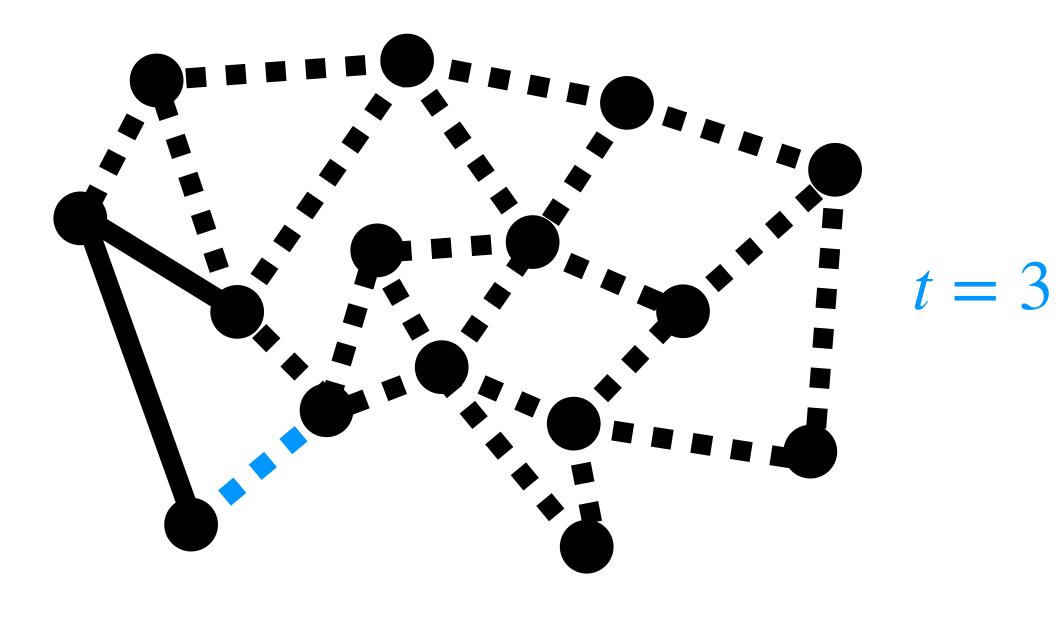
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



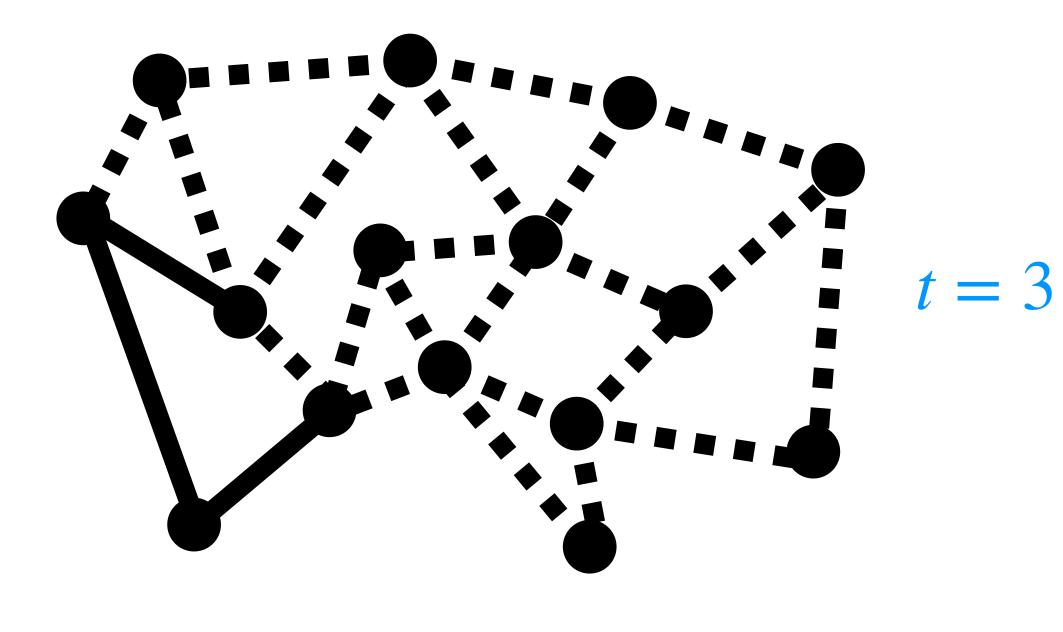
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



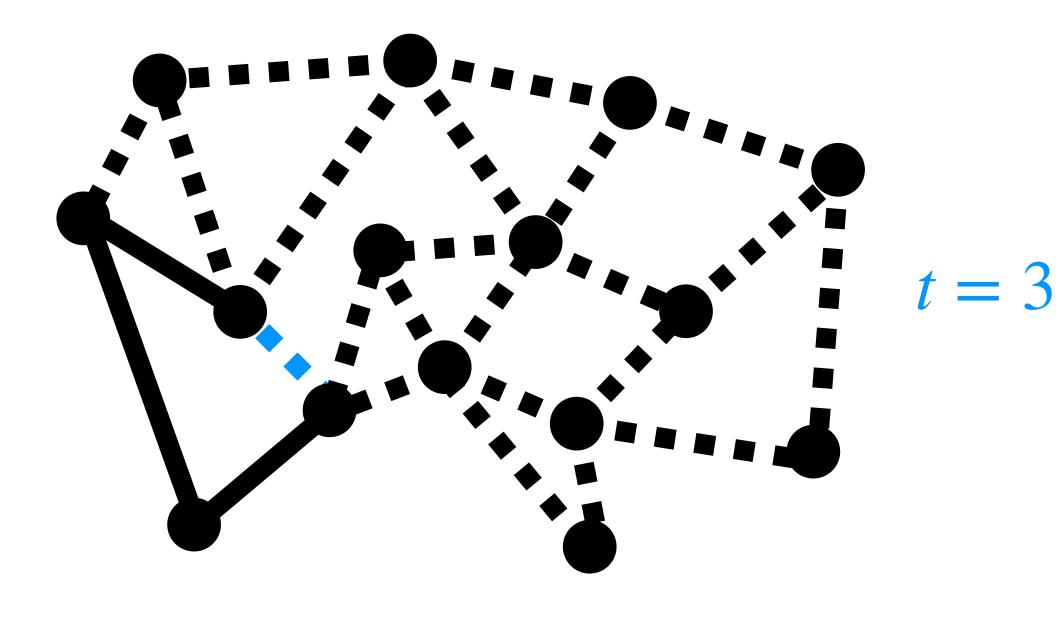
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



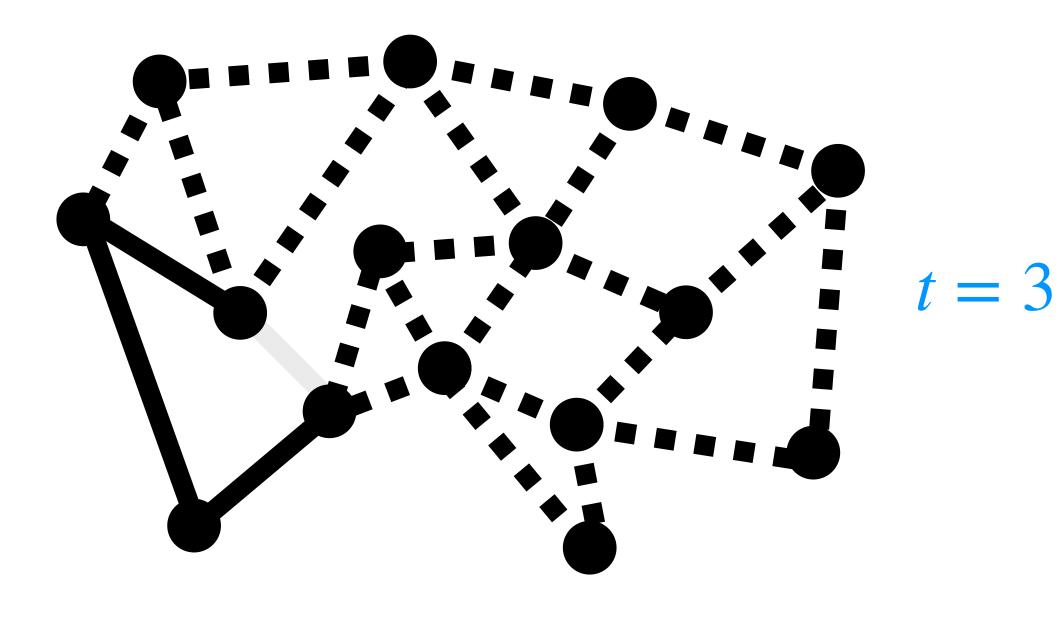
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



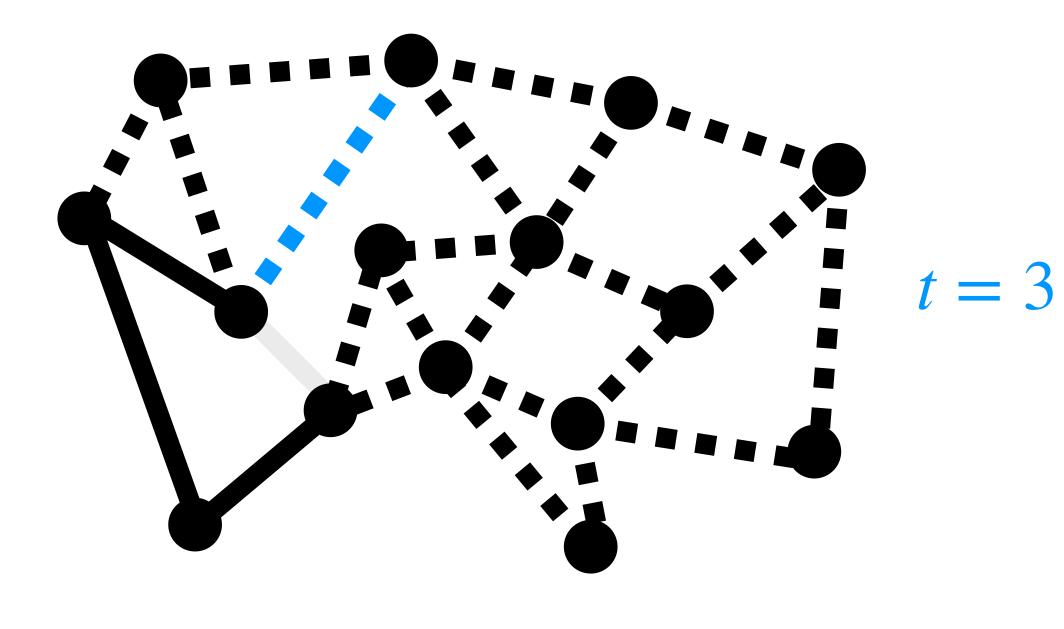
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



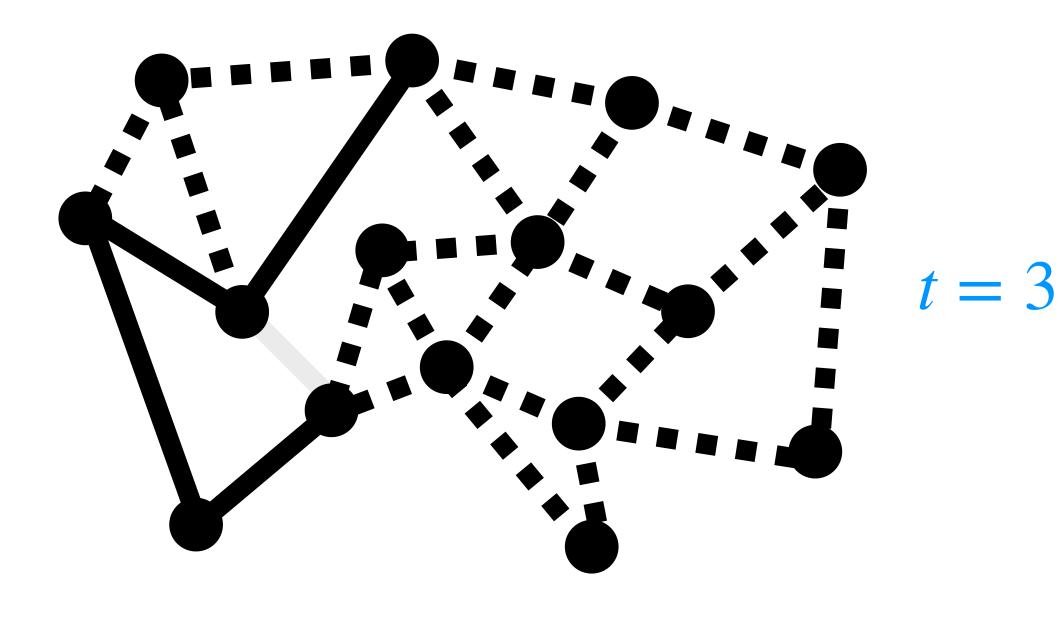
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



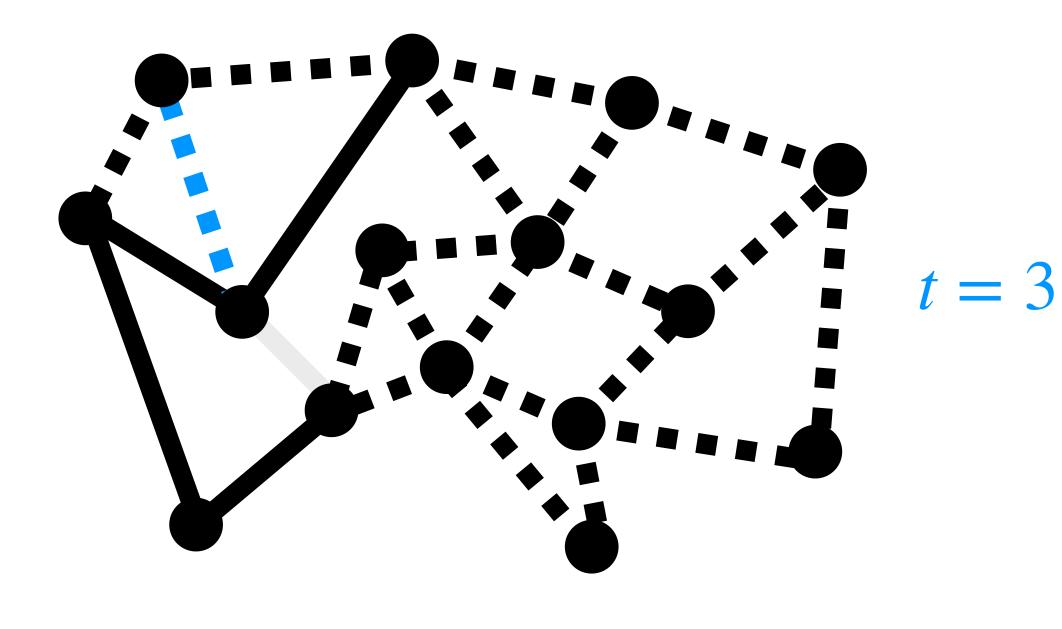
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



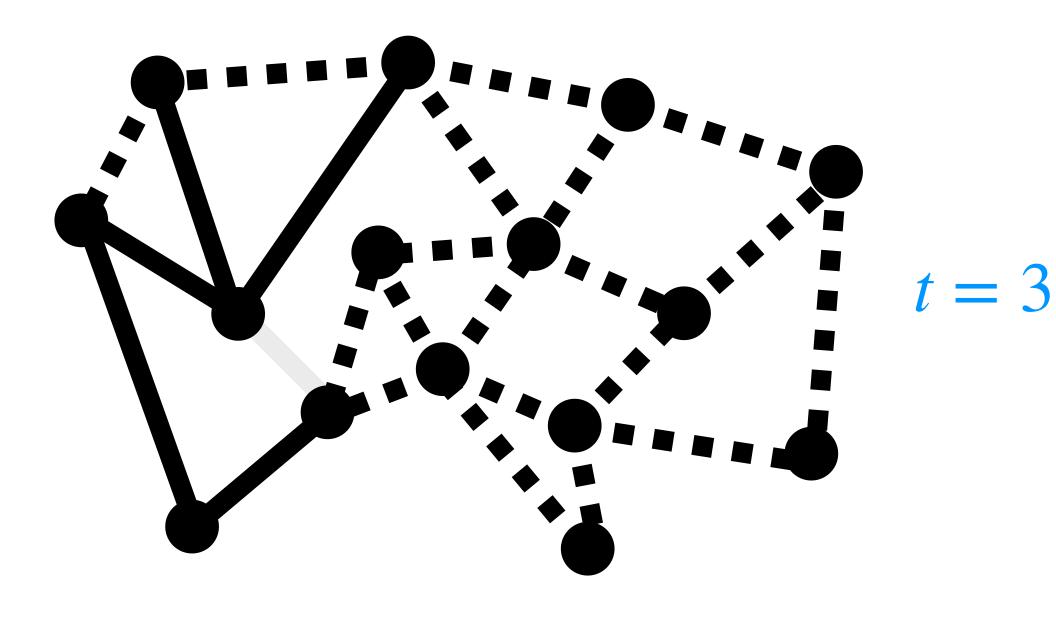
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



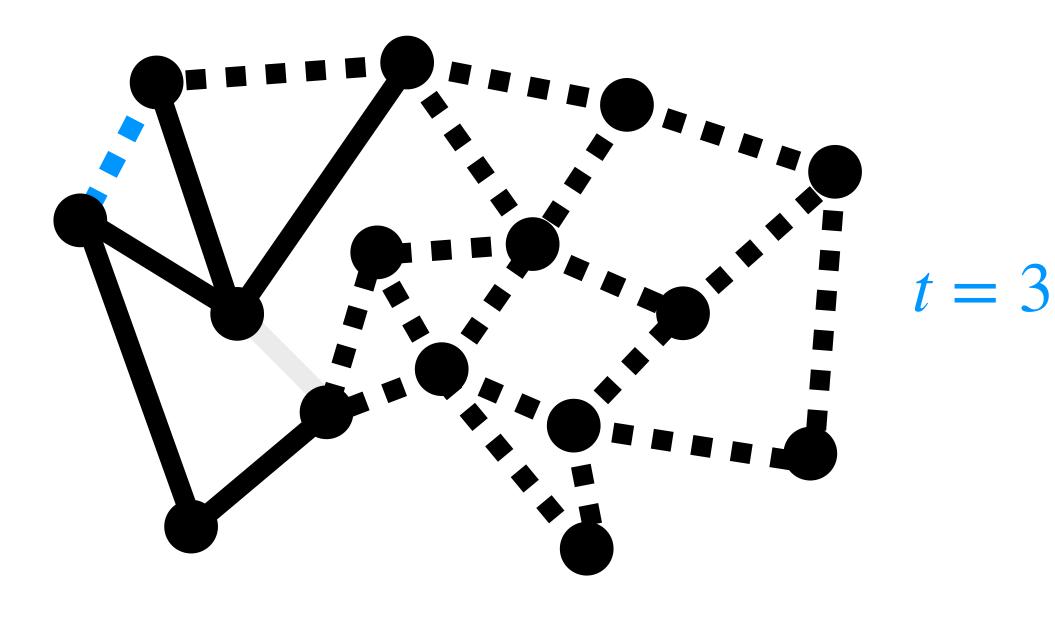
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



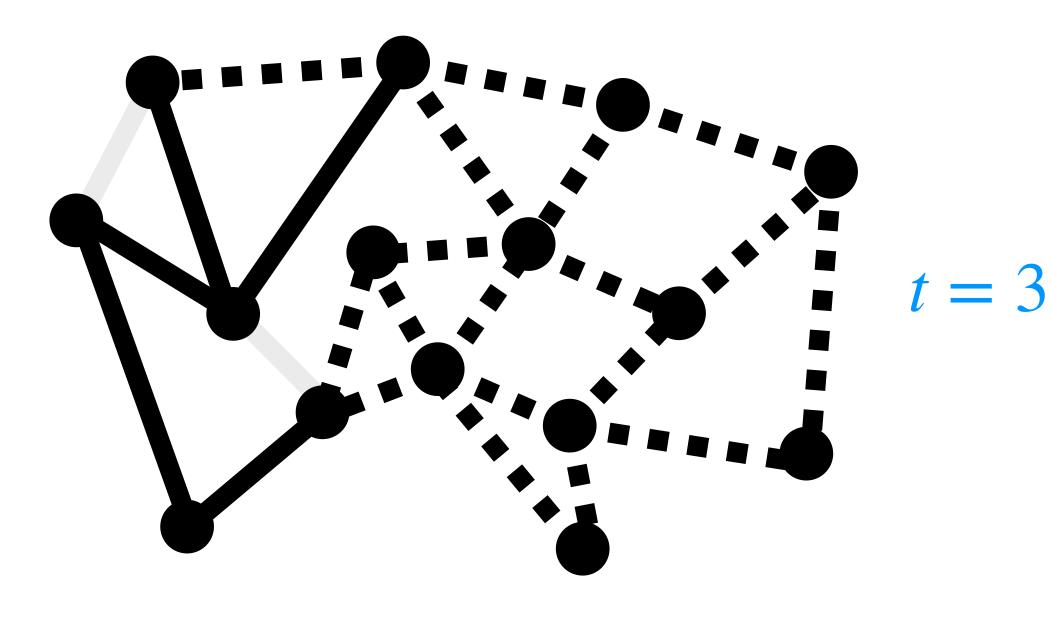
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



