

Today

- 1) LPs as shapes
- 2) Inner products + friends
- 3) Ellipsoid Algorithm

LPs as a "Shape"

$$K = \{x: Ax \leq b\} = \{x: \langle a_i, x \rangle \leq b_i \quad \forall a_i \in \text{rows}(A)\}$$

↑
A bunch of points in \mathbb{R}^n
What kind of "shape"?

A set of the form $K = \{x: Ax \leq b\}$ is called a polyhedron

If $\exists \Delta \in \mathbb{R}$ s.t. $d(x,y) \leq \Delta \quad \forall x,y \in K$, then K is called a polytope
↳ K is "bounded"

Inner Products + Friends

Geometry of $\langle u, u \rangle$: $\sqrt{\langle u, u \rangle} := \sqrt{\sum_i u_i^2} = d(0, u) = \text{length of } u$
↳ Notated $\|u\|$

Geometry of $\langle u, v \rangle$: $\langle \underline{u}, \underline{v} \rangle := \sum_i u_i v_i = ?$

Let $\underline{c}^* := \arg \min_c d(c \cdot v, u)$ and $\text{Proj}(u \rightarrow v) := \underline{c}^* \cdot v$

Do some calculus and get $\underline{c}^* = \frac{\langle u, v \rangle}{\langle v, v \rangle}$

so $\text{Proj}(u \rightarrow v) = \langle u, v \rangle \frac{v}{\langle v, v \rangle}$

$\langle u, v \rangle \Leftrightarrow$ how much u is in direction of v

Some calculus:

$\min_c d(c \cdot v, u) = \min_c (d(c \cdot v, u))^2$ b/c $d \geq 0$ and squaring is monotonically increasing

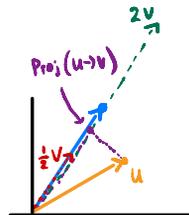
so let $f(c) = (d(c \cdot v, u))^2 = \sum_j (c v_j - u_j)^2 = \sum_j c^2 v_j^2 - 2c v_j u_j + u_j^2$

$\frac{df}{dc} = 2 \sum_j c v_j^2 - 2v_j u_j$

Set $\frac{df}{dc} = 0$, solve for c to get $c = \frac{\langle u, v \rangle}{\langle v, v \rangle}$

Then do 2nd derivative test

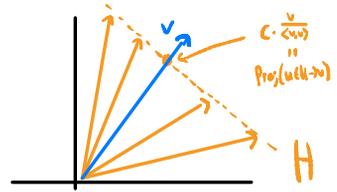
$\langle u, v \rangle = 0 \rightarrow$  $\Rightarrow u, v$ orthogonal



Given $v \in \mathbb{R}^n$, $c \in \mathbb{R}$ $H_{=vc} := \{u : \langle u, v \rangle = c\}$ is called a hyperplane

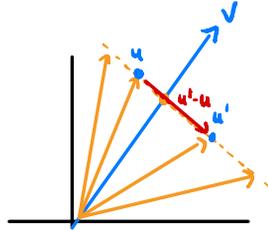
Equivalently, $H_{=vc} = \{u : \text{Proj}_v(u) = c \cdot \frac{v}{\langle v, v \rangle}\}$

\hookrightarrow so $u, u' \in H_{=vc} \rightarrow \text{Proj}_v(u-v) = \text{Proj}_v(u'-v)$

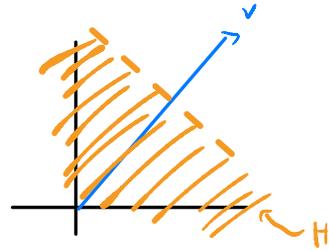
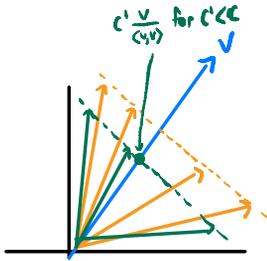


v is called the normal vector of $H_{=vc}$

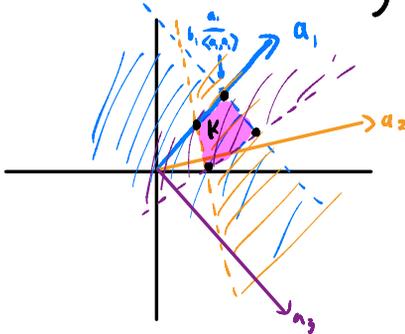
B/c if $u, u' \in H_{=vc}$ then $\langle u'-u, v \rangle = \langle u', v \rangle - \langle u, v \rangle = c - c = 0$



Given $v \in \mathbb{R}^n$, $c \in \mathbb{R}$ $H := \{u : \langle u, v \rangle \leq c\}$ is called a halfspace



$K = \{x : \langle a_i, x \rangle \leq b_i \quad \forall a_i \in \text{rows}(A)\}$ is the intersection of m halfspaces



Notice if x is tight for

$$\langle a_i, x \rangle = b_i$$

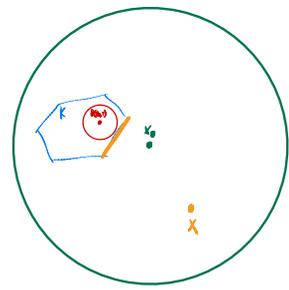
then x is in the hyperplane $\{x : \langle a_i, x \rangle = b_i\}$