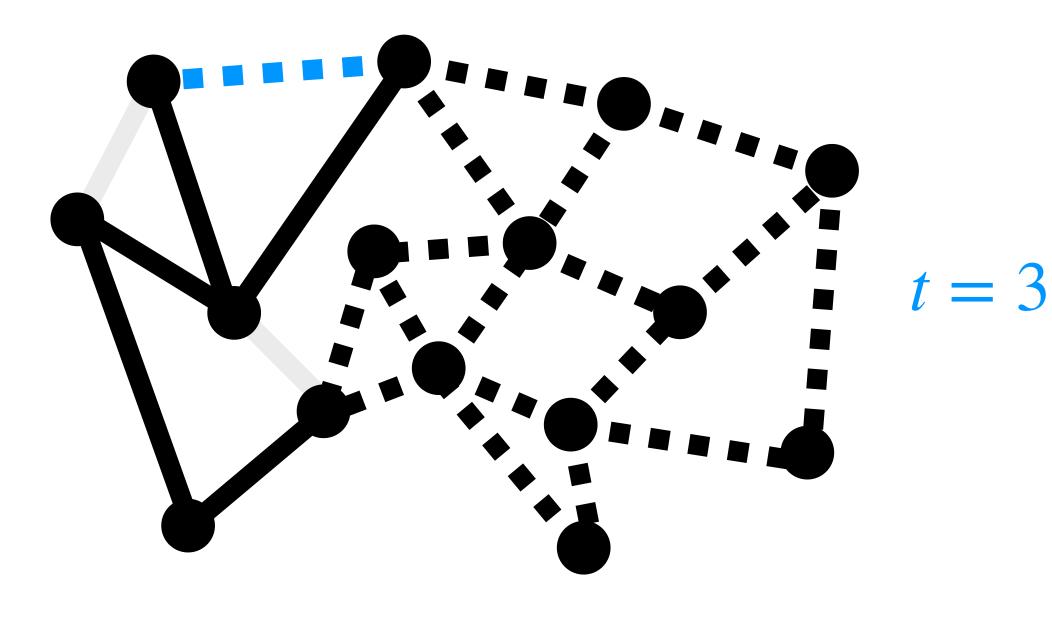
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



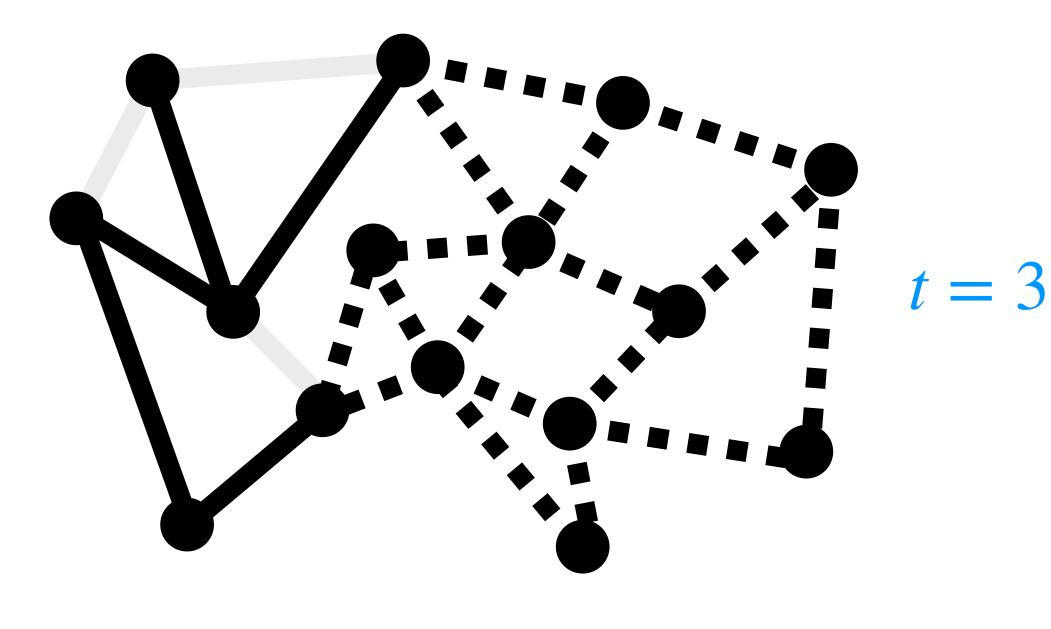
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



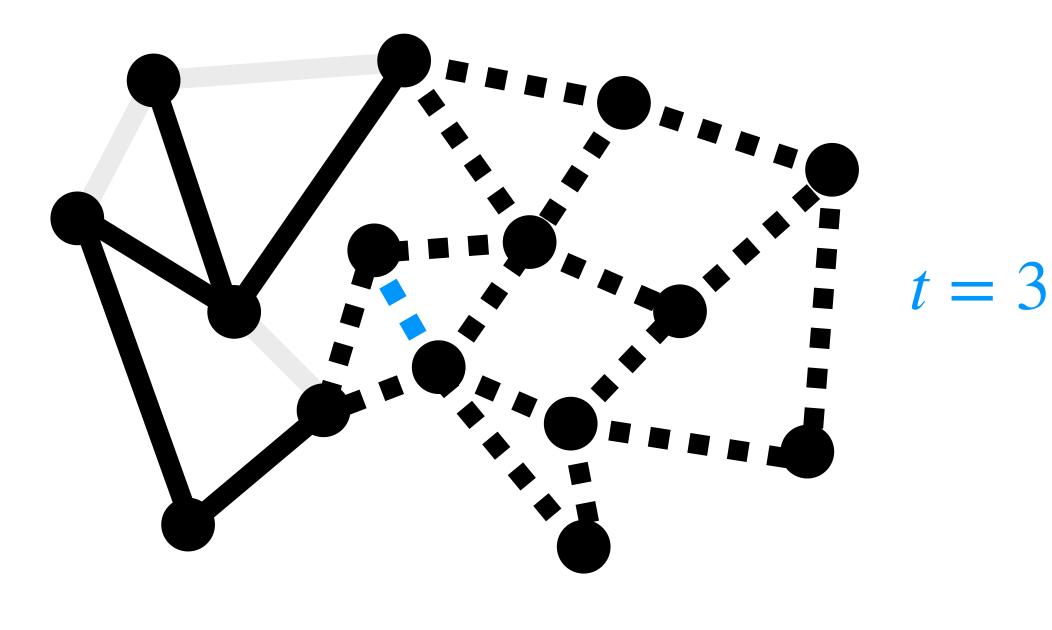
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



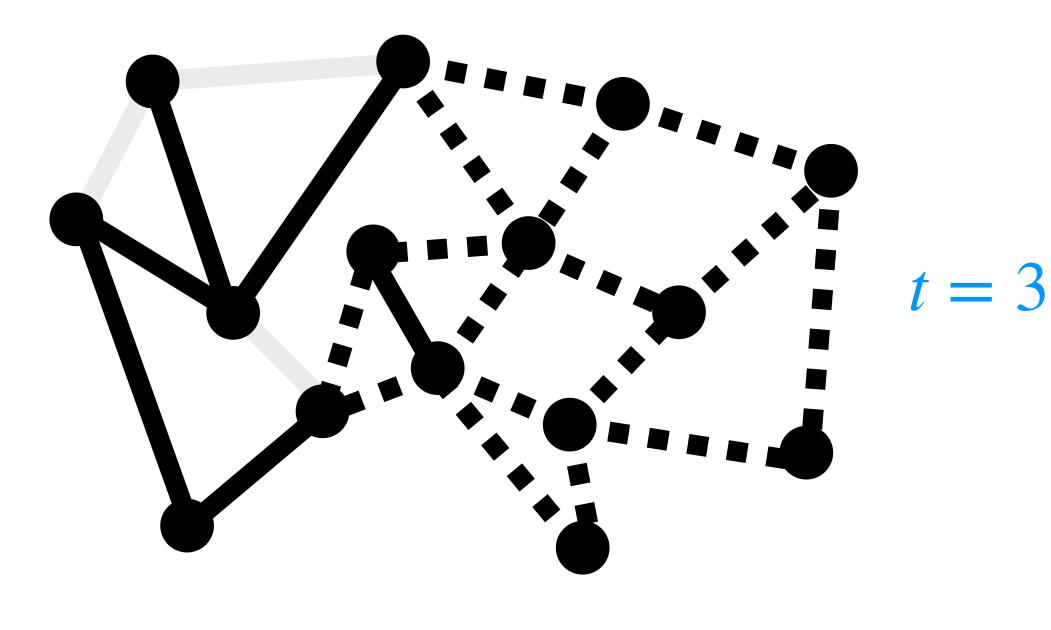
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



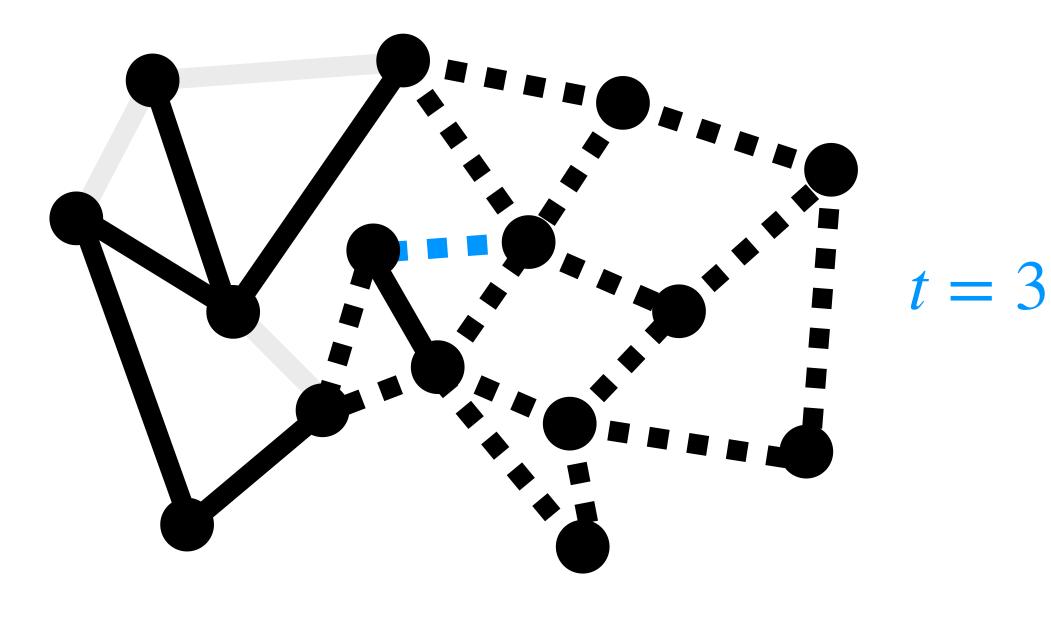
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



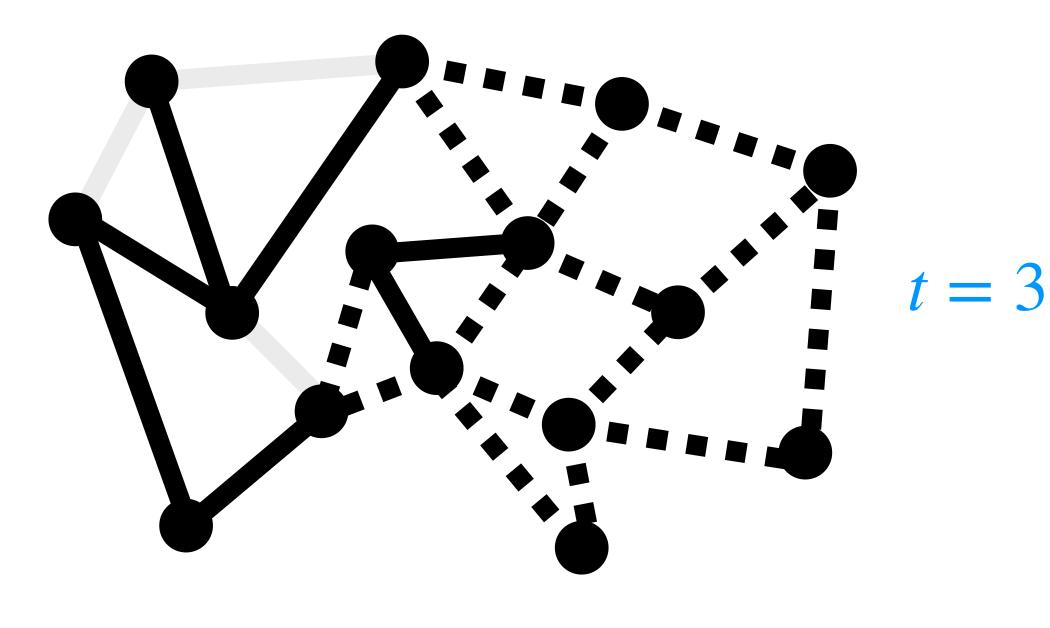
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



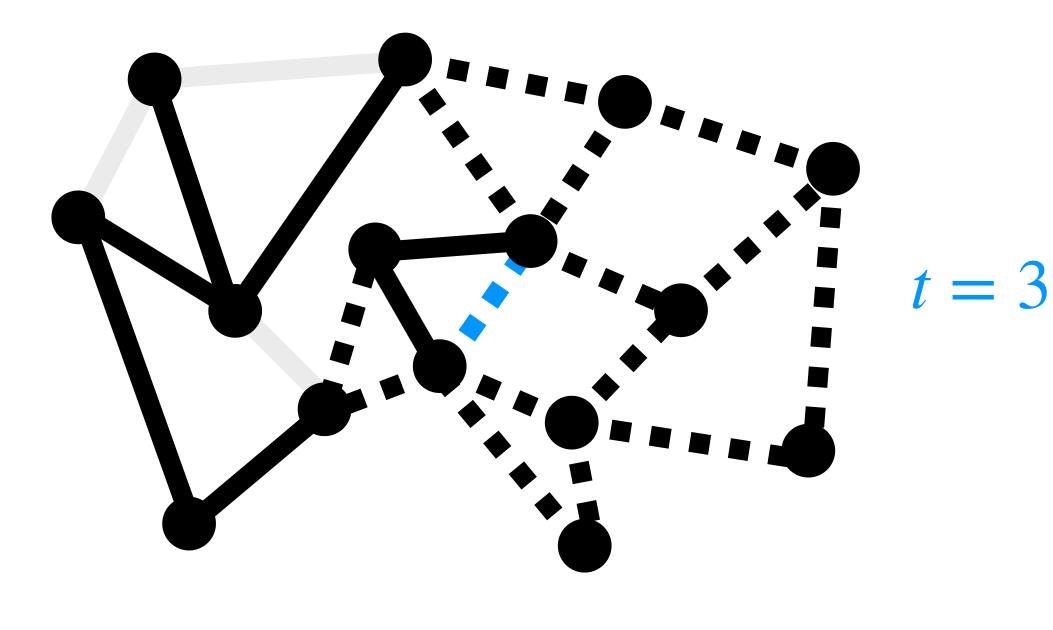
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



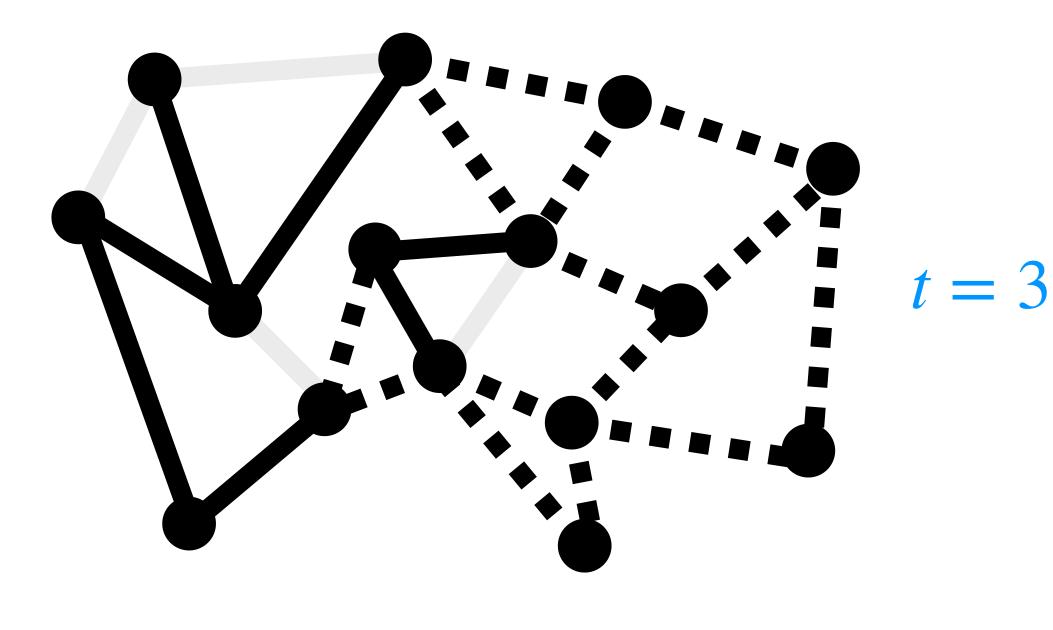
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



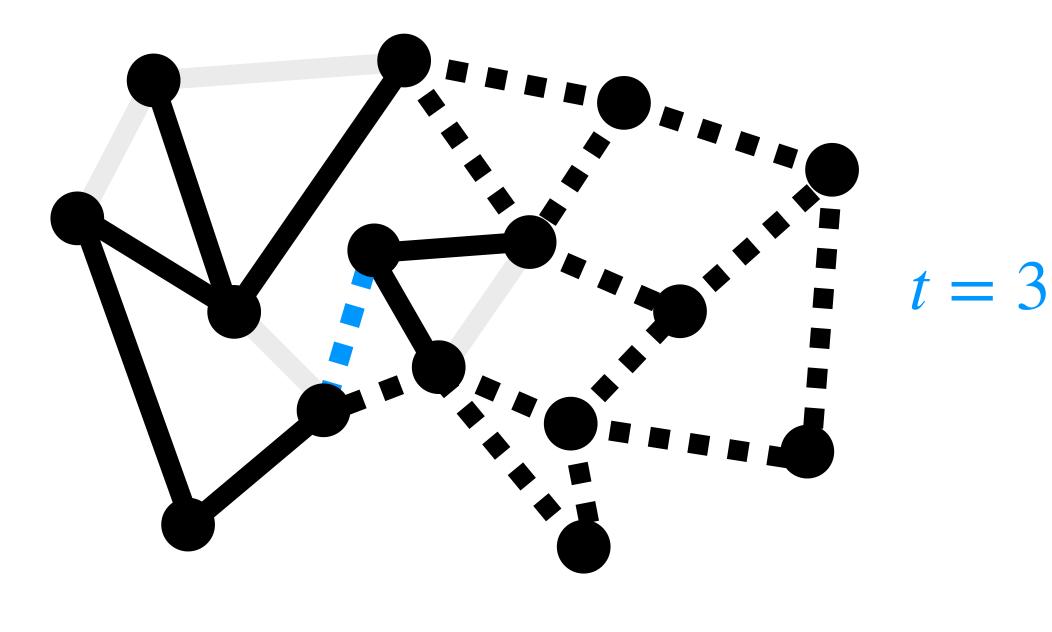
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



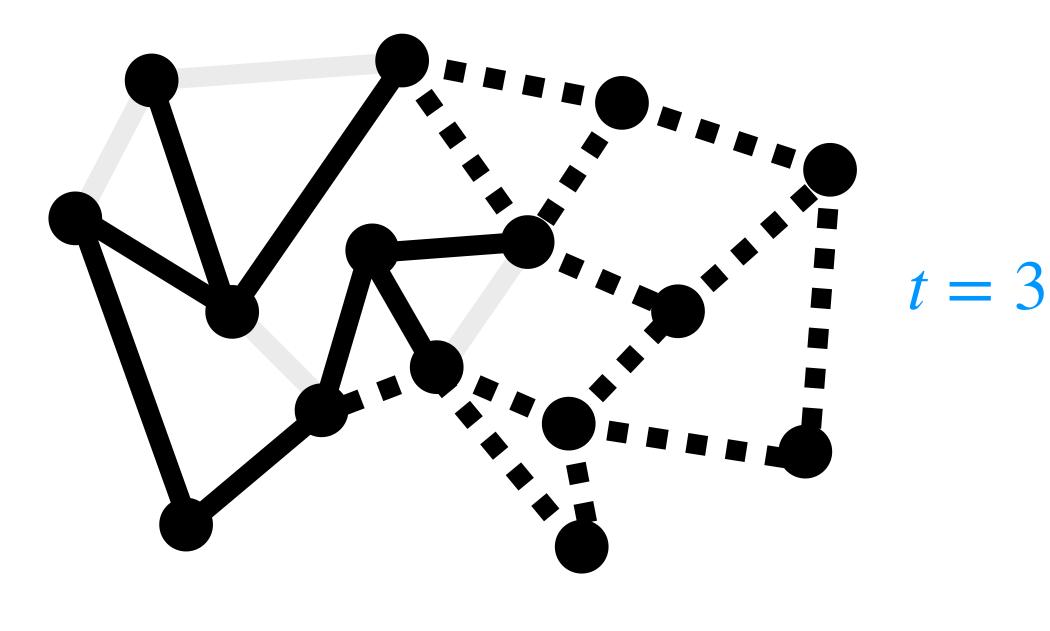
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



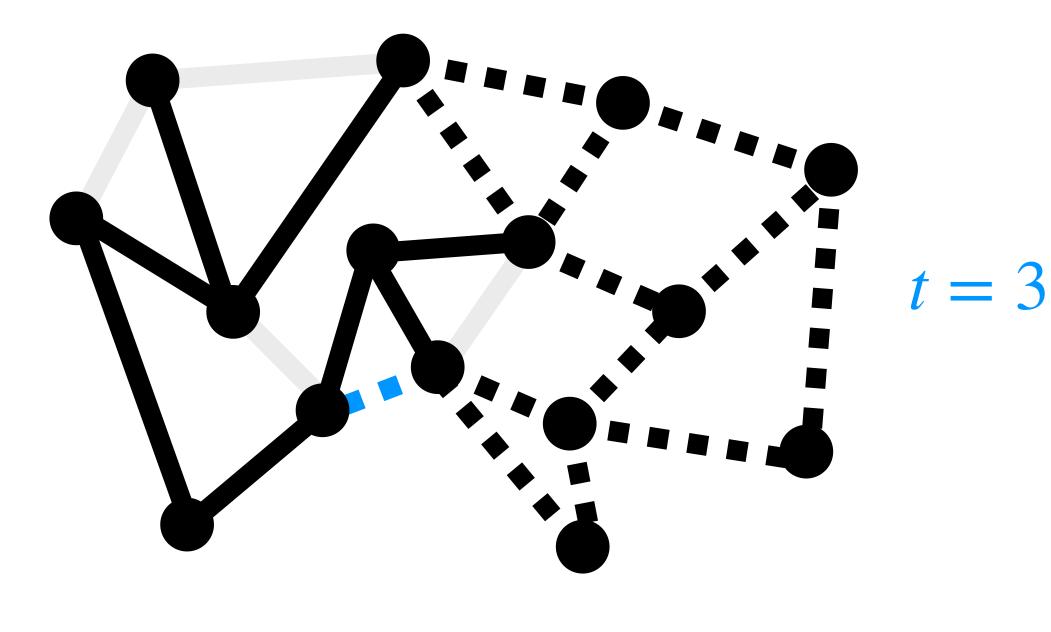
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



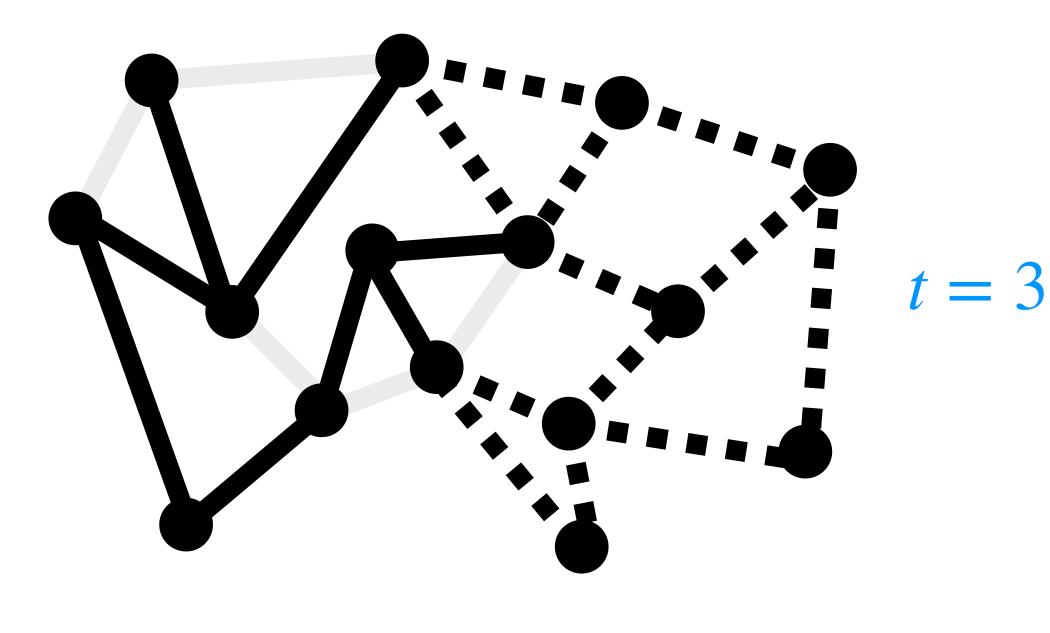
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



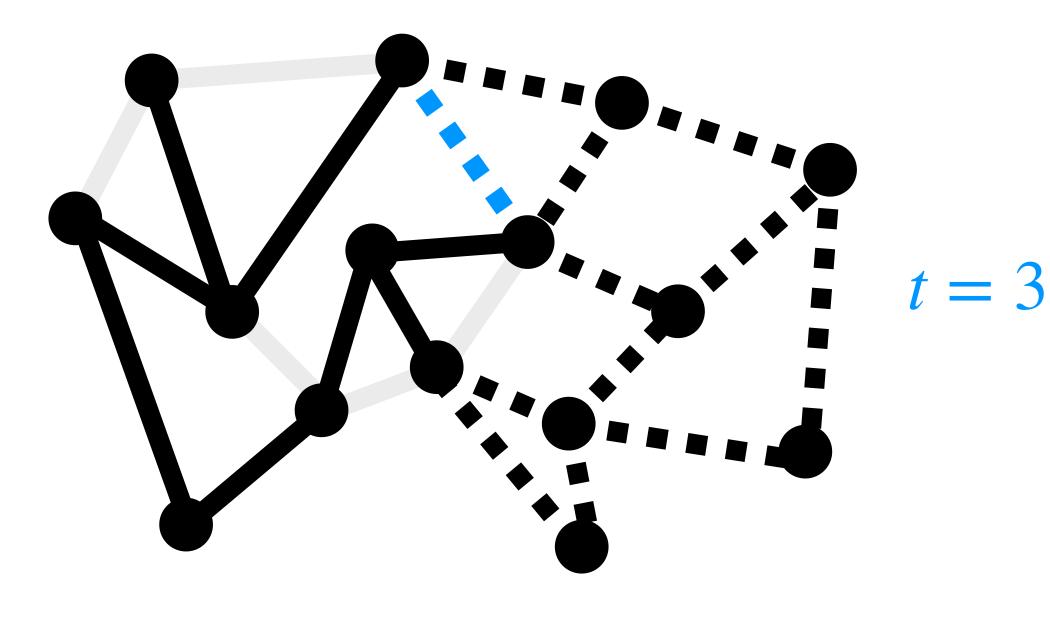
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



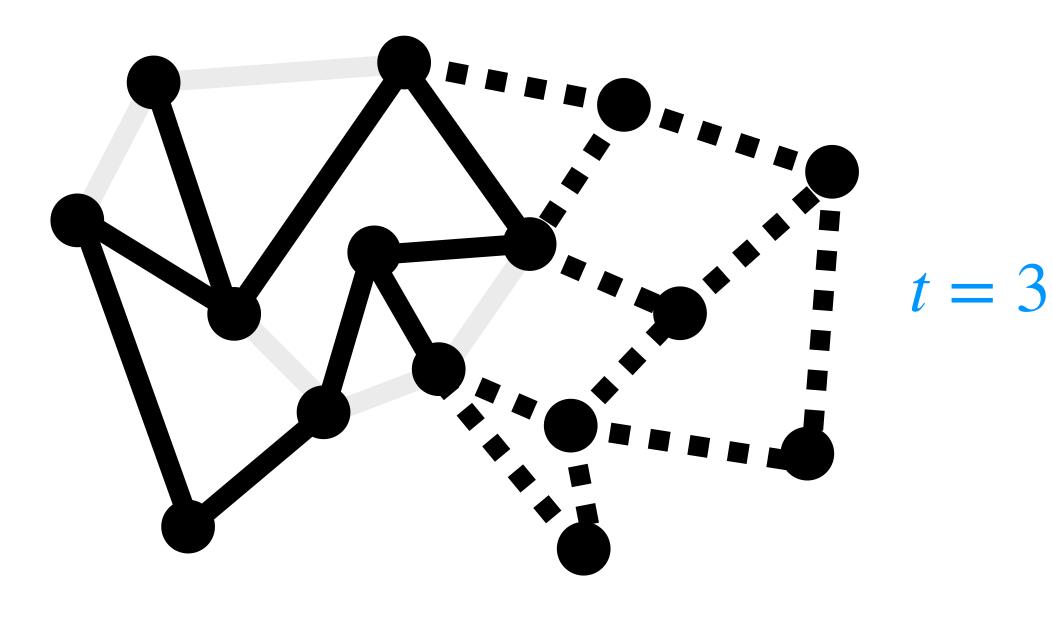
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



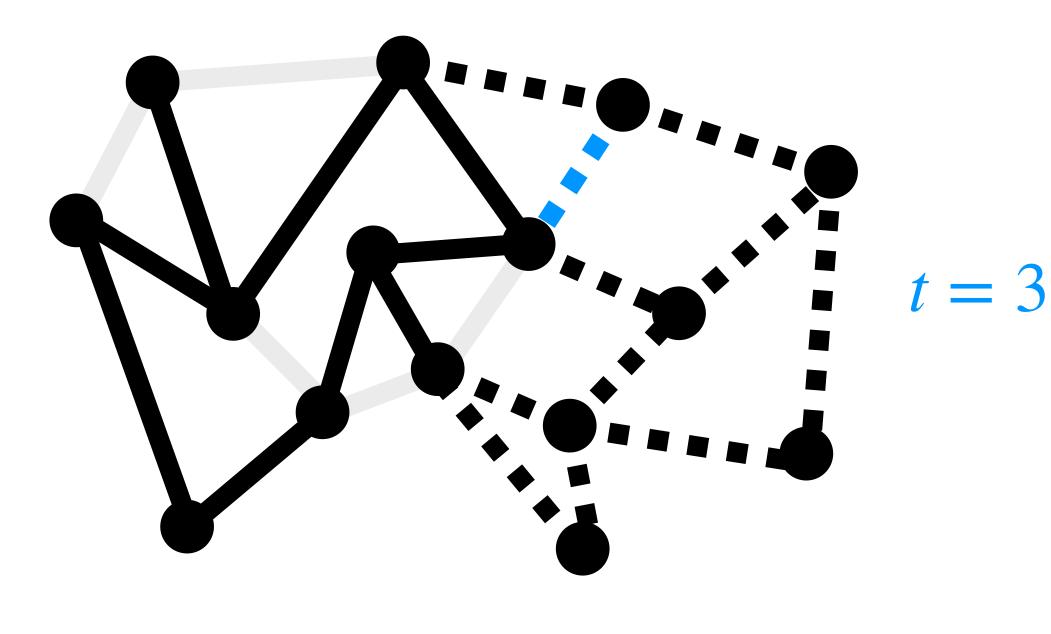
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



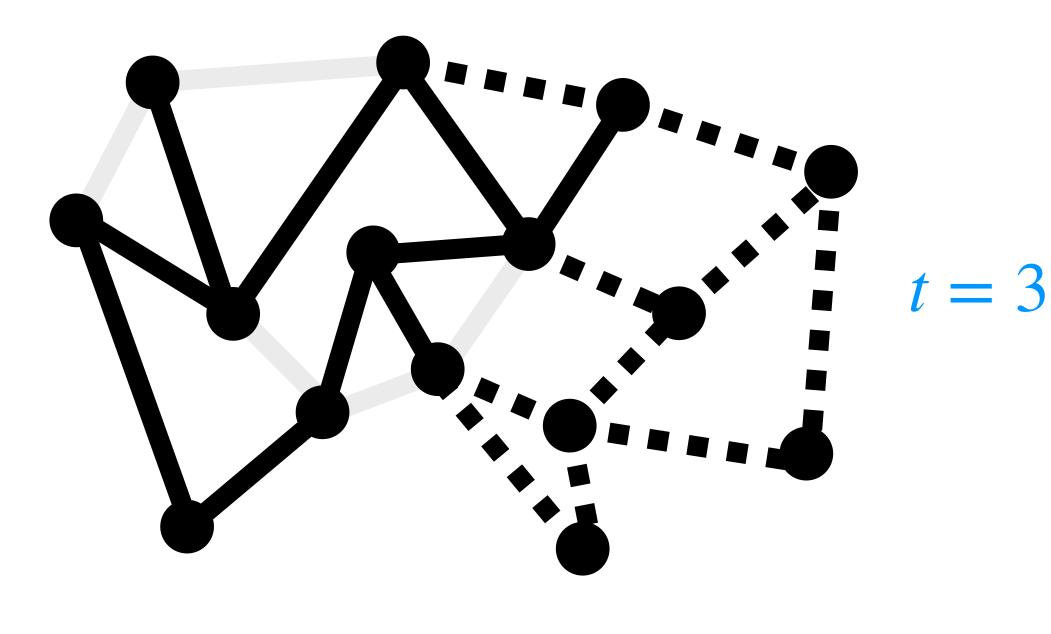
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



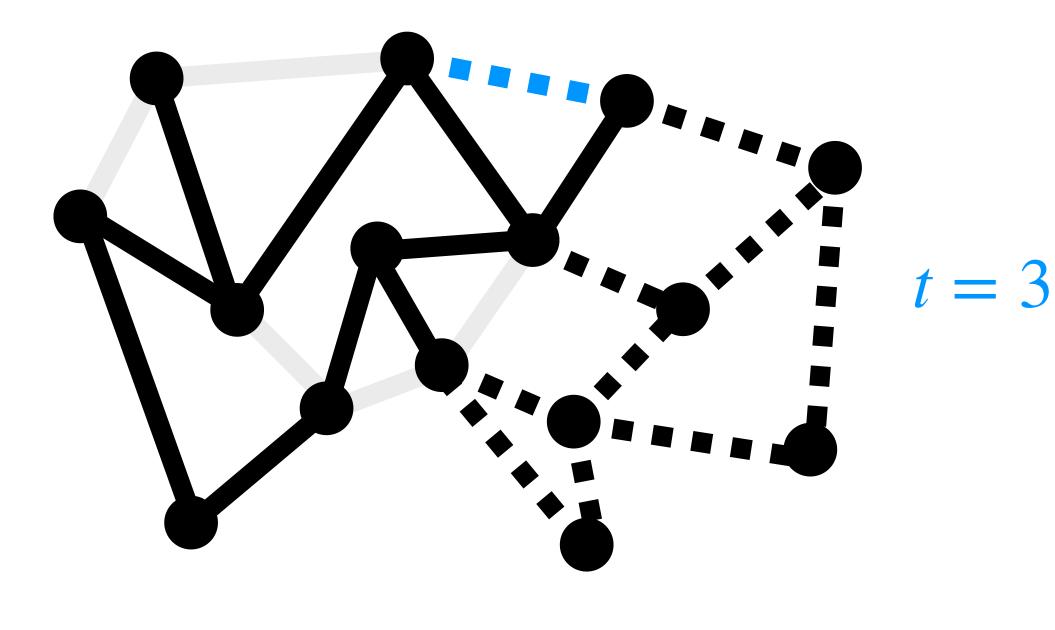
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



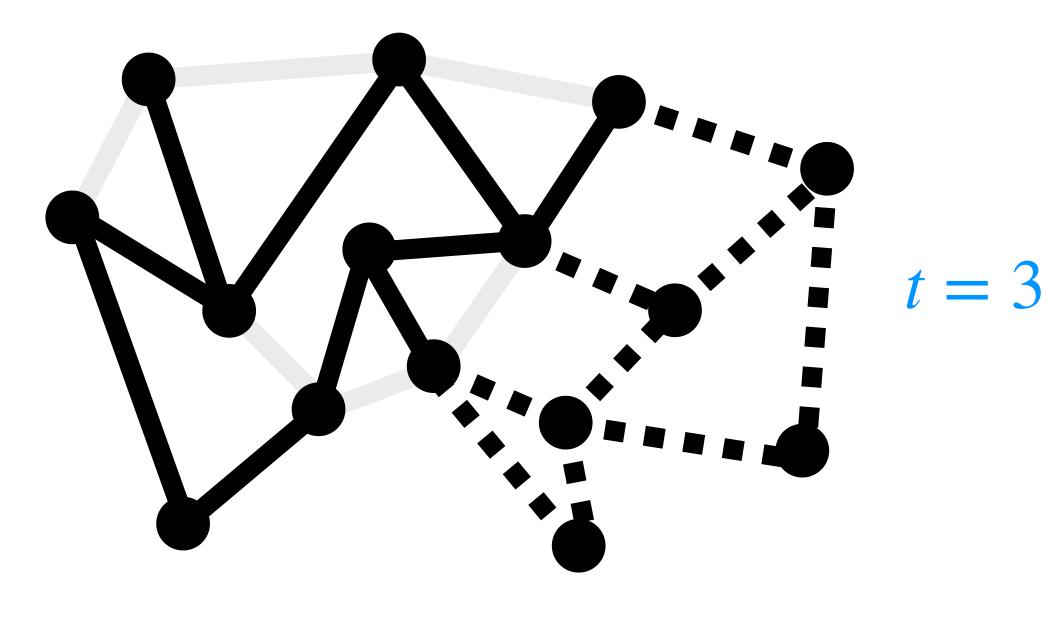
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



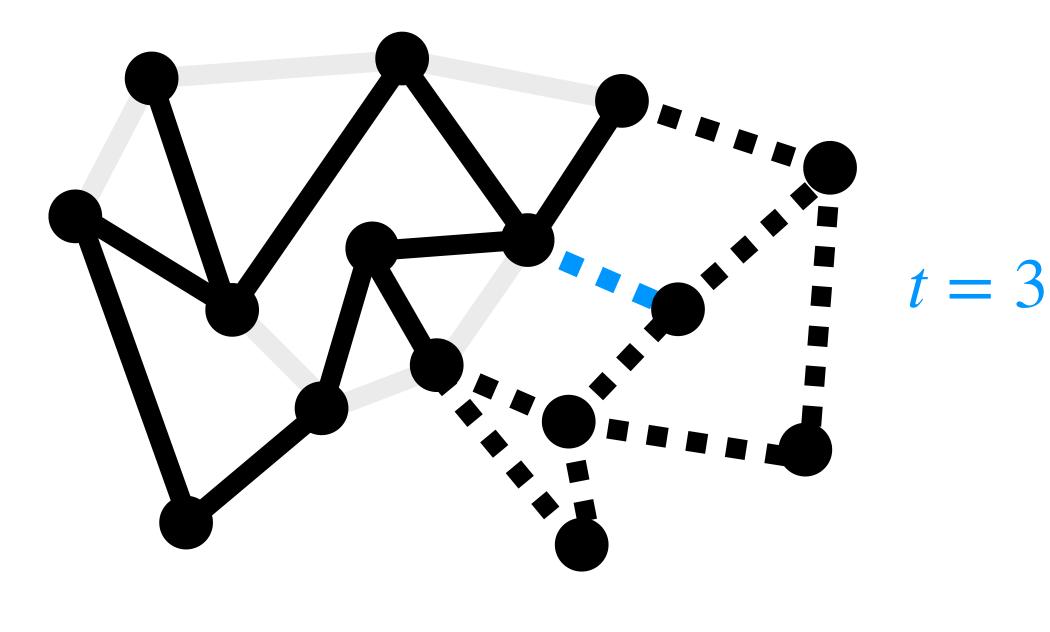
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