Also notice if only 2 constraints here get polyhedra

Main Takeaway: Can solve LP feasibility in Polynomial time (even w/ exponentially-many constraints)

Assumptions

- 1) Given x_0, R s.t. $K \subseteq B(x_0, R)$
- 2) $\exists y_0, r \in \mathbb{R}$ s.t. if $K \neq \emptyset$ $B(y_0, r) \subseteq K$ w/ $\frac{R}{r} \leq \text{EXP}(\text{Poly}(n))$
- 3) Have a "Strong Separation Oracle" for K (in $\text{poly}(n)$ time)



Given $y \in \mathbb{R}^n$, a Strong separation oracle for $K = \{x: Ax \leq b\}$ either correctly outputs "yes" or returns an $a_j \in \text{rows}(A)$ s.t. $\langle y, a_j \rangle > b_j \rightarrow$ Note $\langle x, a_j \rangle \leq b_j \forall x \in K$

Ellipsoid Algorithm

Let $E_0 := B(x_0, R)$

For $i = 1, 2, \dots, 10 \cdot n^2 \cdot \ln(\frac{R}{r})$

Let $c_{i-1} := \text{center}(E_{i-1})$

If $c_{i-1} \in K$, return $K \neq \emptyset$

O/w let $a_j \in \text{rows}(A)$ satisfy

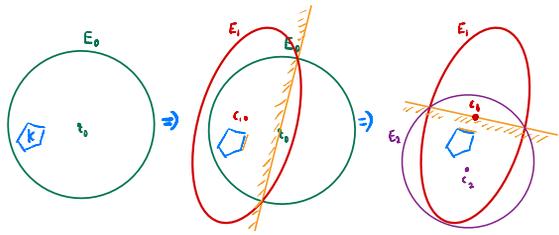
$\langle a_j, c_{i-1} \rangle > b_j$

\rightarrow Via separation oracle

Let $T_i := E_{i-1} \cap \{x: \langle a_j, x \rangle \leq \langle a_j, c_{i-1} \rangle\}$

Let E_i be a carefully chosen "ellipsoid" containing T_i

Return $K = \emptyset$



\rightarrow Will be min. Volume ellipsoid

Volume + Balls

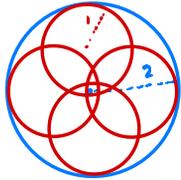
For $S \subseteq \mathbb{R}^n$, the volume of S is $\text{Vol}(S) := \int_{x \in S} 1 dx$

The (closed) radius r ball centered at $x \in \mathbb{R}^n$ is

$B(x, r) := \{y \in \mathbb{R}^n : d(x, y) \leq r\}$

Let $V_n := \text{Vol}(B(x, 1))$

Fact: $\text{Vol}(B(x, r)) = V_n \cdot r^n \forall r \geq 0, x \in \mathbb{R}^n$



Key Lemma: Can $\text{poly}(n)$ -time compute E_i s.t. $T_i \subseteq E_i$ and $\text{vol}(E_i) \leq (1 - \frac{1}{5n}) \cdot \text{vol}(E_{i-1})$

Thm: Given (1)-(3), ellipsoid solves LP feasibility in $\text{Poly}(n)$ time

Proof of Ellipsoid Correctness \rightarrow A halving argument!

If $K = \emptyset$ then never return $K \neq \emptyset$

If $K \neq \emptyset$, know $\exists r, y_0$ as described, AFSOC returned $K = \emptyset$

Let $k := 10 \cdot n^2 \cdot \ln\left(\frac{R}{r}\right)$ be # of iterations

$\text{Vol}(E_k) \geq V_n \cdot r^n$ b/c key lemma $\rightarrow K \subseteq E_i \forall i$ and $\theta(y_0, r) \subseteq K$
so $\theta(y_0, r) \subseteq E_k$ but $\text{Vol}(\theta(y_0, r)) = V_n \cdot r^n$ so $\text{Vol}(E_k) \geq V_n \cdot r^n$

OTOH, by key lemma and $\text{Vol}(E_0) = V_n \cdot R^n$ have

$$\begin{aligned}\text{Vol}(E_k) &\leq \left(1 - \frac{1}{5n}\right) \cdot \text{Vol}(E_{k-1}) \leq \left(1 - \frac{1}{5n}\right)^2 \cdot \text{Vol}(E_{k-2}) \leq \dots \leq \text{Vol}(E_0) \cdot \left(1 - \frac{1}{5n}\right)^k \\ &= V_n \cdot R^n \cdot \left(1 - \frac{1}{5n}\right)^k \\ &\leq V_n \cdot R^n \cdot \exp\left(-\frac{k}{5n}\right) \quad (1-x \leq \exp(-x) \forall x) \\ &= V_n \cdot R^n \cdot \exp\left(-2 \cdot n \cdot \ln\left(\frac{R}{r}\right)\right) \\ &= V_n \cdot R^n \cdot \left(\frac{r}{R}\right)^{2n} \\ &= V_n \cdot \left(\frac{r}{R}\right)^n \cdot r^n \\ &< V_n \cdot r^n \rightarrow \text{contradicts } \text{Vol}(E_k) > V_n \cdot r^n\end{aligned}$$

Proof of Ellipsoid Runtime

Runtime is $T_{\text{separation}} \cdot O\left(n^2 \cdot \ln\left(\frac{R}{r}\right)\right) = \text{Poly}(n)$ (by $\frac{R}{r} \leq \exp(\text{Poly}(n))$)