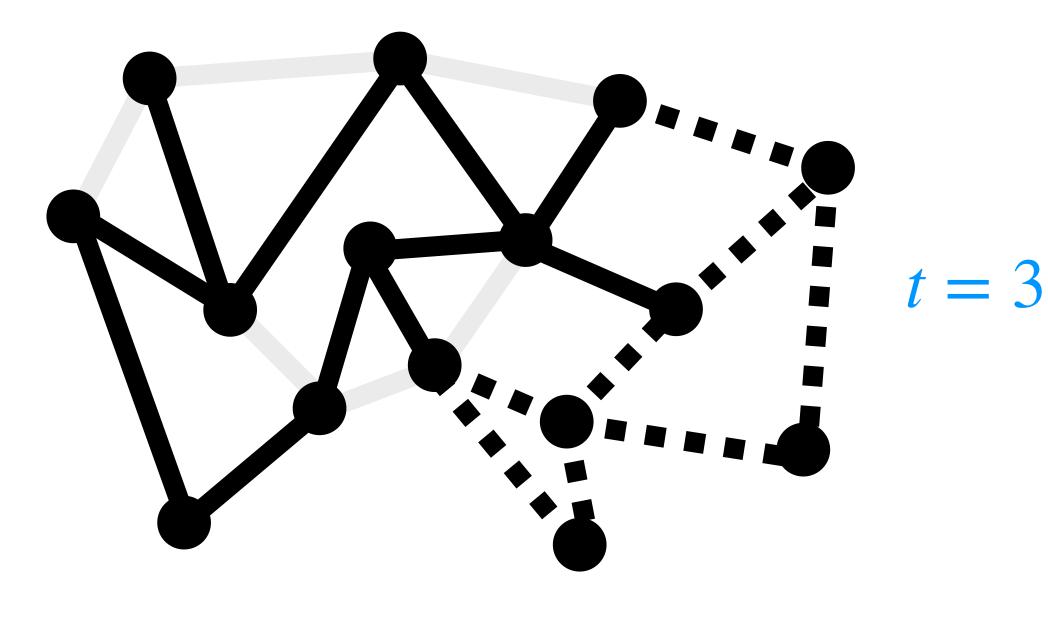
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



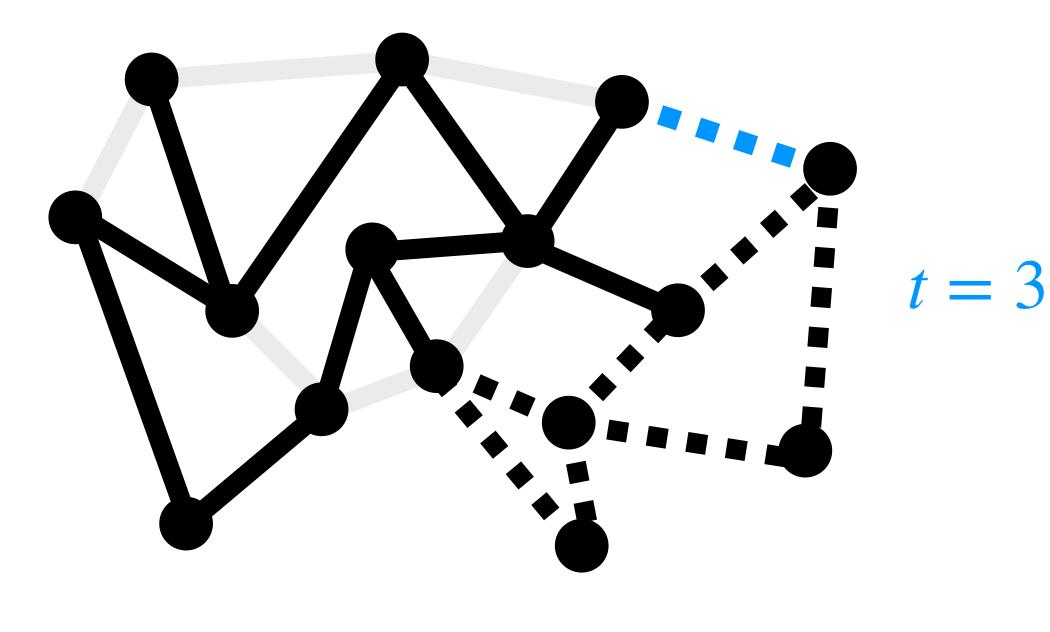
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



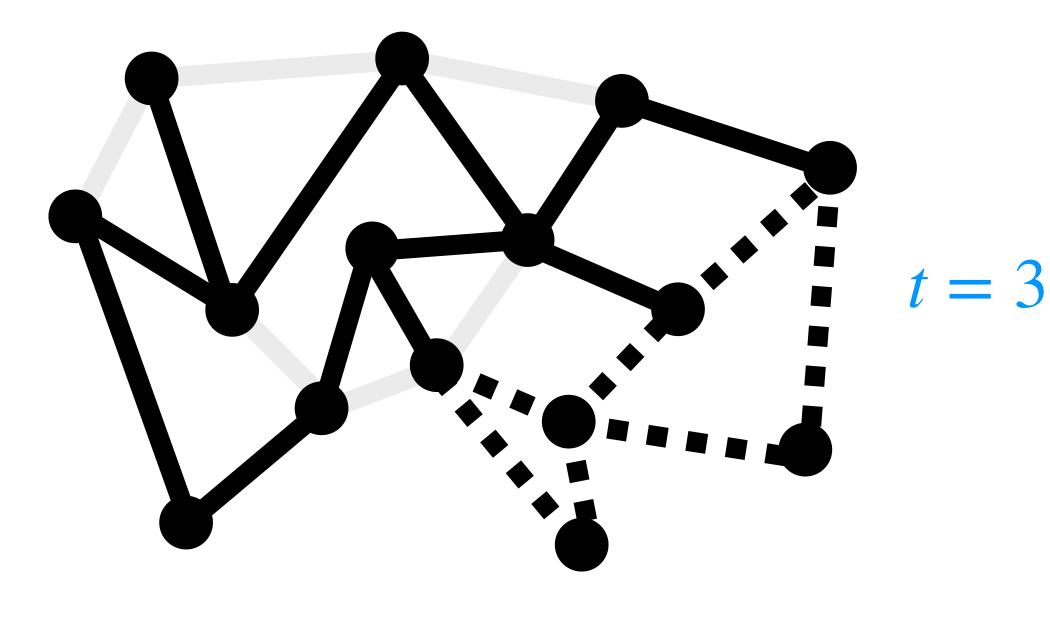
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



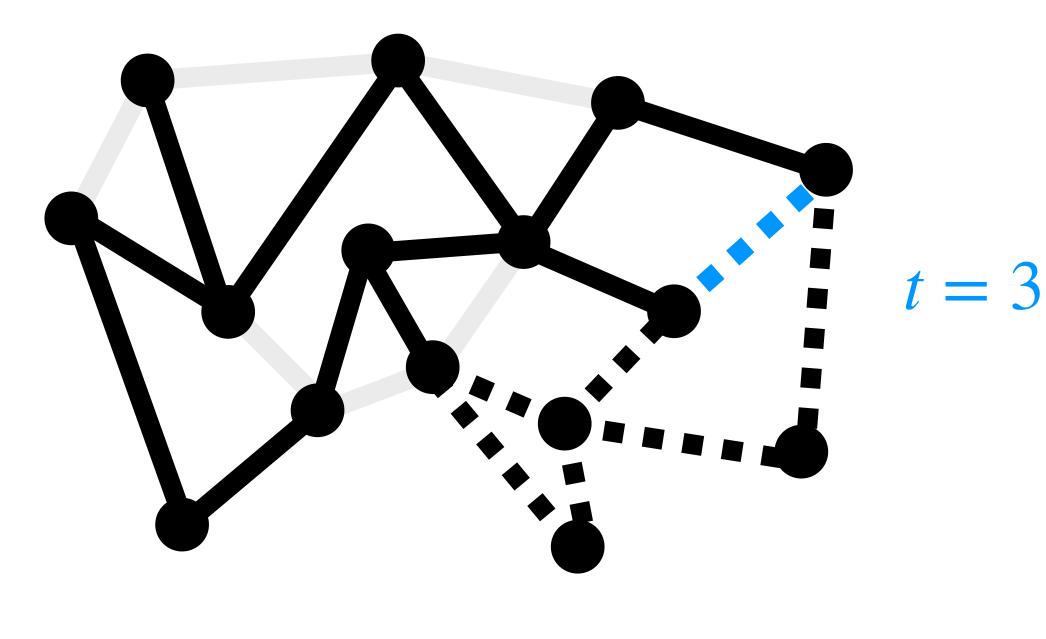
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



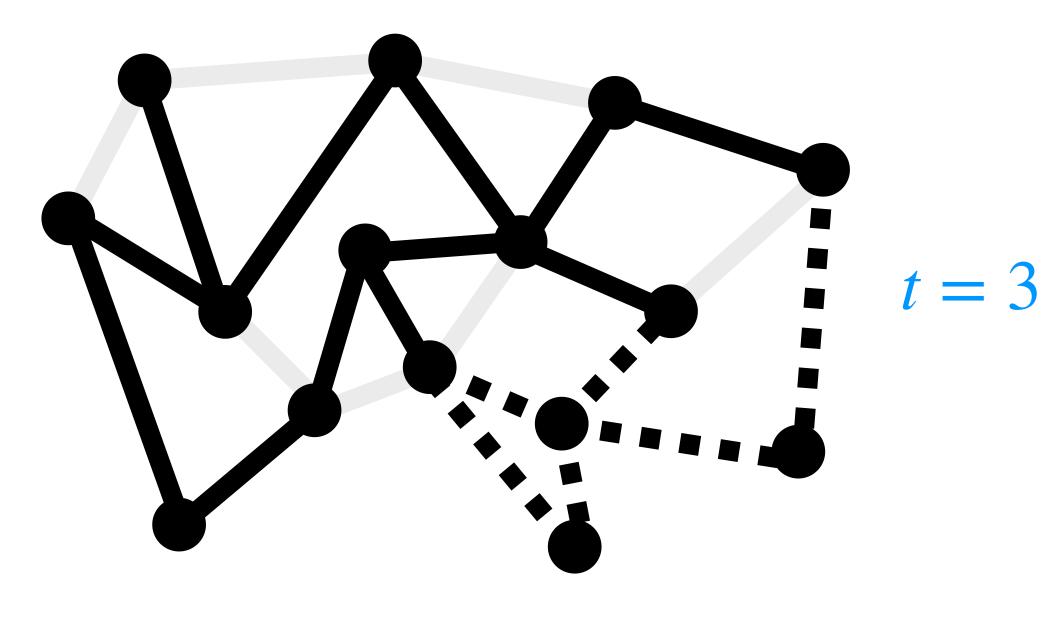
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



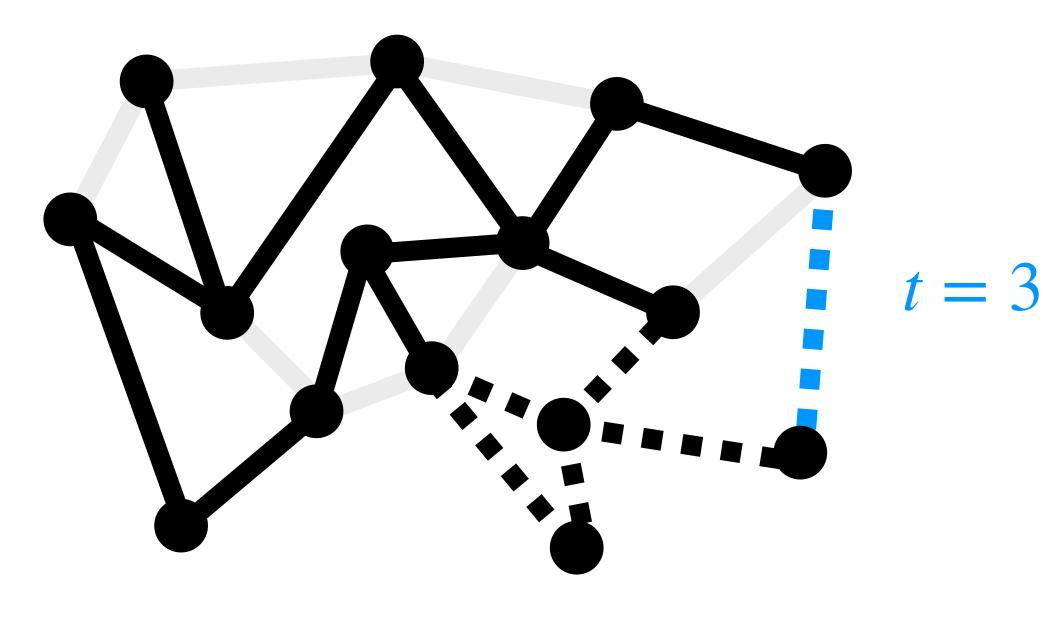
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



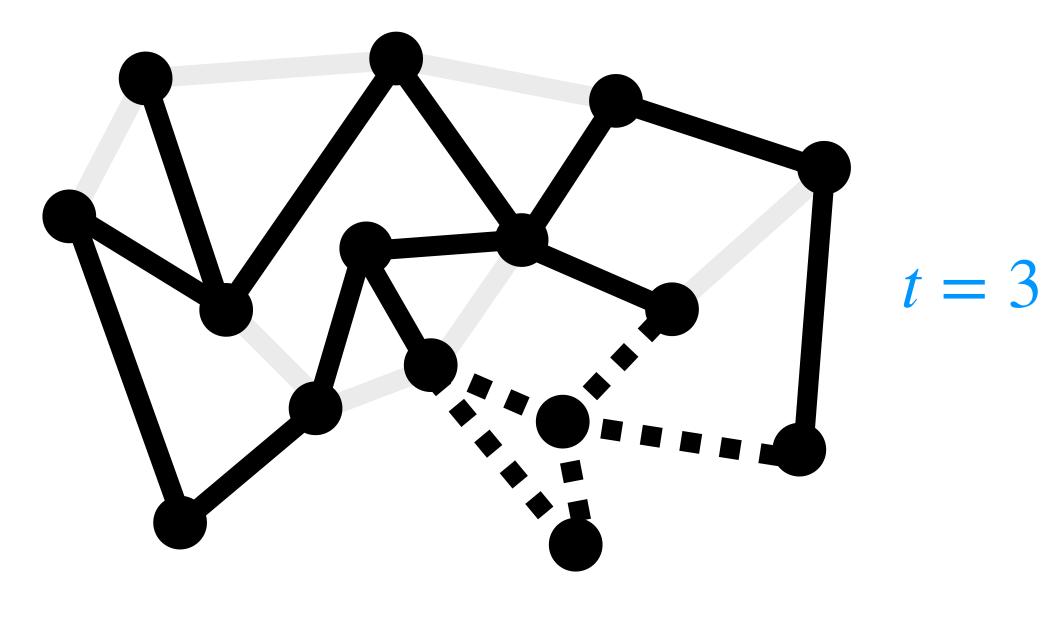
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



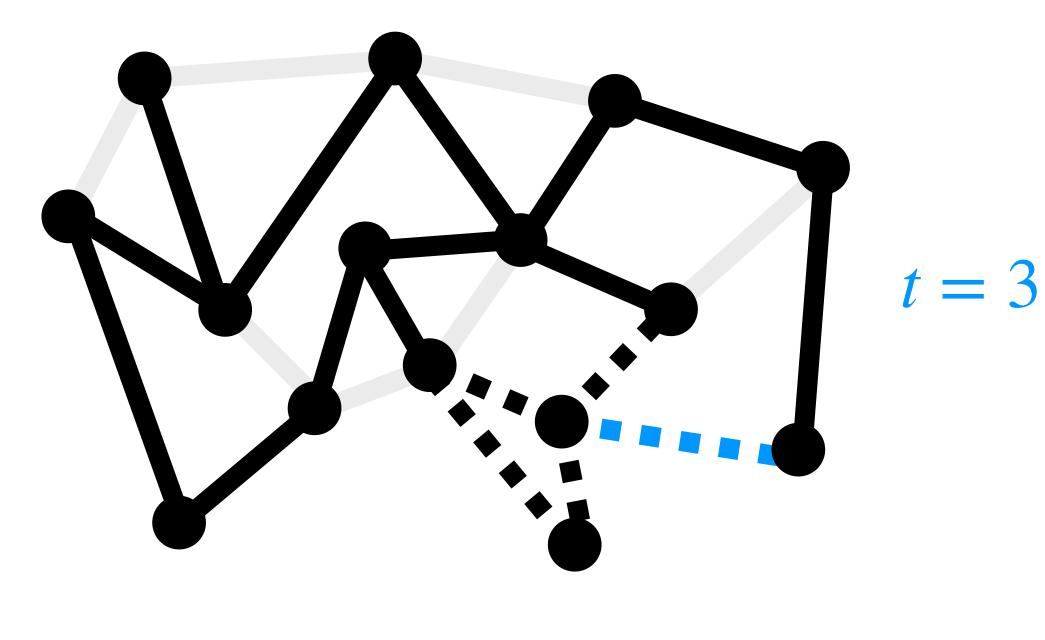
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



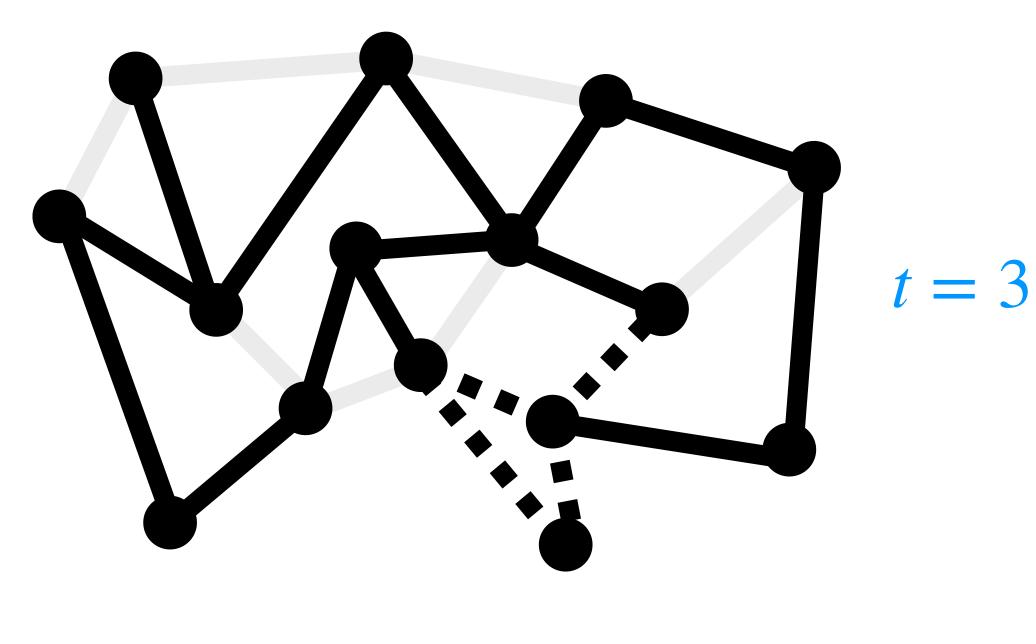
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



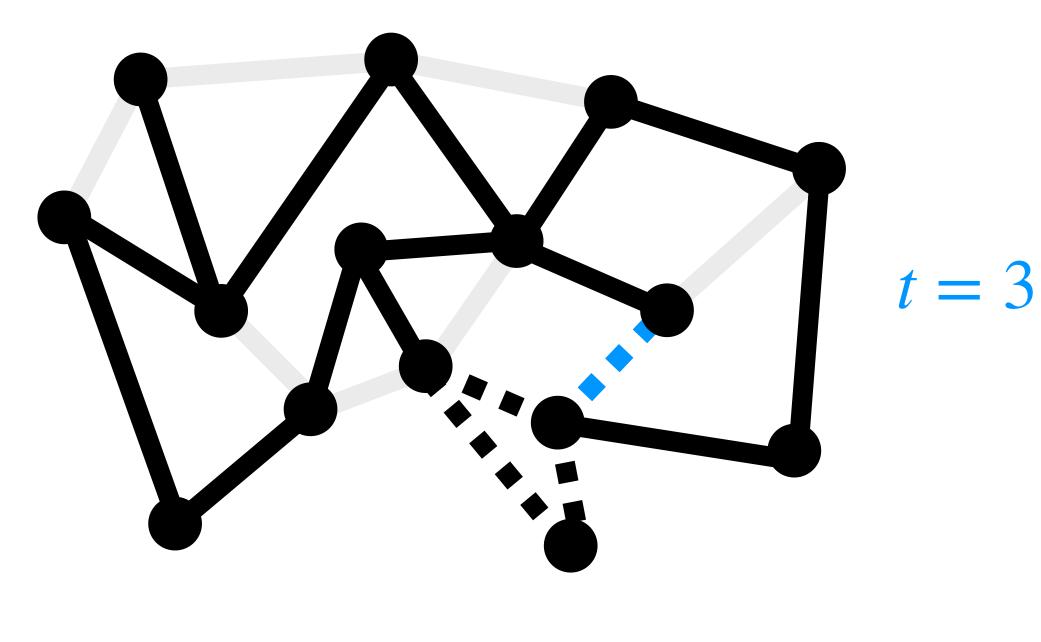
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



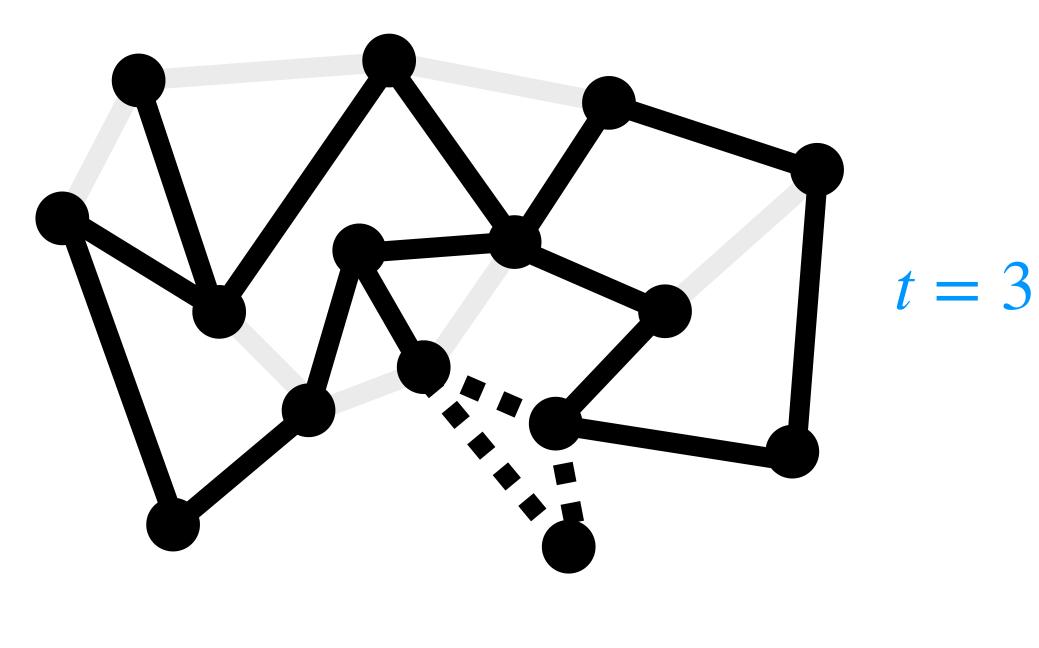
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



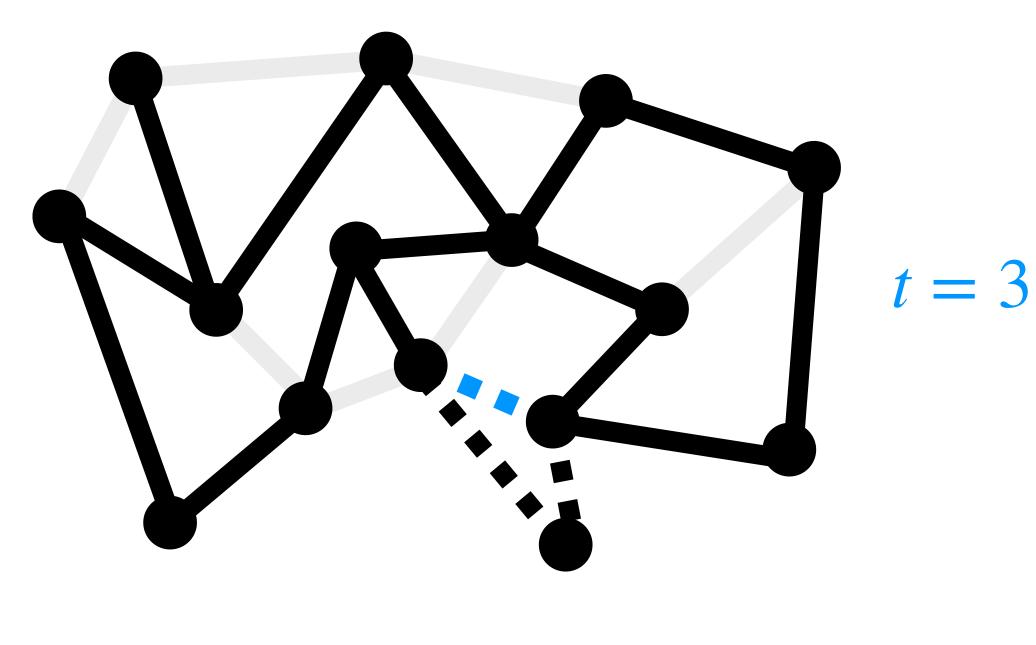
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



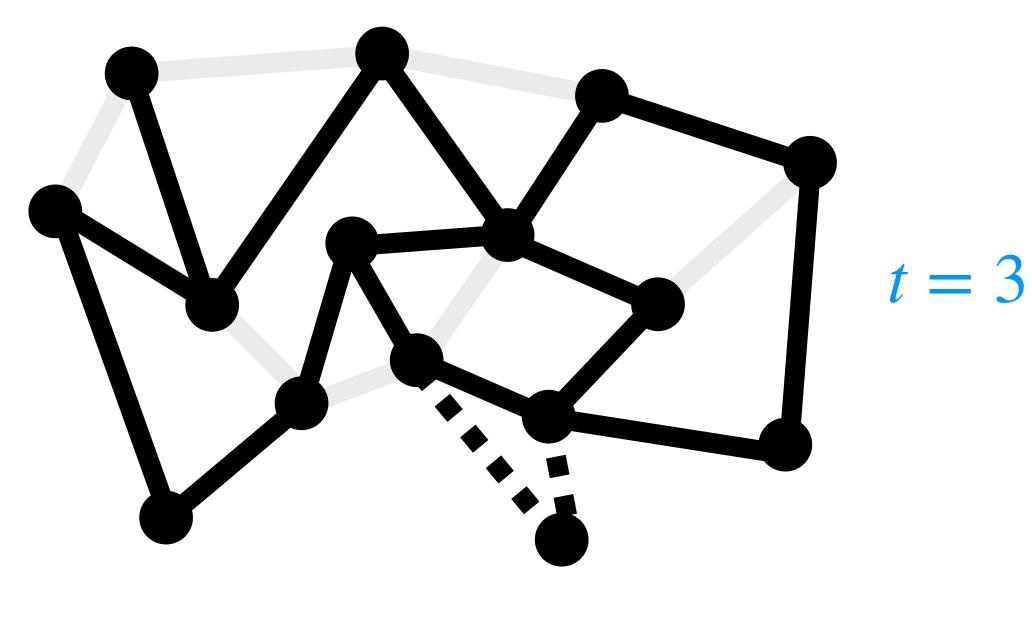
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



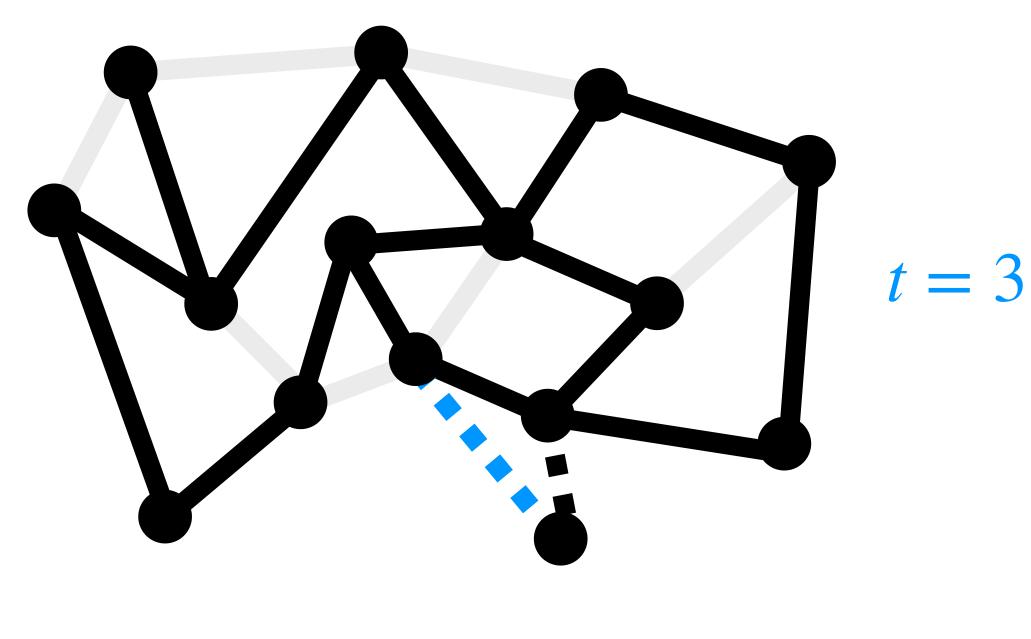
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



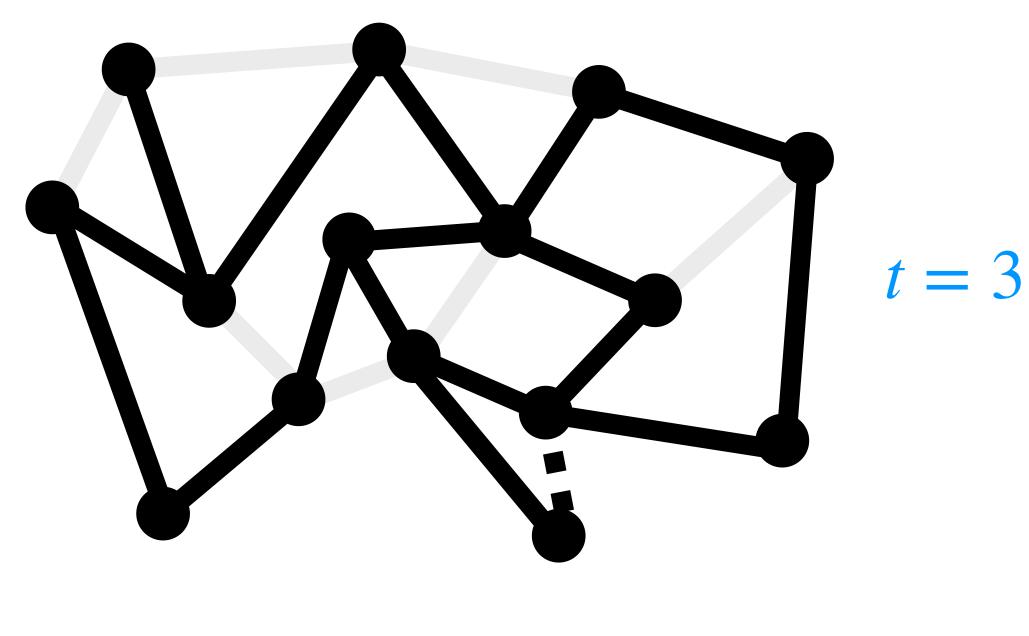
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



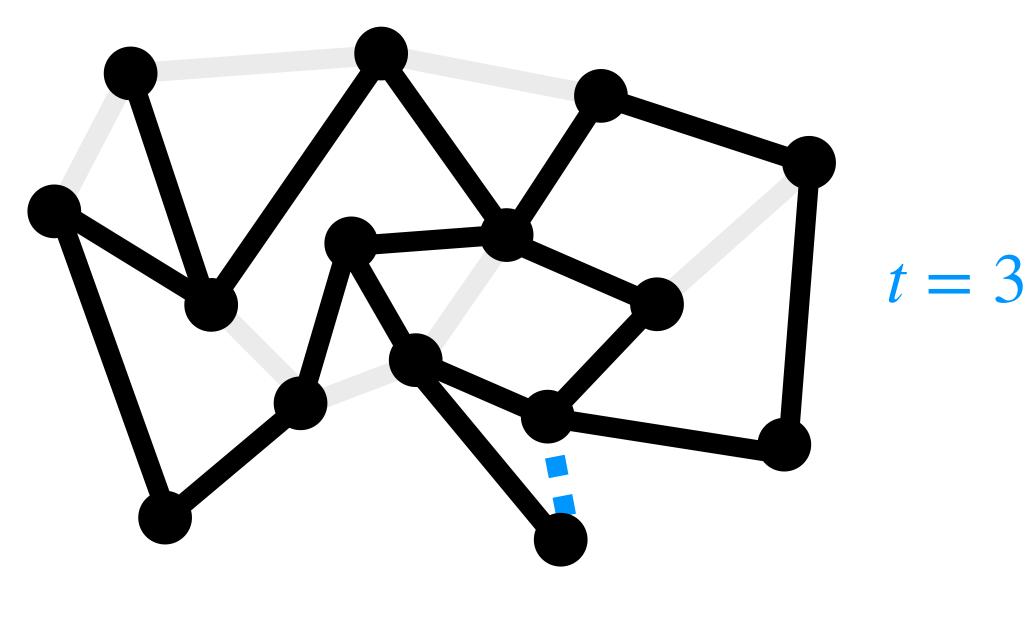
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



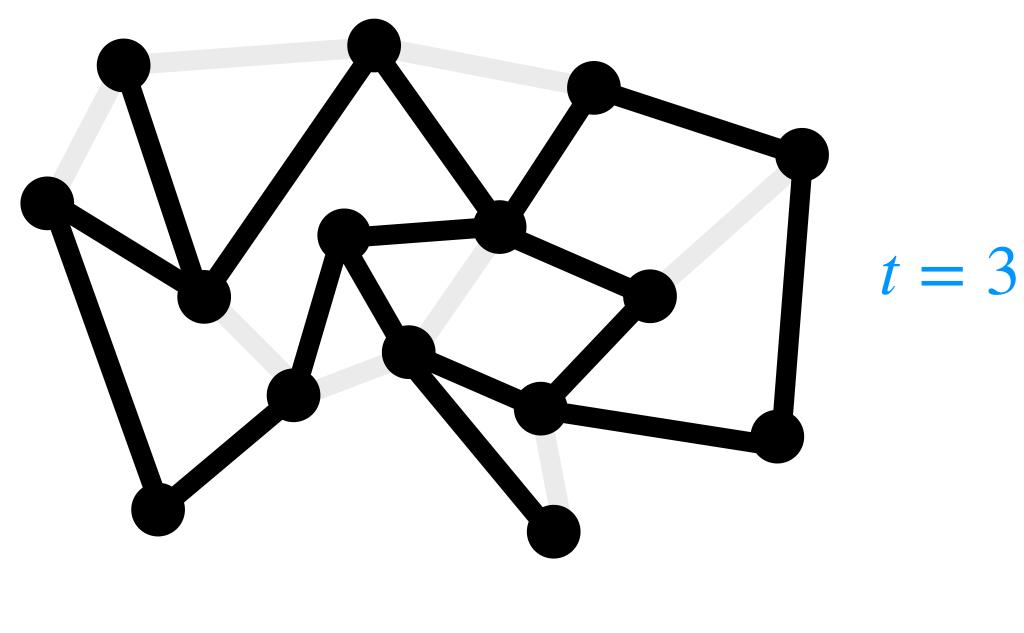
• $H \leftarrow \emptyset$

• For $\{u, v\} \in E$:

• If $d_H(u, v) > t$ then

$H \leftarrow H + \{u, v\}$





G = (V, E)



Roadmap of Proof



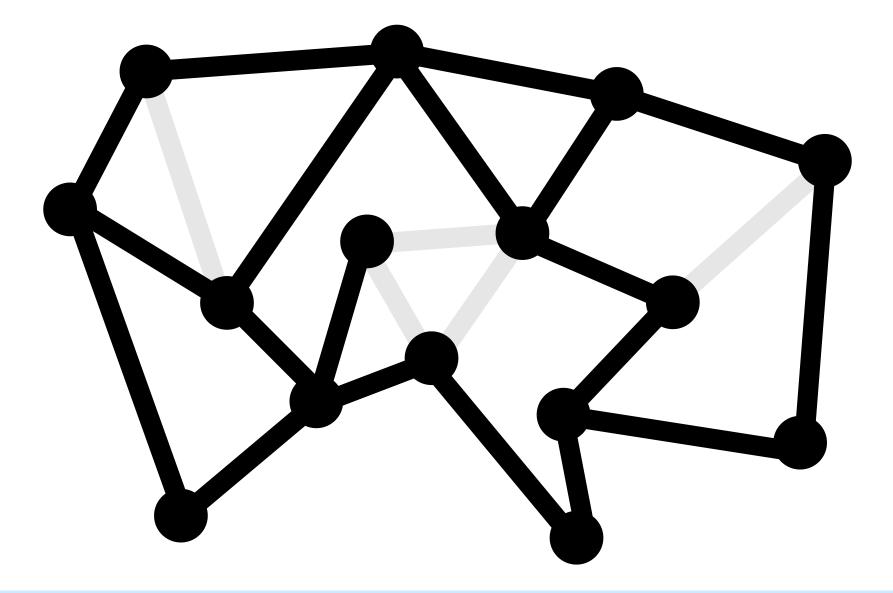
edge spanners suffice

2. Greedy Algorithm

suggested by observation

- 3. Distortion Analysis
- 4. Size Analysis

by "Moore Bounds"



Theorem: every graph G has a t-spanner H w/
Distortion: t = O(log n)

• **Size:** |H| = O(n)



Roadmap of Proof



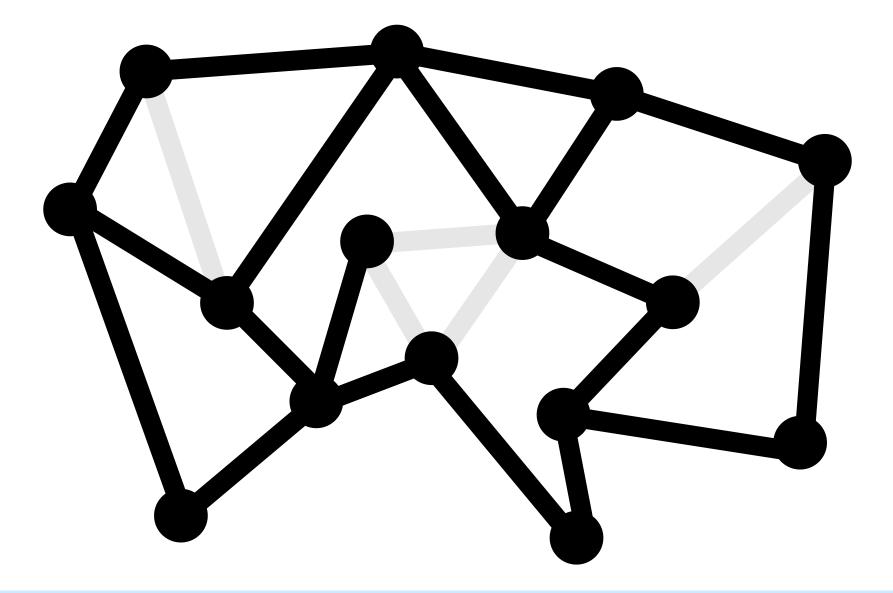
edge spanners suffice



suggested by observation

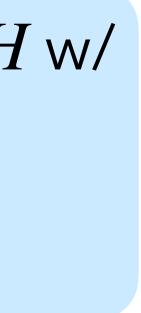
- 3. Distortion Analysis
- 4. Size Analysis

by "Moore Bounds"



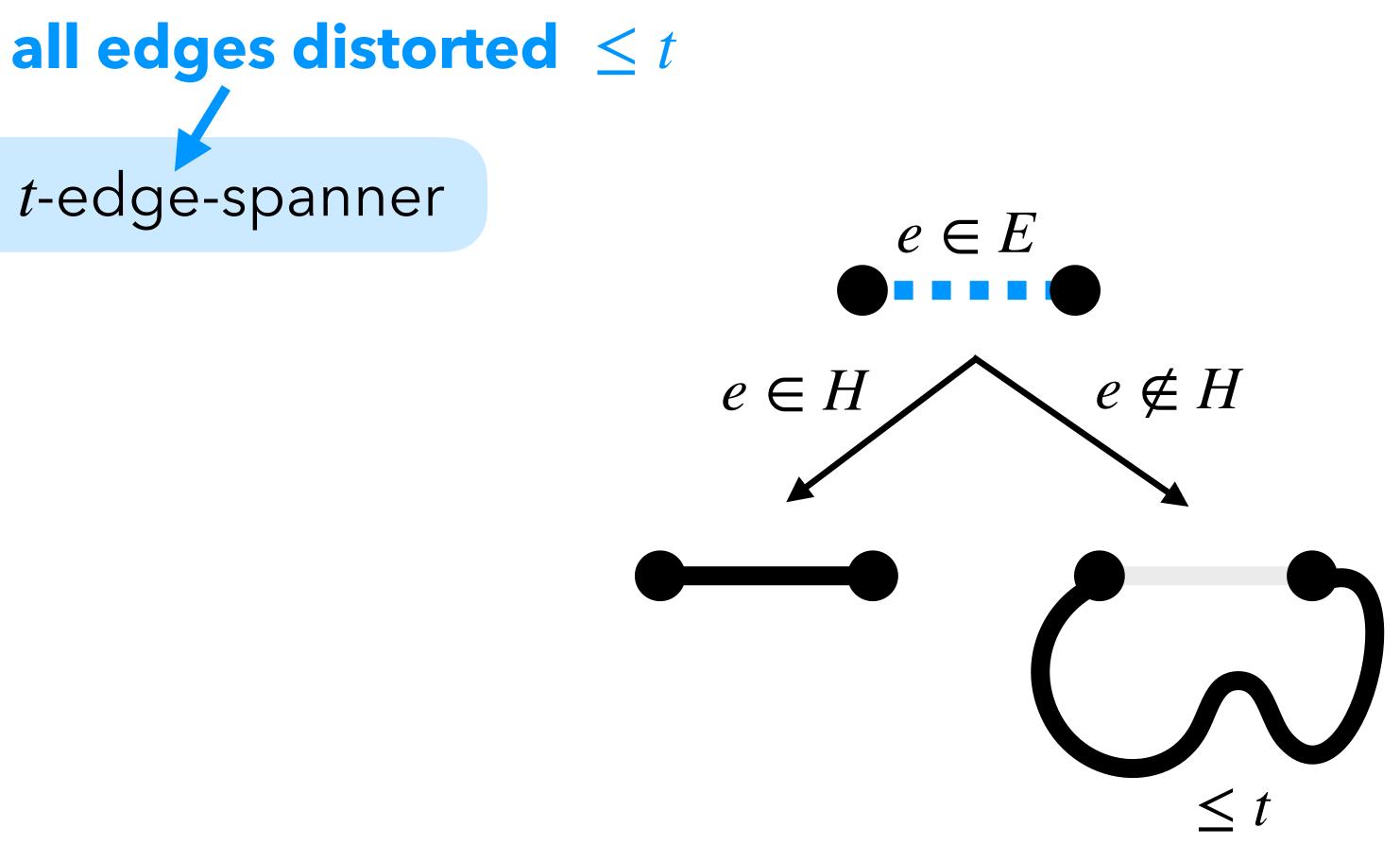
Theorem: every graph G has a t-spanner $H \le G(\log x)$

- **Distortion:** $t = O(\log n)$
- **Size:** |H| = O(n)



Distortion Analysis Edge Spanners

Claim: output *H* of greedy is a *t*-edge-spanner

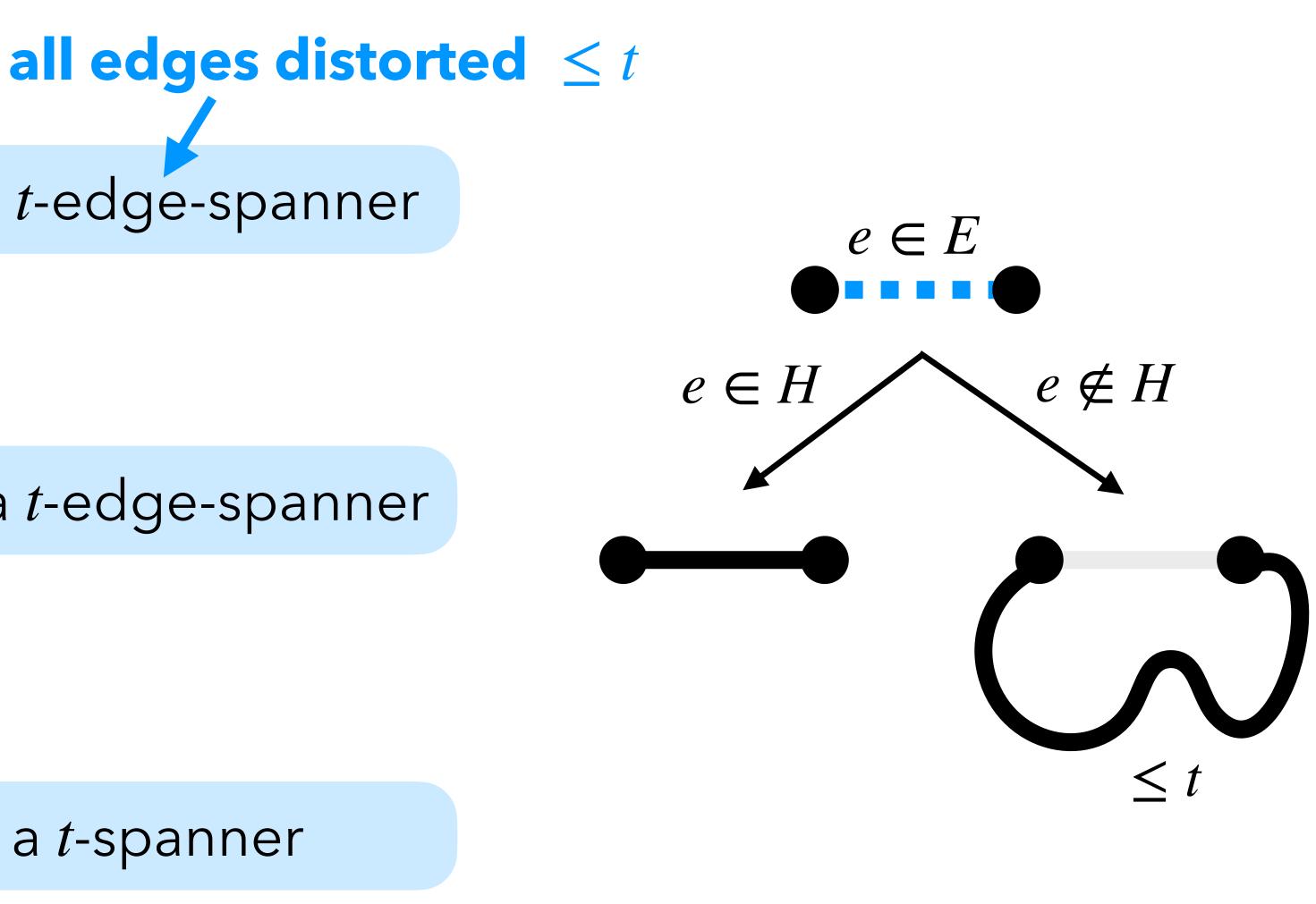


Distortion Analysis Edge Spanners

Claim: output *H* of greedy is a *t*-edge-spanner

Claim: *H* is a *t*-spanner iff it is a *t*-edge-spanner

Claim: output of greedy is a *t*-spanner



Roadmap of Proof



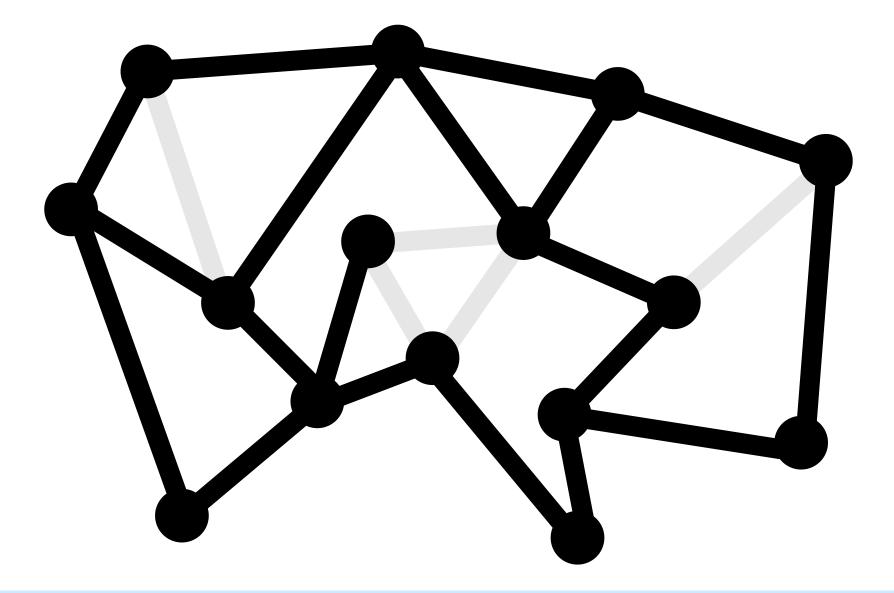
edge spanners suffice



suggested by observation

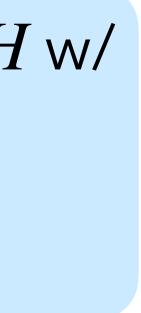
- 3. Distortion Analysis
- 4. Size Analysis

by "Moore Bounds"



Theorem: every graph G has a t-spanner $H \le t - O(\log n)$

- **Distortion:** $t = O(\log n)$
- **Size:** |H| = O(n)



Roadmap of Proof



edge spanners suffice

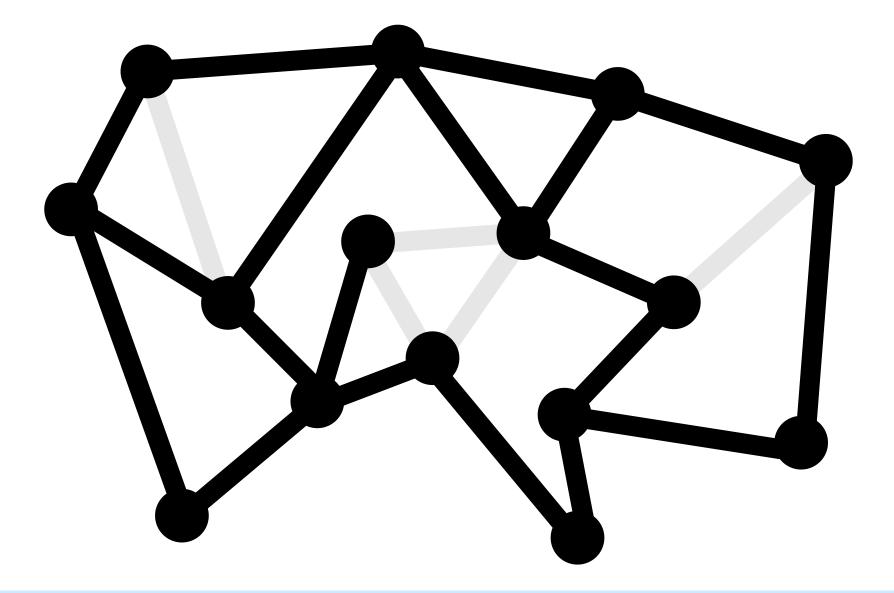


suggested by observation



4. Size Analysis

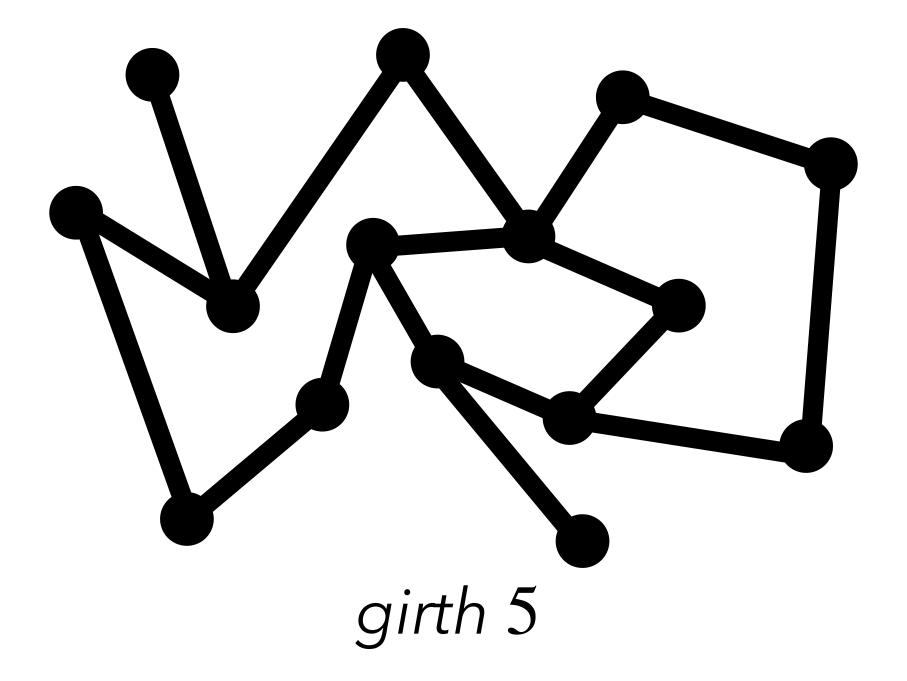
by "Moore Bounds"



Theorem: every graph G has a t-spanner H w/

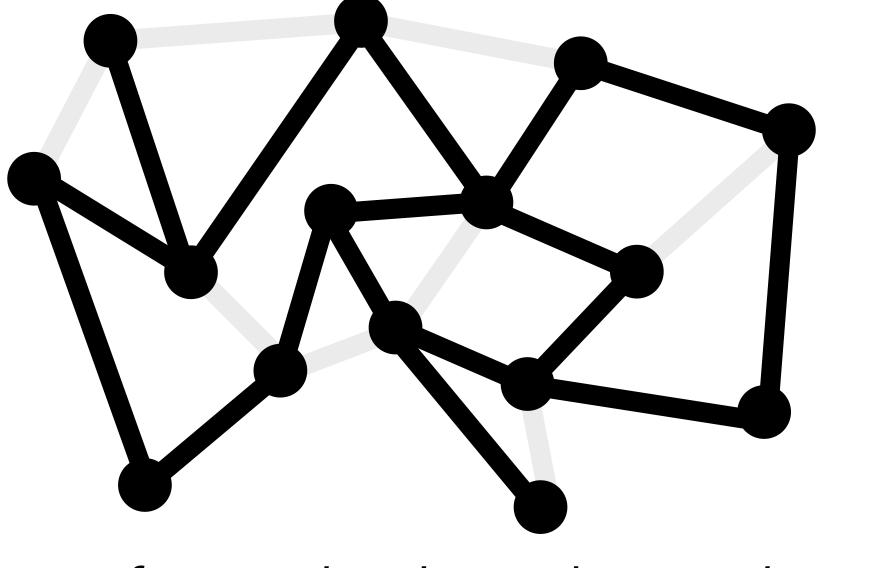
- **Distortion:** $t = O(\log n)$
- **Size:** |H| = O(n)





Definition (girth): the girth g of graph H is the length of its shortest cycle

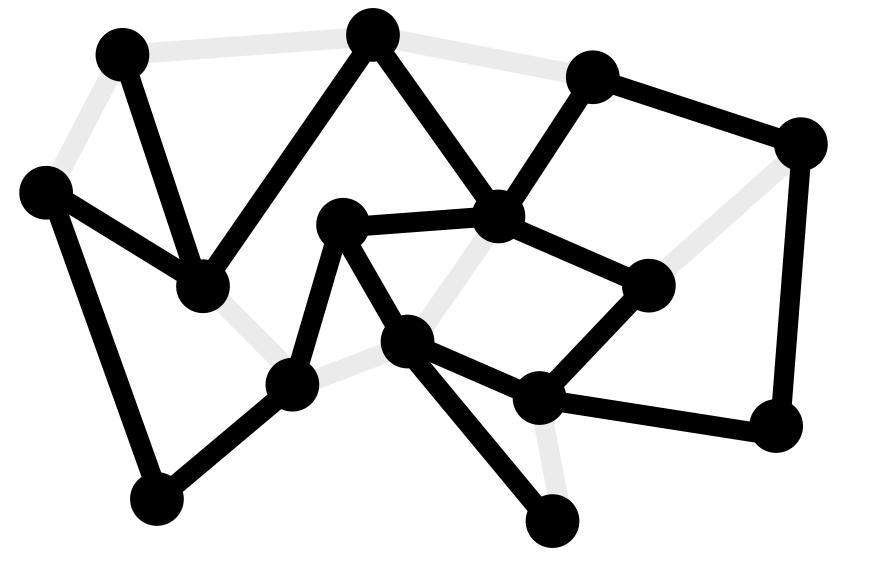




output of greedy algorithm with t = 3

Definition (girth): the girth g of graph H is the length of its shortest cycle





Claim: output of greedy algorithm has girth $\geq t + 2$

output of greedy algorithm with t = 3

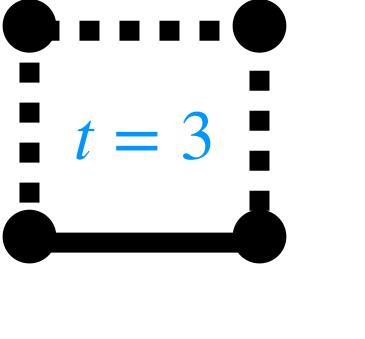
t = 3 $AFSOC a \le t + 1$ -Cycle

Claim: output of greedy algorithm has girth $\geq t + 2$

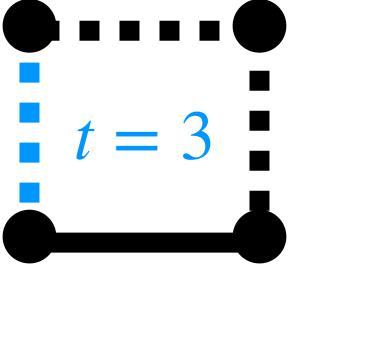
t = 3 $AFSOC a \le t + 1$ -Cycle

Claim: output of greedy algorithm has girth $\geq t + 2$

Claim: output of greedy algorithm has girth $\geq t + 2$

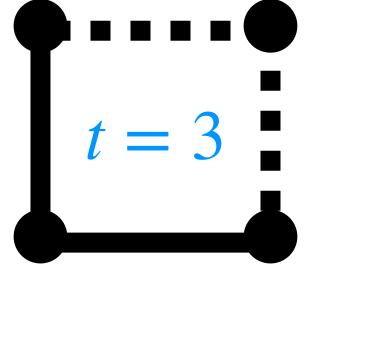


Claim: output of greedy algorithm has girth $\geq t + 2$



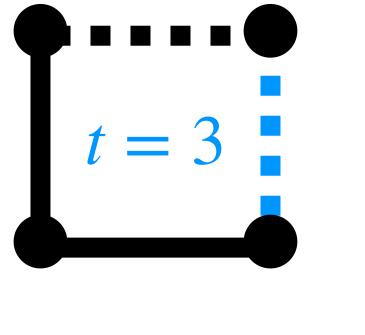


Claim: output of greedy algorithm has girth $\geq t + 2$



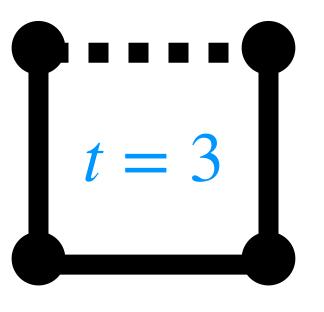


Claim: output of greedy algorithm has girth $\geq t + 2$



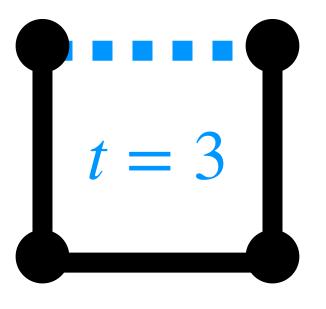


Claim: output of greedy algorithm has girth $\geq t + 2$



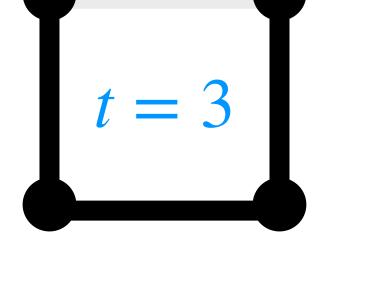


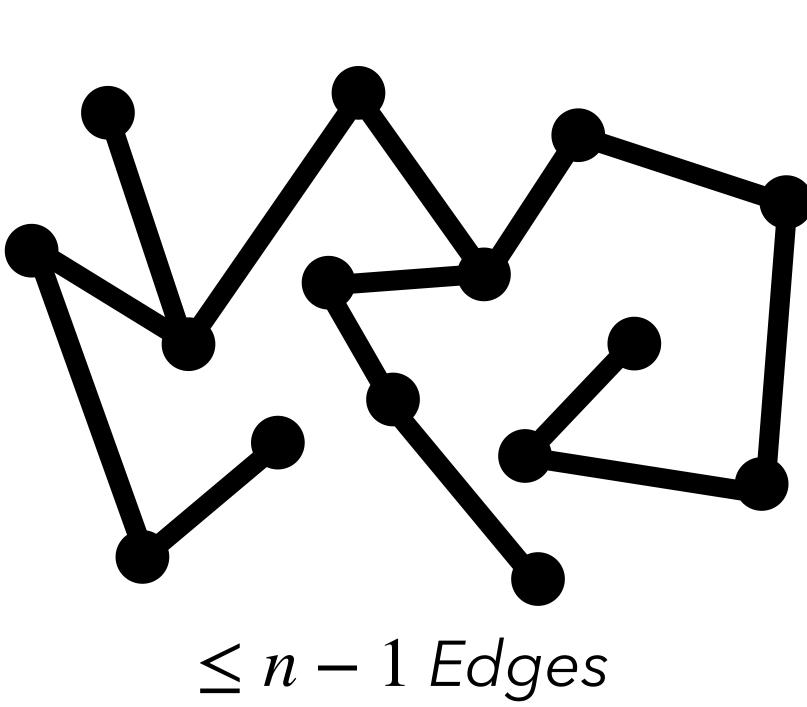
Claim: output of greedy algorithm has girth $\geq t + 2$



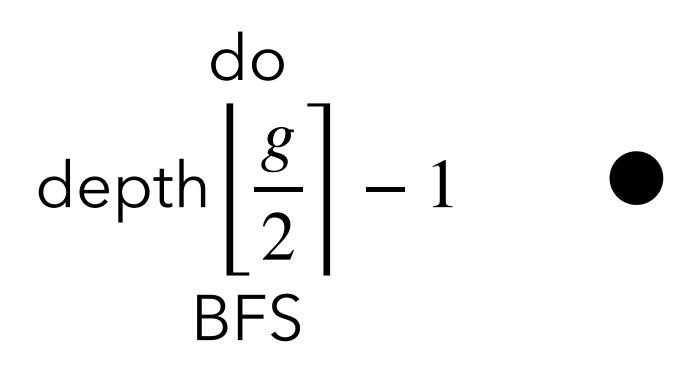


Claim: output of greedy algorithm has girth $\geq t + 2$

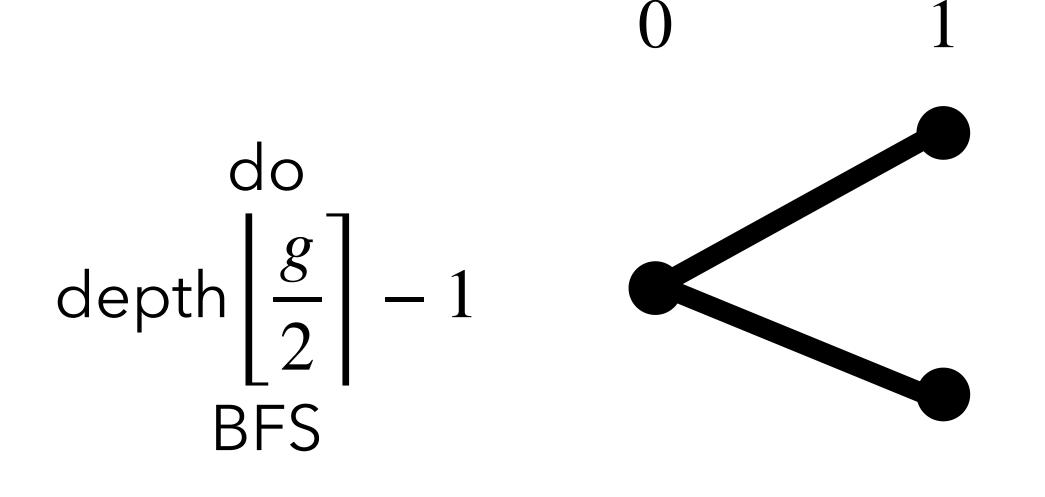




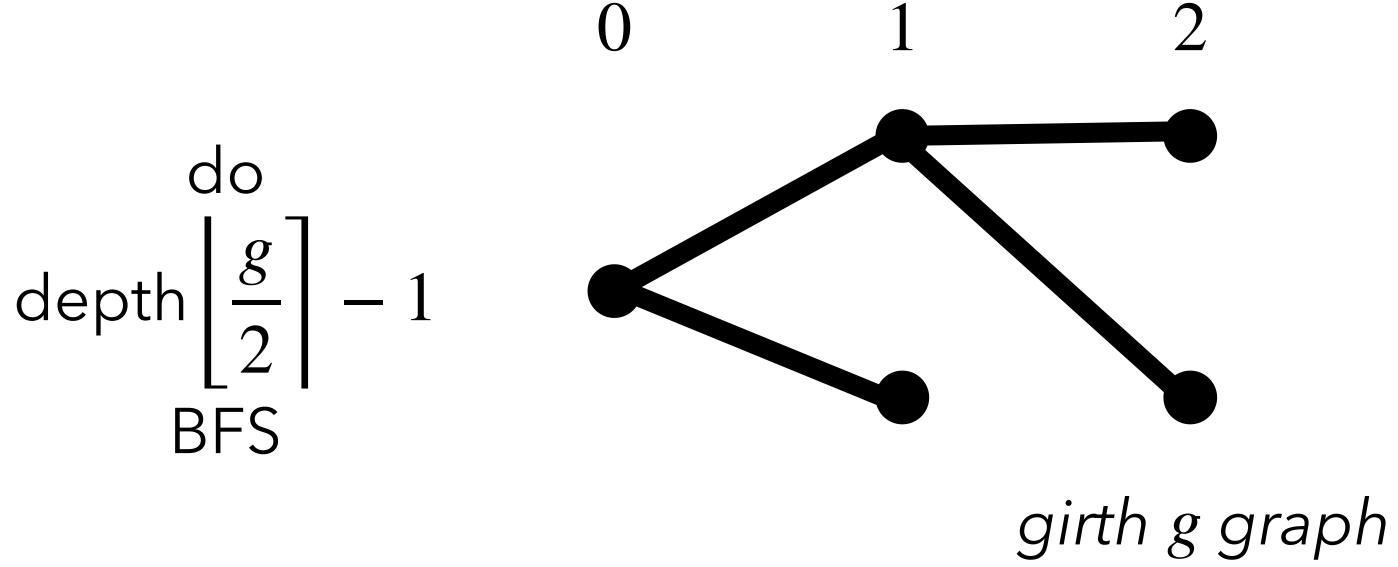
0

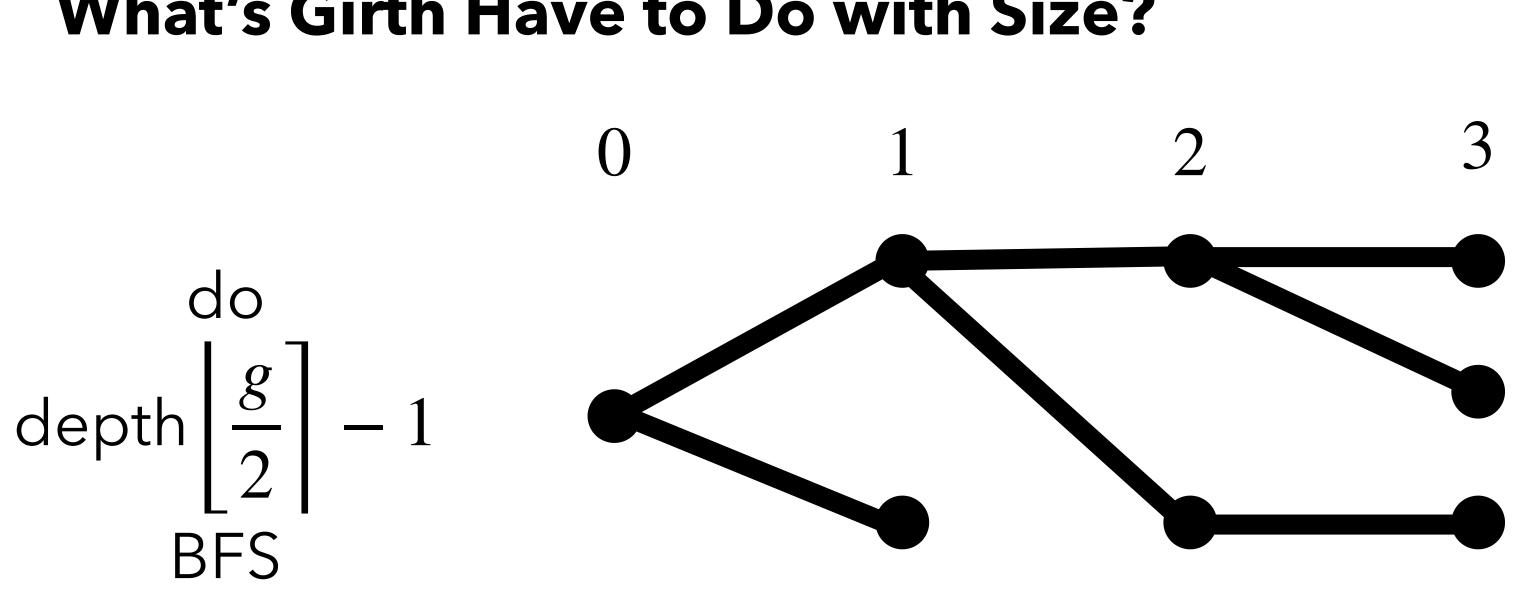


girth g graph

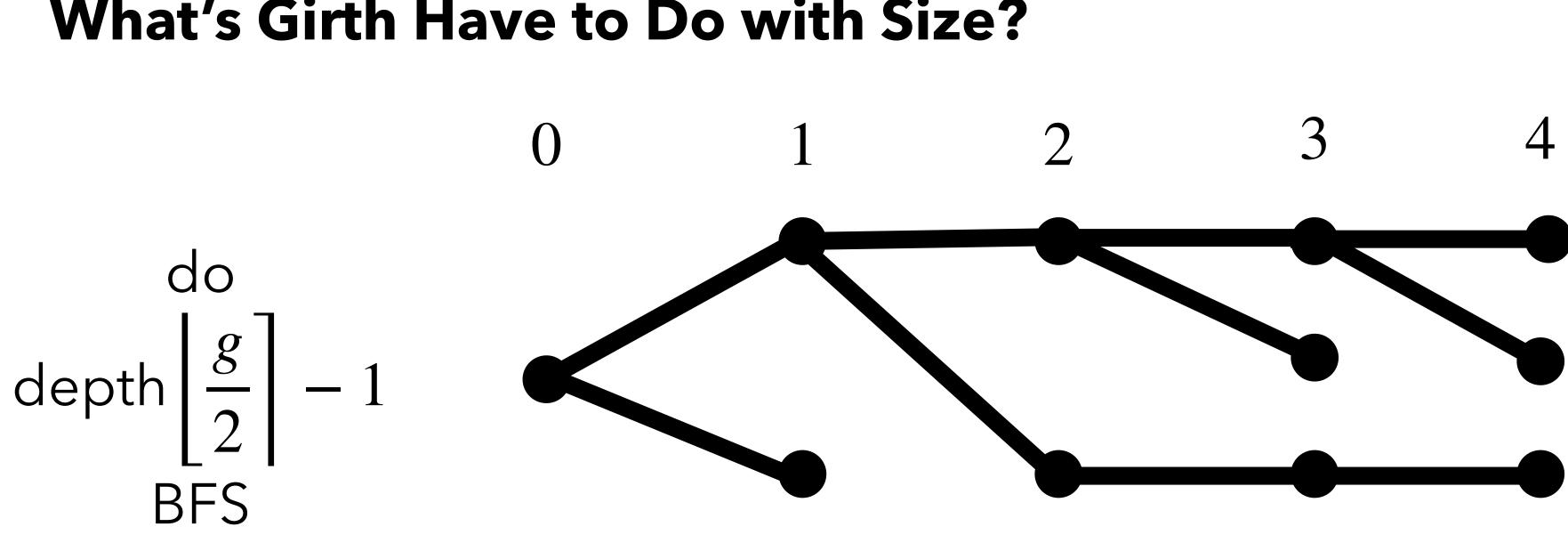


girth g graph

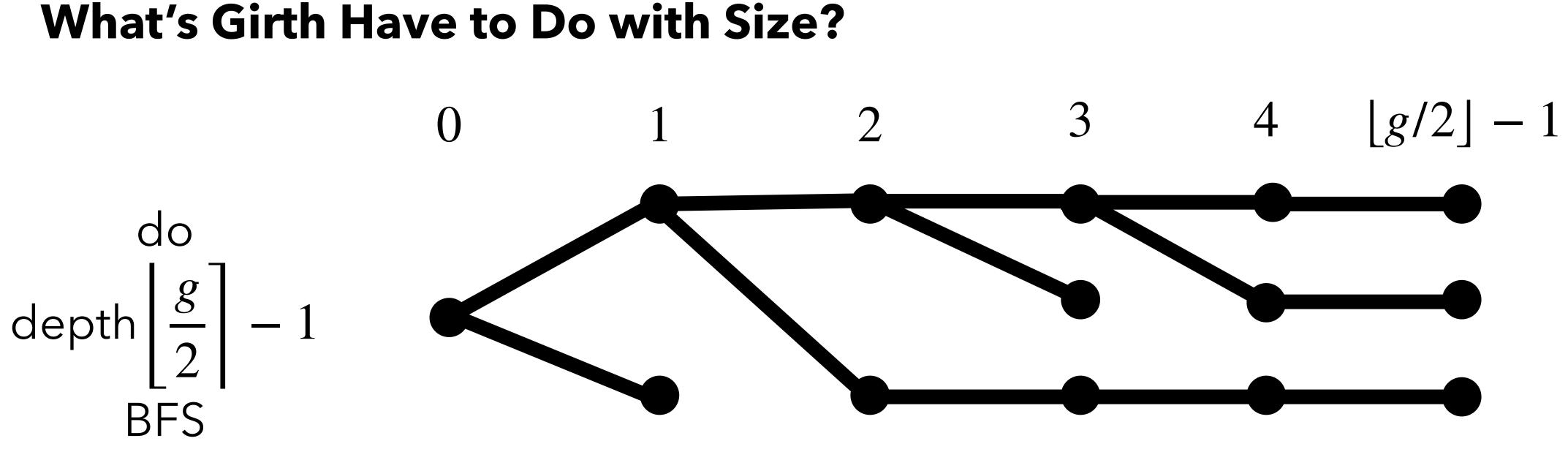




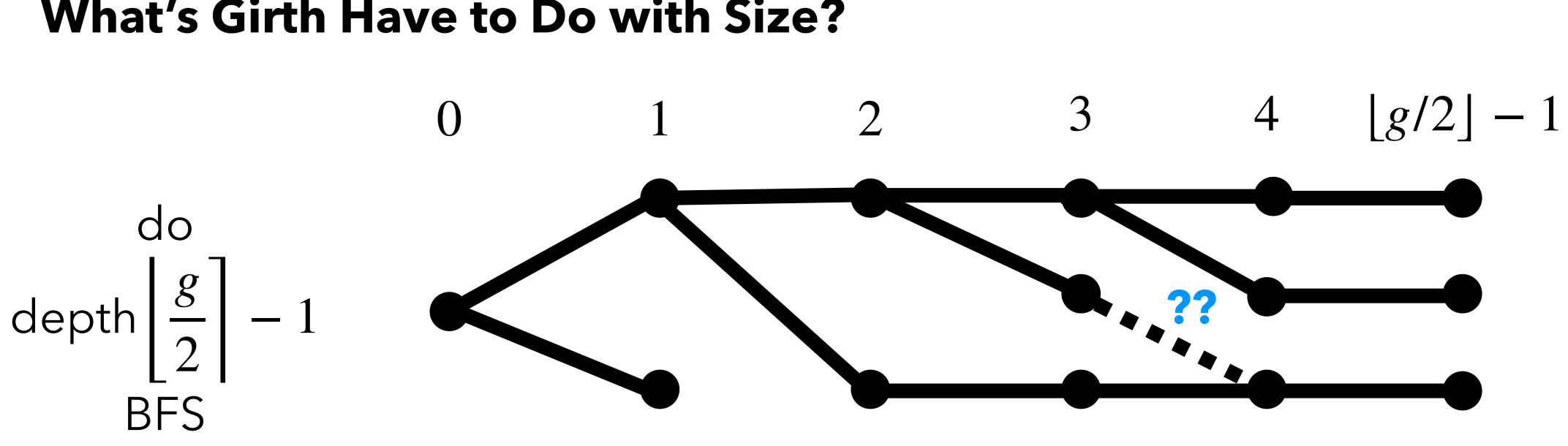
girth g graph



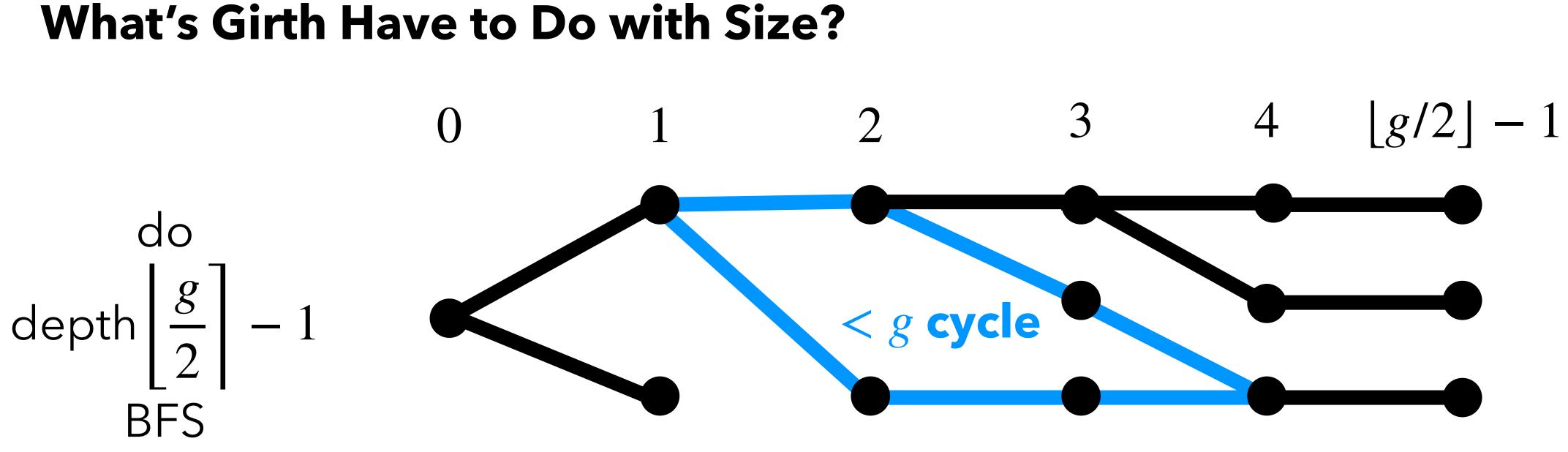
girth g graph



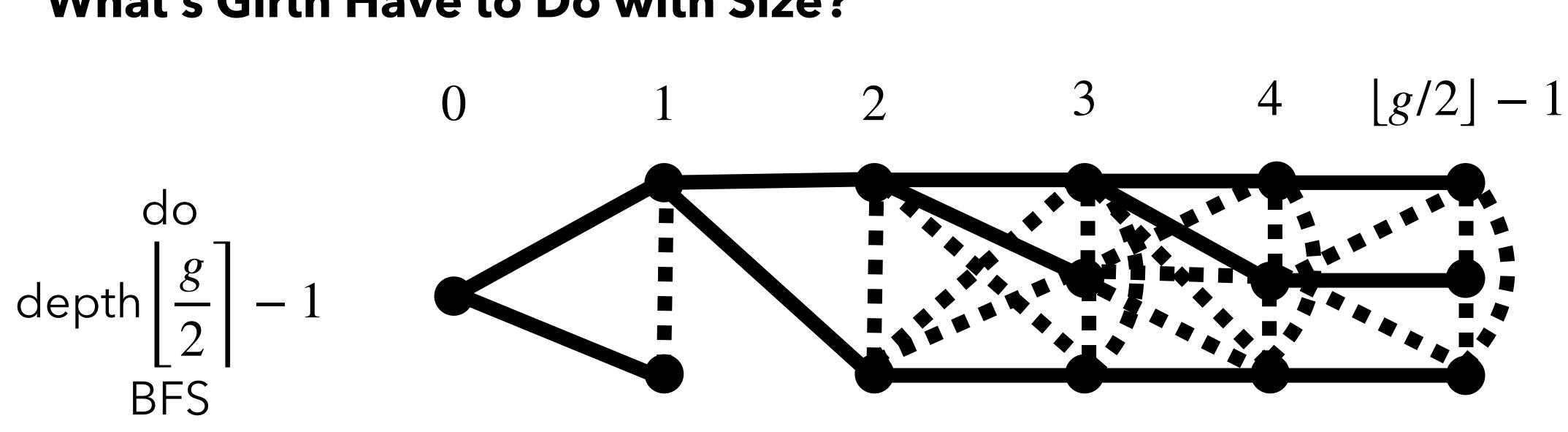
girth g graph



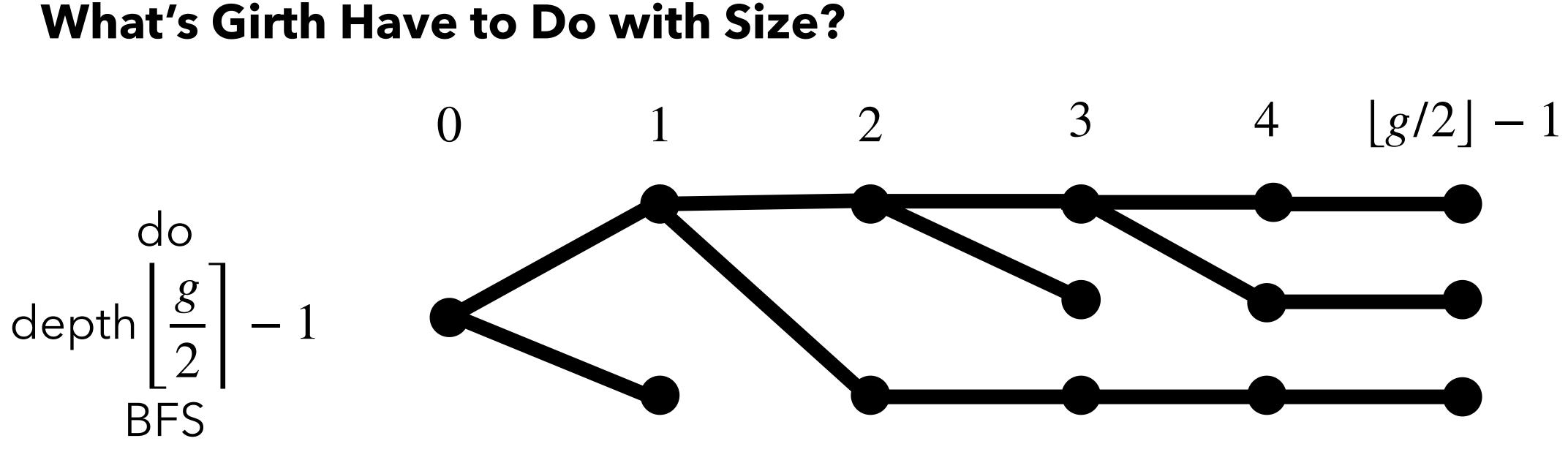
girth g graph



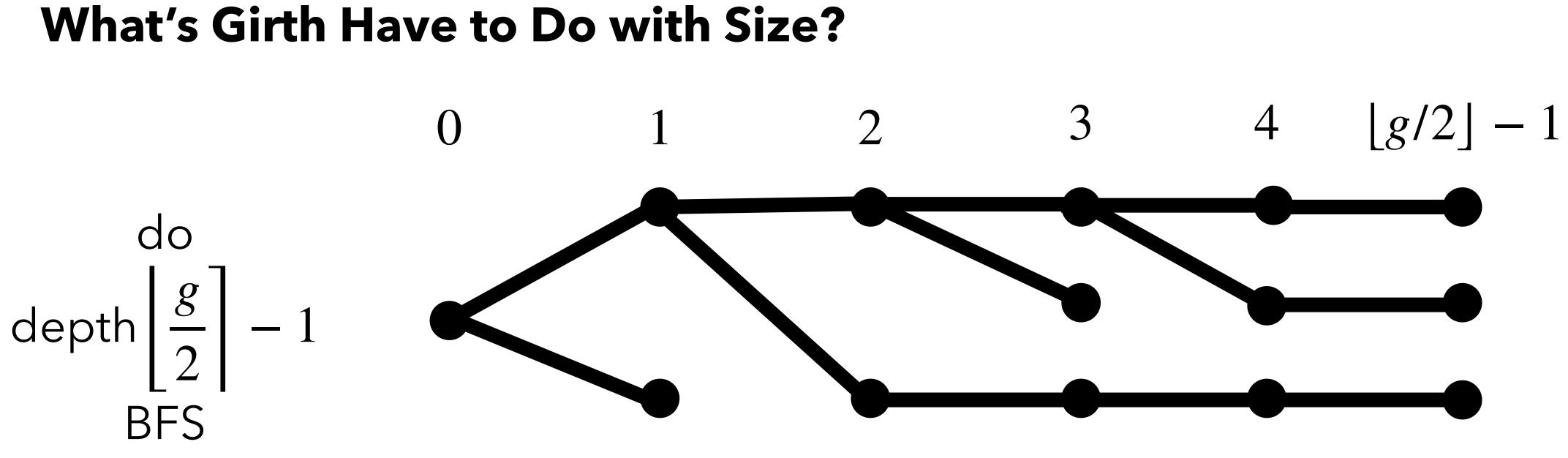
girth g graph



girth g graph

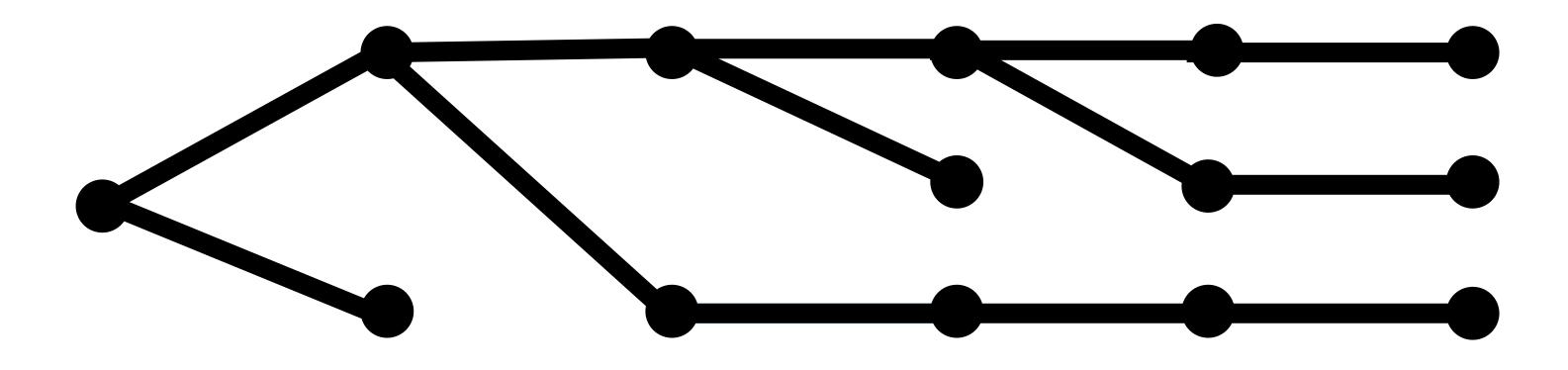


girth g graph

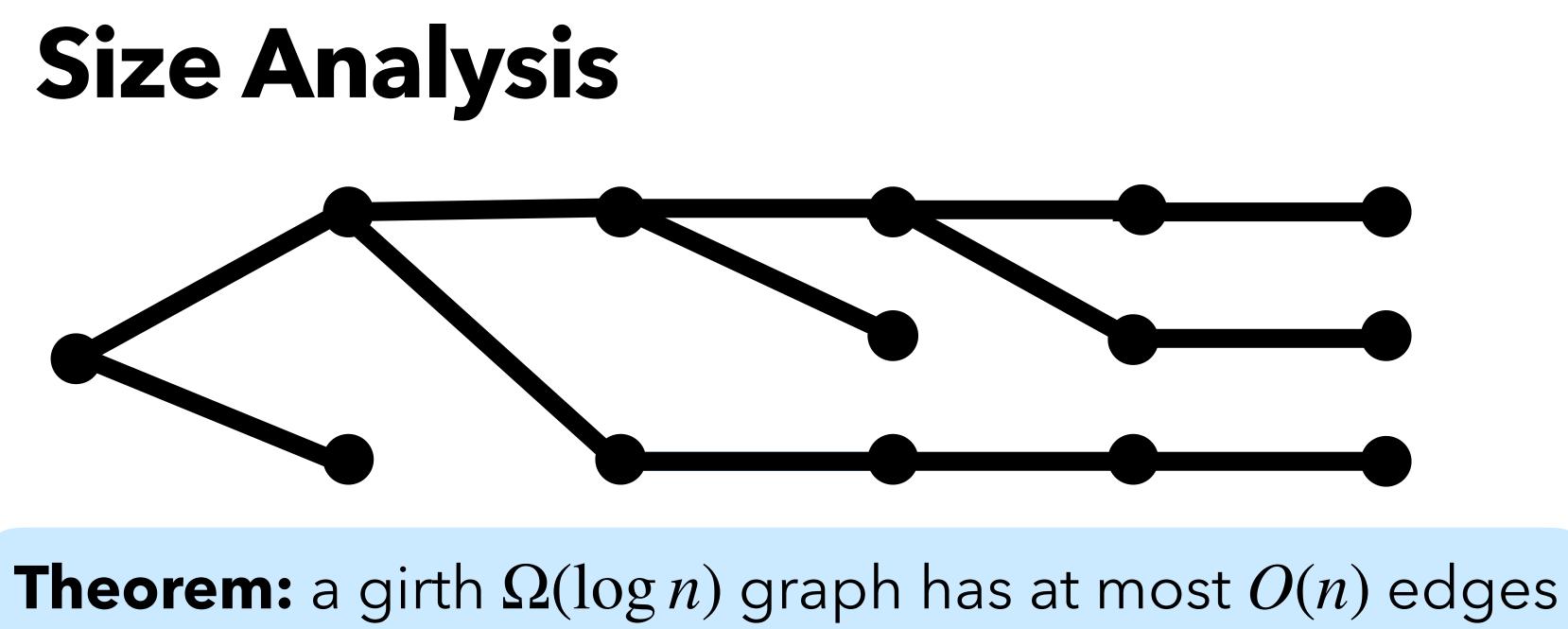


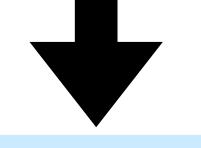
Theorem: a girth $\Omega(\log n)$ graph has at most O(n) edges

girth g graph



Theorem: a girth $\Omega(\log n)$ graph has at most O(n) edges





Claim: output of greedy algorithm has girth $\geq t + 2$

Theorem: output of greedy algorithm with $t = \Omega(\log n)$ has at most O(n) edges



Roadmap of Proof



edge spanners suffice

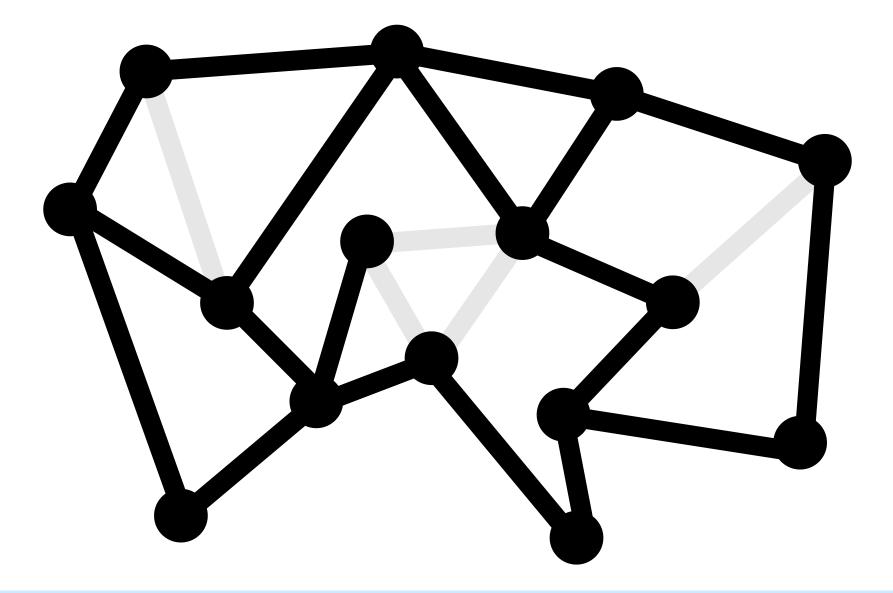


suggested by observation



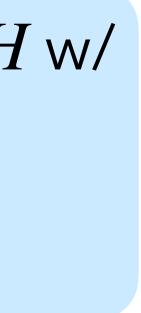
4. Size Analysis

by "Moore Bounds"



Theorem: every graph G has a t-spanner H w/

- **Distortion:** $t = O(\log n)$
- **Size:** |H| = O(n)



Roadmap of Proof



edge spanners suffice

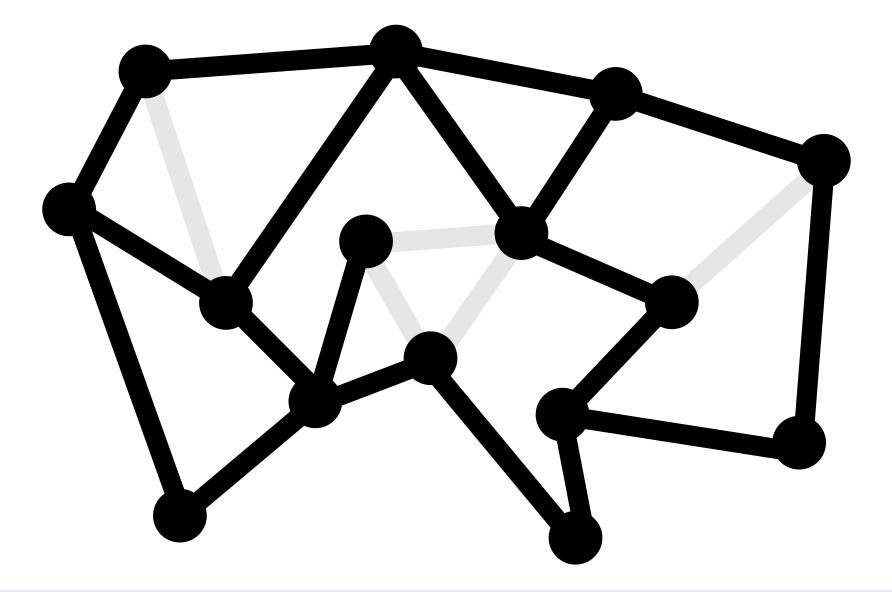


suggested by observation





by "Moore Bounds"



Theorem: every graph *G* has a *t*-spanner *H* w/

- **Distortion:** $t = O(\log n)$
- **Size:** |H| = O(n)

Observe: poly-time computable



Notable Generalizations

 Edge-weighted graphs Run greedy algorithm in increasing order of edge lengths

• Size-distortion tradeoff

Just run greedy; optimal assuming "girth conjecture" of Erdős

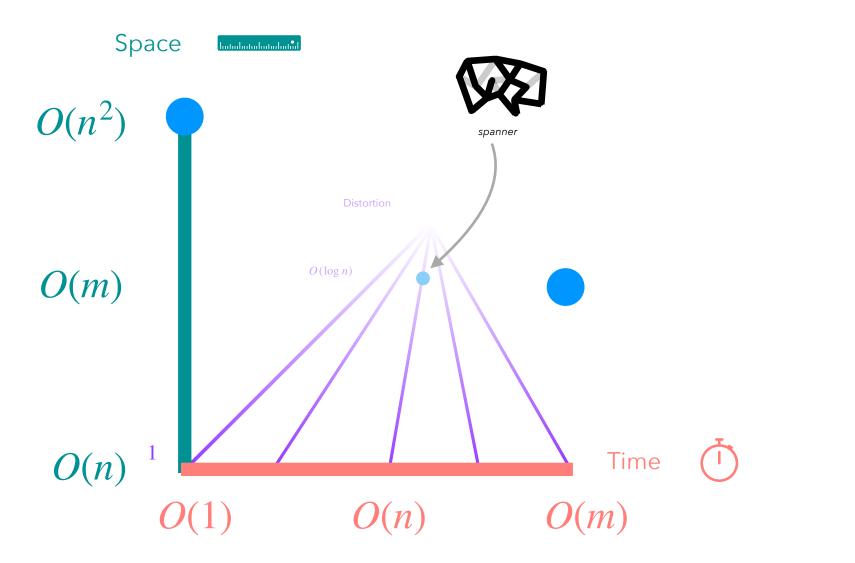
Theorem: every graph *G* has a *t*-spanner *H* w/

- **Distortion:** $t = O(\log n)$
- Size: |H| = O(n)

Theorem: every graph *G* for every *t* has a *t*-spanner *H* w/

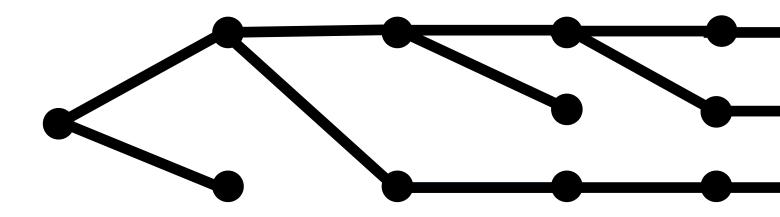
- **Distortion:** *t*
- Size: $|H| = n^{1+O(\frac{1}{t})}$

Summary



Theorem: every graph G has a *t*-spanner H w/ Distortion: t = O(log n) Size: |H| = O(n)

Motivation: distance oracles



Key Idea: greedy output is high girth, high girth is sparse

Main Result

Simple Observation

edge spanners suffice

2. Greedy Algorithm

suggested by observation

- 3. **Distortion Analysis**
- 4. Size Analysis

by "Moore Bounds"

Roadmap

